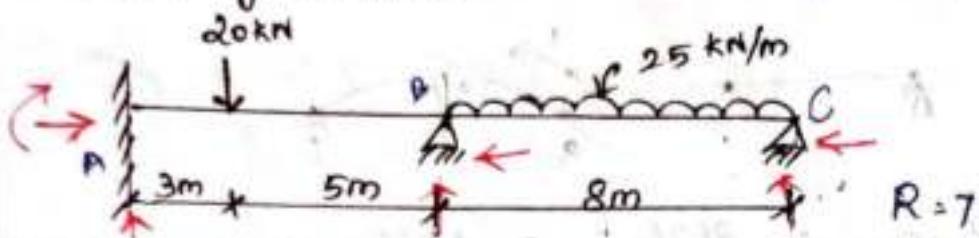


2. A two span continuous beam is fixed at A and hinged over the supports B and C, $AB = 8m$ and $BC = 8m$. The moment of inertia is constant throughout. It is loaded as shown in fig. Analyse the beam by stiffness matrix method.



Soln:

Step-1 : Kinematic Indeterminacy :

$$D_K = 3j - R \\ = (3 \times 3) - 7 \\ = 2$$

System co-ordinates = & (B, c)

Element co-ordinates :

$$1 \left(\begin{array}{c} 1 \\ 2 \\ 3 \\ 4 \end{array} \right) \left(\begin{array}{c} 1 \\ 2 \\ 3 \\ 4 \end{array} \right) \\ \text{Element coordinates} = 4$$

B matrix = 4×9

Fixed end moments :

$$M_{FAB} = -\frac{Wa^2b}{l^2} = -\frac{20 \times 3^2 \times 5^2}{8^2} = -23.43 \text{ kNm}$$

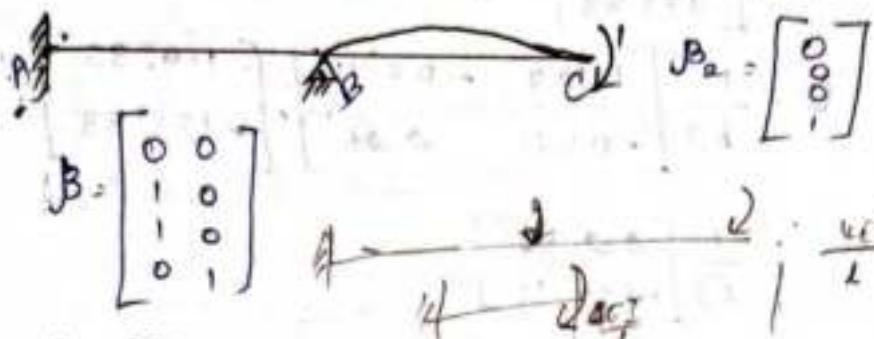
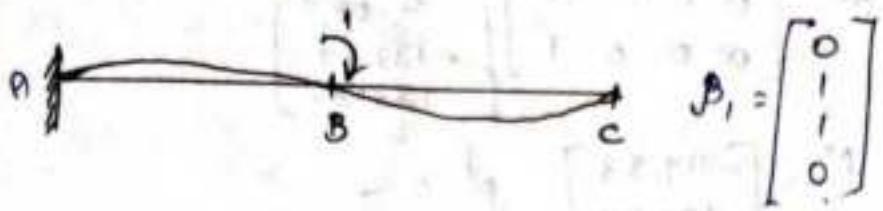
$$M_{FBA} = \frac{Wa^2b}{l^2} = \frac{20 \times 3^2 \times 5}{8^2} = 14.06 \text{ kNm}$$

$$M_{FCB} = -\frac{wl^2}{12} = -\frac{25 \times 8^2}{12} = -133.33 \text{ kNm}$$

$$M_{FCB} = \frac{wl^2}{12} = \frac{25 \times 8^2}{12} = 133.33 \text{ kNm.}$$

$$[P^e] = \begin{bmatrix} -23.43 \\ 14.06 \\ -133.33 \\ 133.33 \end{bmatrix}$$

β matrix:



Element Stiffness Matrix:

$$[k] = \begin{bmatrix} 4EI/8 & 2EI/8 \\ 2EI/8 & 4EI/8 \end{bmatrix} = EI \begin{bmatrix} 0.5 & 0.25 \\ 0.25 & 0.5 \end{bmatrix}$$

$$K_2 = k_1, \quad K_0 = \begin{bmatrix} 0.5 & 0.25 & 0 & 0 \\ 0.25 & 0.5 & 0 & 0 \\ 0 & 0 & 0.5 & 0.25 \\ 0 & 0 & 0.25 & 0.5 \end{bmatrix}$$

System Stiffness matrix:

$$[k] = [\beta^*]^T [k] [\beta]$$

$$= \begin{bmatrix} 0 & 1 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} EI \begin{bmatrix} 0.5 & 0.25 & 0 & 0 \\ 0.25 & 0.5 & 0 & 0 \\ 0 & 0 & 0.5 & 0.25 \\ 0 & 0 & 0.25 & 0.5 \end{bmatrix} \begin{bmatrix} 0 & 0 \\ 1 & 0 \\ 1 & 0 \\ 0 & 1 \end{bmatrix}$$

$$= EI \begin{bmatrix} 0.25 & 0.5 & 0.5 & 0.25 \\ 0 & 0 & 0.25 & 0.5 \end{bmatrix} \begin{bmatrix} 0 & 0 \\ 1 & 0 \\ 1 & 0 \\ 0 & 1 \end{bmatrix}$$

$$= EI \begin{bmatrix} 1 & 0.25 \\ 0.25 & 0.5 \end{bmatrix}$$

$$A' = \frac{1}{|A|} \text{adj } A.$$

$$[k]^{-1} = \frac{1}{EI} \begin{bmatrix} 1.143 & -0.571 \\ -0.571 & 2.28 \end{bmatrix}$$

System displacement:

$$[U] = [k]^{-1} \{ f^t - f^o \}$$

$$= \frac{EI}{4} \begin{bmatrix} 1 & 1 \\ 1 & 2 \end{bmatrix} \{ f^t - f^o \} = [\beta]^T [P^o]$$

$$= \begin{bmatrix} 4 & 1 \\ 1 & 2 \end{bmatrix} \begin{bmatrix} 1 & 2 & 2 & 1 \\ 0 & 0 & 1 & 2 \end{bmatrix} \begin{bmatrix} 0 & 0 \\ 1 & 0 \\ 1 & 0 \\ 0 & 1 \end{bmatrix}$$

$$f^o = \begin{bmatrix} 0 & 1 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} -23.43 \\ 4.06 \\ -133.33 \\ 133.33 \end{bmatrix}$$

$$f^e = \begin{bmatrix} -119.33 \\ 133.33 \end{bmatrix} \quad f^e = 0$$

$$U = \frac{1}{EI} \begin{bmatrix} 1.143 & -0.571 \\ -0.571 & 2.28 \end{bmatrix} \begin{bmatrix} 119.33 \\ -133.33 \end{bmatrix}$$

$$= \frac{1}{EI} \begin{bmatrix} 212.52 \\ -372.12 \end{bmatrix}$$

Element displacement (δ):

$$(\delta) = \{B\} \{U\}$$

$$= \begin{bmatrix} 0 & 0 \\ 1 & 0 \\ 1 & 0 \\ 0 & 1 \end{bmatrix} \frac{1}{EI} \begin{bmatrix} 212.52 \\ -372.12 \end{bmatrix}$$

$$= \frac{1}{EI} \begin{bmatrix} 0 \\ 212.52 \\ 212.52 \\ -372.12 \end{bmatrix}$$

Element forces (P')

$$P' = [k] [\delta]$$

$$= EI \begin{bmatrix} 0.5 & 0.25 & 0 & 0 \\ 0.25 & 0.5 & 0 & 0 \\ 0 & 0 & 0.5 & 0.25 \\ 0 & 0 & 0.25 & 0.5 \end{bmatrix} \frac{1}{EI} \begin{bmatrix} 0 \\ 212.52 \\ 212.52 \\ -372.12 \end{bmatrix}$$

$$= \begin{bmatrix} 53.13 \\ 106.26 \\ 13.23 \\ -132.93 \end{bmatrix}$$

final forces (P^f)

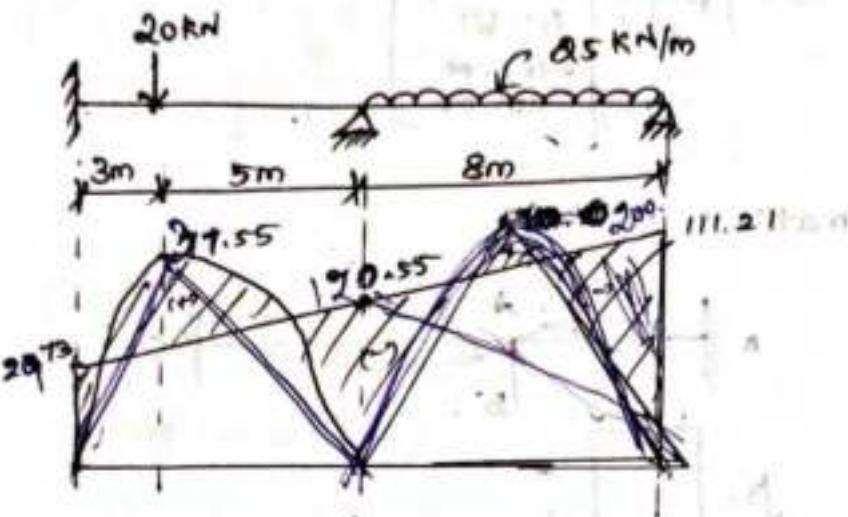
$$P^f = [P'] + [P']$$

$$= \begin{bmatrix} -23.43 \\ 4.06 \\ -133.33 \\ 133.33 \end{bmatrix} + \begin{bmatrix} 53.13 \\ 106.26 \\ 13.23 \\ -132.93 \end{bmatrix} = \begin{bmatrix} 29.7 \\ 120.32 \\ -120.1 \\ 0 \end{bmatrix}$$

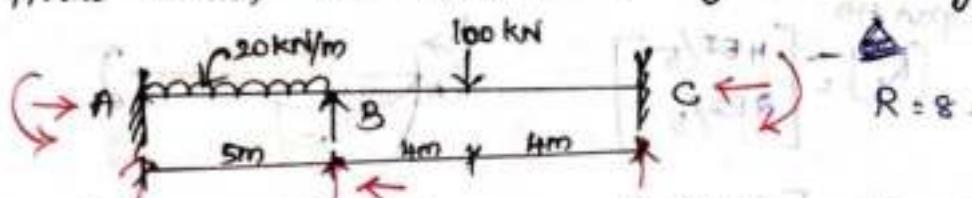
Maximum Bending moments:

$$M_{AB} = \frac{Wab}{l} = \frac{20 \times 3 \times 5}{8} = 37.5 \text{ kNm}$$

$$M_{BC} = \frac{WL^2}{8} = \frac{20 \times 8^2}{8} = 200 \text{ kNm.}$$



3. Analyse the continuous beam as shown in figure by stiffness method and draw the bending moment diagram.



Soln: Both ends are fixed, so the center will be a pin-jointed only.

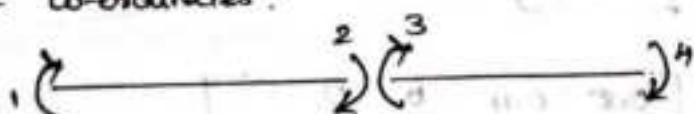
Kinematic Indeterminacy:

$$\begin{aligned}D_k &= 3j - R \\&= (3 \times 3) - 8 \\&= 1\end{aligned}$$

$$\begin{bmatrix} 31 \pm 3A \\ 31 \pm 3B \end{bmatrix}$$

System co-ordinate = 1 (B)

Element co-ordinates:



Fixed End Moments:

$$MF_{AB} = -\frac{WL^2}{12} = -\frac{20 \times 5^2}{12} = -41.67 \text{ kNm.}$$

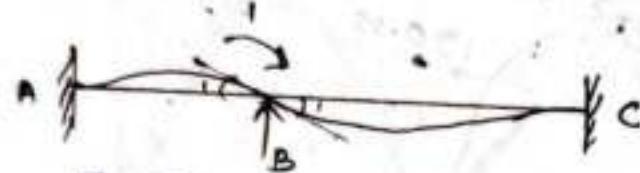
$$MF_{BA} = \frac{WL^2}{12} = \frac{20 \times 5^2}{12} = 41.67 \text{ kNm}$$

$$M_{FBc} = -\frac{Wl}{8} = \frac{100 \times 8}{8} = -100 \text{ kNm}$$

$$M_{FCB} = \frac{Wl}{8} = \frac{100 \times 8}{8} = 100 \text{ kNm}$$

$$[P^0] = \begin{bmatrix} -41.67 \\ 41.67 \\ -100.00 \\ 100.00 \end{bmatrix}$$

β matrix:

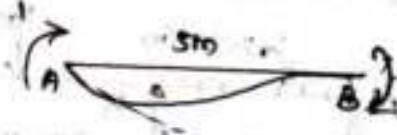


$$\beta = \begin{bmatrix} 0 \\ 1 \\ 1 \\ 0 \end{bmatrix}$$

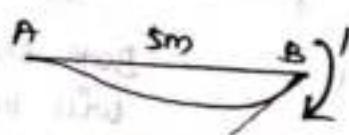
Element stiffness matrix:

Span AB:

$$[k_1] = \begin{bmatrix} 4EI/5 \\ 2EI/5 \end{bmatrix}$$

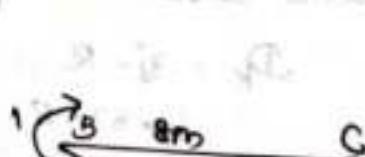


$$k_2 = \begin{bmatrix} 2EI/5 \\ 4EI/5 \end{bmatrix}$$

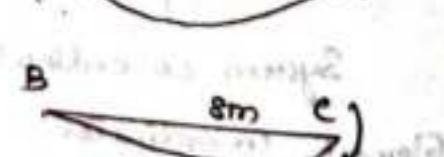


Span BC:

$$k_3 = \begin{bmatrix} 4EI/8 \\ 2EI/8 \end{bmatrix}$$



$$k_4 = \begin{bmatrix} 2EI/8 \\ AEI/8 \end{bmatrix}$$



$$[K] = \begin{bmatrix} 0.8 & 0.4 & 0 & 0 \\ 0.4 & 0.8 & 0 & 0 \\ 0 & 0 & 0.5 & 0.5 \\ 0 & 0 & 0.5 & 0.5 \end{bmatrix}$$

$$\text{Ansatz: } \begin{bmatrix} 1 & 2 & 3 & 4 \end{bmatrix} = \begin{bmatrix} 1 & 2 & 3 & 4 \end{bmatrix} \cdot \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} = \text{Ansatz M}$$

System Stiffness matrix :

$$[K] = [B]^T [k] [B]$$
$$= [0 \ 1 \ 1 \ 0] E_2 \begin{bmatrix} 0.8 & 0.4 & 0 & 0 \\ 0.4 & 0.8 & 0 & 0 \\ 0 & 0 & 0.5 & 0.25 \\ 0 & 0 & 0.25 & 0.5 \end{bmatrix} \begin{bmatrix} 0 \\ 1 \\ 1 \\ 0 \end{bmatrix}$$
$$= E_2 [0.4 \ 0.8 \ 0.5 \ 0.25] \begin{bmatrix} 0 \\ 1 \\ 1 \\ 0 \end{bmatrix}$$
$$= 1.3 E_2$$

$$[k]^{-1} = \frac{1}{1.3 E_2}$$

System displacement $[U]$:

$$[U] = [k]^{-1} \{ F^f - F^o \}$$

$[F^f]$ forces applied at system co-ordinates = 0.

(\therefore There is no external force at the system coordinates)

$$F^o = \text{Fixed coordinate forces} = [B]^T [P^o]$$
$$= [0 \ 1 \ 1 \ 0] \begin{bmatrix} -41.67 \\ 41.67 \\ -100 \\ 100 \end{bmatrix}$$
$$\therefore [-58.33],$$

$$U = \frac{1}{1.3 E_2} [0 - (-58.33)]$$

$$= \frac{58.33}{1.3 E_2} = \frac{44.86}{E_2}$$

Element displacement (δ) :

$$\delta = [B] [0]$$

$$= [0 \ 1 \ 1 \ 0] \frac{44.86}{E_2} = \frac{1}{E_2} \begin{bmatrix} 0 \\ 44.86 \\ 44.86 \\ 0 \end{bmatrix}$$

$$= \frac{1}{E_2} \begin{bmatrix} 0 \\ 44.86 \\ 44.86 \\ 0 \end{bmatrix}$$

Element forces $[P']$:

$$[P'] = [K][\delta]$$

$$\therefore EI \begin{bmatrix} 0.8 & 0.4 & 0 & 0 \\ 0.4 & 0.8 & 0 & 0 \\ 0 & 0 & 0.5 & 0.25 \\ 0 & 0 & 0.25 & 0.5 \end{bmatrix} / EI \begin{bmatrix} 0 \\ 44.86 \\ 44.86 \\ 0 \end{bmatrix}$$

$$= \begin{bmatrix} 17.94 \\ 35.88 \\ 22.43 \\ 11.215 \end{bmatrix}$$

Final forces (P_f):

$$P_f = [P^e] + [P']$$

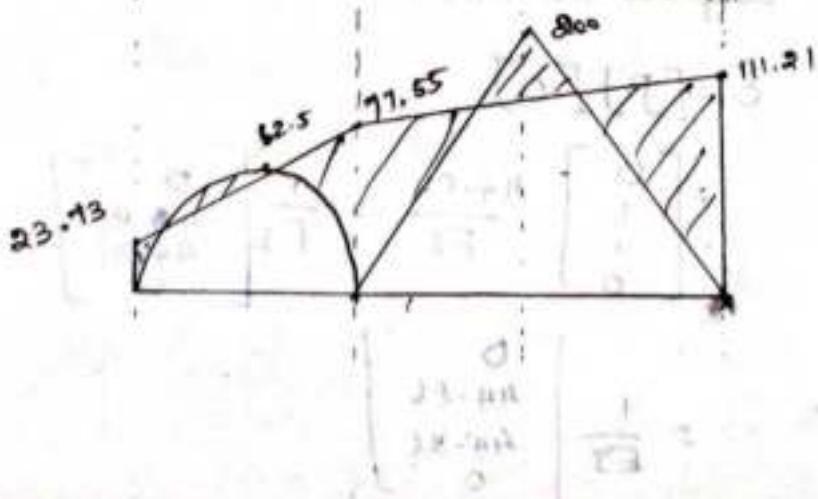
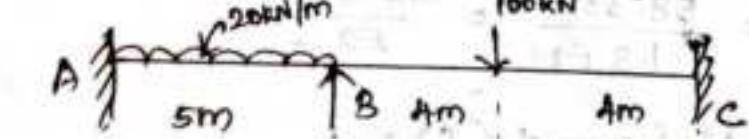
$$= \begin{bmatrix} -41.67 \\ 41.67 \\ -100 \\ 100 \end{bmatrix} + \begin{bmatrix} 17.94 \\ 35.88 \\ 22.43 \\ 11.215 \end{bmatrix}$$

$$= \begin{bmatrix} -23.73 \\ 77.55 \\ -77.55 \\ 111.21 \end{bmatrix}$$

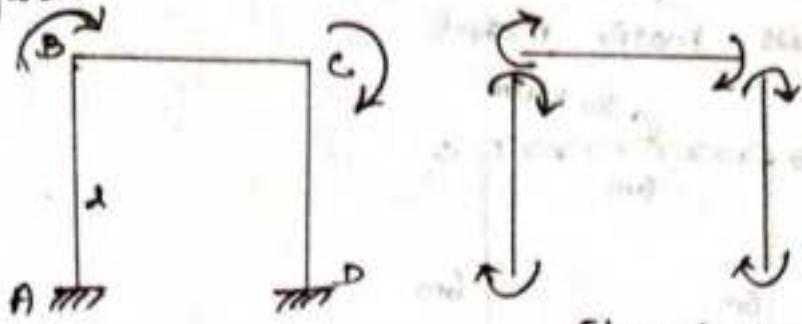
Maximum Bending Moment:

$$M_{AB} = \frac{Wl^2}{8} = \frac{200 \times 5^2}{8} = 62.5 \text{ kNm}$$

$$M_{BC} = \frac{Wl}{4} = \frac{100 \times 8}{4} = 200 \text{ kNm}$$



4. Generate the β matrix for the Portal frame as shown in figure.



Element coordinates

Soln:

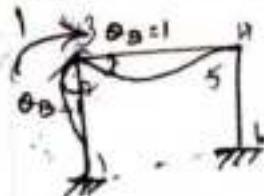
Kinematic indeterminacy:

$$D_K = 3j - (m+r)$$

Here there is 2 system coordinates and 6 element coordinates.

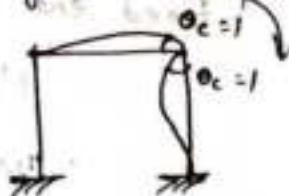
Apply unit rotation at first system coordinate

$$\beta = \begin{bmatrix} 0 \\ 1 \\ 1 \\ 0 \\ 0 \\ 0 \end{bmatrix}$$



Apply unit rotation at Second, system coordinate.

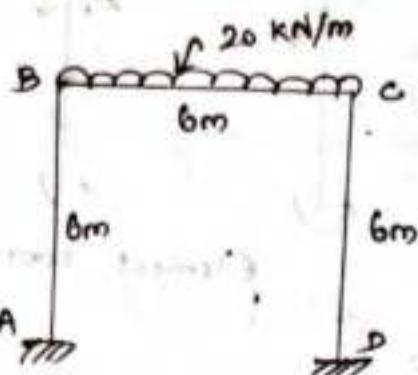
$$\beta = \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \\ -1 \\ -1 \\ 0 \end{bmatrix}$$



$$\beta = \begin{bmatrix} 0 & 0 \\ 1 & 0 \\ 1 & 0 \\ 0 & 1 \\ 0 & 1 \\ 0 & 0 \end{bmatrix}$$

$$\begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \end{bmatrix}$$

5. Find Bending Moment of the given frame by Stiffness matrix method.

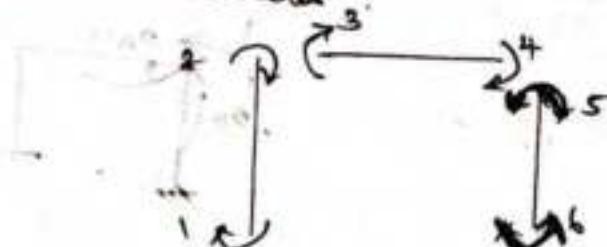


Sol:

Unknown displacements = θ_B, θ_C

System coordinates = & (B and C)

Element coordinates:



Fixed end moments:

$$MF_{AB} = MF_{BA} = 0$$

$$MF_{BC} = -\frac{Wl^2}{12} = -\frac{20 \times 6^2}{12}$$
$$= -60 \text{ kNm}$$

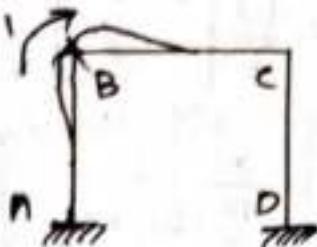
$$MF_{CB} = \frac{Wl^2}{12} = \frac{20 \times 6^2}{12} = 60 \text{ kNm}$$

$$MF_{CD} = MF_{DC} = 0$$

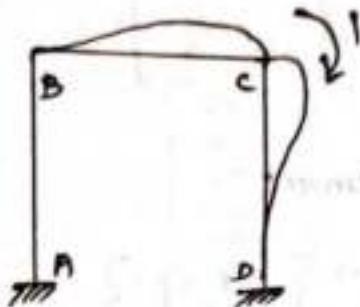
$$\vec{P} = \begin{bmatrix} 0 \\ 0 \\ -60 \\ 60 \\ 0 \\ 0 \end{bmatrix}$$

β Matrix :

$$\beta_1 = \begin{bmatrix} 0 \\ 1 \\ 0 \\ 0 \end{bmatrix}$$



$$\beta_2 = \begin{bmatrix} 0 \\ 0 \\ 0 \\ -1 \\ -1 \\ 0 \end{bmatrix}$$



$$\beta = \begin{bmatrix} 0 & 0 \\ 1 & 0 \\ 1 & 0 \\ 0 & 1 \\ 0 & 0 \\ 0 & 0 \end{bmatrix}$$

Element Stiffness Matrix :

$$K_1 = \frac{EI}{6} \begin{bmatrix} 4 & 2 \\ 2 & 4 \end{bmatrix}$$

$$K_2 = \frac{EI}{6} \begin{bmatrix} 4 & 2 \\ 2 & 4 \end{bmatrix} \quad K_3 = \frac{EI}{6} \begin{bmatrix} 4 & 2 \\ 2 & 4 \end{bmatrix}$$

$$k = \frac{EI}{6} \begin{bmatrix} 4 & 2 & 0 & 0 & 0 & 0 \\ 2 & 4 & 0 & 0 & 0 & 0 \\ 0 & 0 & 4 & 2 & 0 & 0 \\ 0 & 0 & 2 & 4 & 0 & 0 \\ 0 & 0 & 0 & 0 & 4 & 2 \\ 0 & 0 & 0 & 0 & 2 & 4 \end{bmatrix}$$

System Stiffness Matrix :

$$K = [\beta]^T [k] [\beta]$$

$$\begin{bmatrix} 0 & 1 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & 1 & 0 \end{bmatrix} \frac{EI}{6} \begin{bmatrix} 4 & 2 & 0 & 0 & 0 & 0 \\ 2 & 4 & 0 & 0 & 0 & 0 \\ 0 & 0 & 4 & 2 & 0 & 0 \\ 0 & 0 & 2 & 4 & 0 & 0 \\ 0 & 0 & 0 & 0 & 4 & 2 \\ 0 & 0 & 0 & 0 & 2 & 4 \end{bmatrix} \begin{bmatrix} 0 & 0 \\ 1 & 0 \\ 1 & 0 \\ 0 & 1 \\ 0 & 1 \\ 0 & 0 \end{bmatrix}$$

$$k = \frac{EI}{L} \begin{bmatrix} 8 & 2 \\ 2 & 8 \end{bmatrix}$$

$$\begin{aligned} k^{-1} &= \frac{1}{\frac{EI}{L}(64-4)} \begin{bmatrix} 8 & -2 \\ -2 & 8 \end{bmatrix} \\ &= \frac{1}{10EI} \begin{bmatrix} 8 & -2 \\ -2 & 8 \end{bmatrix} \end{aligned}$$

System displacement:

$$U = [k]^{-1} \{ F^t - f^o \}$$

$$\begin{aligned} f^o &= [B]^T [P^o] \\ &= \begin{bmatrix} 0 & 1 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & 1 & 0 \end{bmatrix} \begin{bmatrix} 0 \\ 0 \\ -60 \\ 60 \\ 0 \\ 0 \end{bmatrix} \\ &= \begin{bmatrix} -60 \\ 60 \end{bmatrix} \end{aligned}$$

$$\begin{aligned} U &= \frac{1}{10EI} \begin{bmatrix} 8 & -2 \\ -2 & 8 \end{bmatrix} \left\{ \begin{bmatrix} 0 \\ 0 \end{bmatrix} - \begin{bmatrix} -60 \\ 60 \end{bmatrix} \right\} \\ &= \frac{1}{EI} \begin{bmatrix} 60 \\ -60 \end{bmatrix} \end{aligned}$$

Element displacement:

$$\delta = [B][U]$$

$$= \begin{bmatrix} 0 & 0 \\ 1 & 0 \\ 1 & 0 \\ 0 & 1 \\ 0 & 0 \end{bmatrix} \frac{1}{EI} \begin{bmatrix} 60 \\ -60 \end{bmatrix}$$

$$= \frac{1}{EI} \begin{bmatrix} 0 \\ 60 \\ 60 \\ -60 \\ -60 \\ 0 \end{bmatrix}$$

Element force (P')

$$P = [k][\delta]$$

$$= \frac{EI}{L} \begin{bmatrix} 4 & 2 & 0 & 0 & 0 & 0 \\ 2 & 4 & 0 & 0 & 0 & 0 \\ 0 & 0 & 2 & 2 & 0 & 0 \\ 0 & 0 & 2 & 4 & 0 & 0 \\ 0 & 0 & 0 & 0 & 4 & 2 \\ 0 & 0 & 0 & 0 & 2 & 4 \end{bmatrix} \begin{bmatrix} 0 \\ 60 \\ 60 \\ -60 \\ -60 \\ 0 \end{bmatrix} \text{ kN}$$

$$= \frac{1}{6} \begin{bmatrix} 120 \\ 240 \\ 120 \\ -120 \\ -240 \\ -120 \end{bmatrix} = \begin{bmatrix} 20 \\ 40 \\ 20 \\ -20 \\ -40 \\ 20 \end{bmatrix}$$

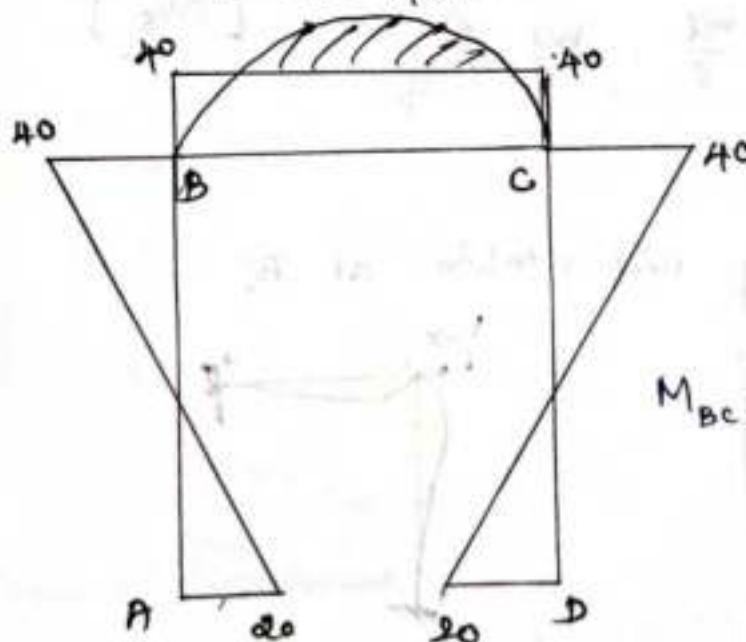
Final force (P^f):

$$P^f = P' + P$$

$$= \begin{bmatrix} 20 \\ 40 \\ 20 \\ -20 \\ -40 \\ -20 \end{bmatrix} + \begin{bmatrix} 0 \\ 0 \\ -60 \\ 60 \\ 0 \\ 0 \end{bmatrix}$$

$$= \begin{bmatrix} 20 \\ 40 \\ -40 \\ 40 \\ -40 \\ -20 \end{bmatrix} \text{ KNM.}$$

90 KNM

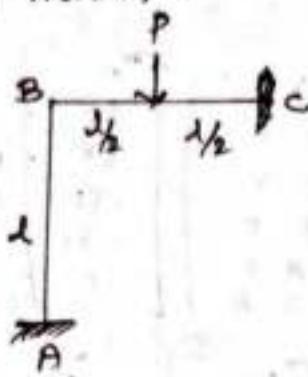


$$M_{BC} = \frac{Wl}{8}$$

$$= \frac{20 \times 6}{8}$$

$$= 90 \text{ KNM.}$$

b. Analyse the frame as shown in figure by Stiffness method



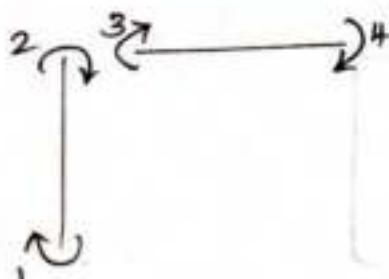
Soln:

System coordinates:

$$\text{Unknown displacements} = \theta_B$$

$$\text{System coordinate} = 1 (B)$$

Element coordinates:



Fixed end Moments:

$$MF_{AB} = MF_{BA} = 0$$

$$MF_{BC} = -\frac{wl}{8} = -\frac{Pl}{8}$$

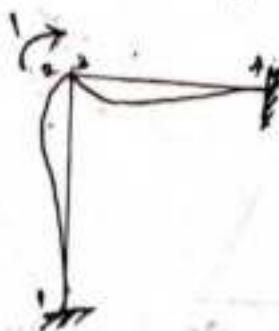
$$MF_{CB} = \frac{wl}{8} = \frac{Pl}{8}$$

$$P^o = \begin{bmatrix} 0 \\ 0 \\ -Pl/8 \\ Pl/8 \end{bmatrix}$$

β matrix:

Applying unit rotation at B,

$$\beta = \begin{bmatrix} 0 \\ 1 \\ 0 \\ 0 \end{bmatrix}$$



Element stiffness matrix:

$$K_1 = \frac{EI}{l} \begin{bmatrix} 4 & 2 \\ 2 & 4 \end{bmatrix} \quad K_2 = \frac{EI}{l} \begin{bmatrix} 4 & 2 \\ 2 & 4 \end{bmatrix}$$

$$K = \frac{EI}{l} \begin{bmatrix} 4 & 2 & 0 & 0 \\ 2 & 4 & 0 & 0 \\ 0 & 0 & 4 & 2 \\ 0 & 0 & 2 & 4 \end{bmatrix}$$

System stiffness matrix:

$$K = [B]^T [K] [B]$$

$$= \begin{bmatrix} 0 & 1 & 1 & 0 \end{bmatrix} \frac{EI}{l} \begin{bmatrix} 4 & 2 & 0 & 0 \\ 2 & 4 & 0 & 0 \\ 0 & 0 & 4 & 2 \\ 0 & 0 & 2 & 4 \end{bmatrix} \begin{bmatrix} 0 \\ 1 \\ 1 \\ 0 \end{bmatrix}$$

$$= \frac{8EI}{l}$$

$$k^{-1} = \frac{l}{8EI}$$

System displacement:

$$U = [k]^{-1} \{f^* - f^0\}$$

Element displacement:

$$\delta = [B][u]$$

$$f^0 = [B]^T [\phi] \\ = \begin{bmatrix} 0 & 1 & 1 & 0 \end{bmatrix} \begin{bmatrix} 0 \\ 0 \\ -P/8 \\ P/8 \end{bmatrix}$$

$$= \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} \frac{Pl^2}{64EI}$$

$$f^* = -P/8$$

$$f^* - f^0 = 0 - (-P/8) = P/8$$

$$U = l/8EI \left[\frac{Pl^2}{64EI} \right]$$

$$= \frac{Pl^2}{64EI}$$

done!
Element displacement:

$$\phi = [k][\delta] = \frac{EI}{l} \begin{bmatrix} 4 & 2 & 0 & 0 \\ 2 & 4 & 0 & 0 \\ 0 & 0 & 4 & 2 \\ 0 & 0 & 2 & 4 \end{bmatrix} \begin{bmatrix} 0 \\ 1 \\ 1 \\ 0 \end{bmatrix} \frac{Pl^2}{64EI}$$

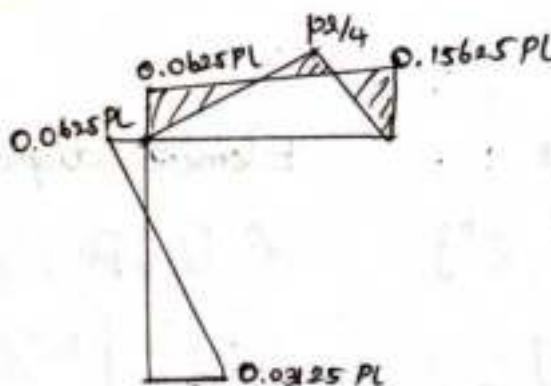
$$P' = \frac{P\ell}{64} \begin{bmatrix} 2 \\ 4 \\ 4 \\ 2 \end{bmatrix}$$

Final forces:

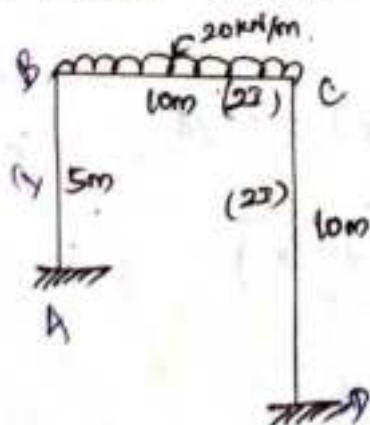
$$\begin{aligned} P^f &= P^o + P' \\ &= \begin{bmatrix} 0 \\ 0 \\ -P\ell/8 \\ P\ell/8 \end{bmatrix} + \frac{P\ell}{64} \begin{bmatrix} 2 \\ 4 \\ 4 \\ 2 \end{bmatrix} \\ &= P\ell \begin{bmatrix} 0.031 \\ 0.0625 \\ -0.0625 \\ 0.15625 \end{bmatrix} \end{aligned}$$

Maximum Bending moment:

$$M_{BC} = \frac{WJ}{4} = \frac{P\ell}{4} \cdot 0.25\ell$$

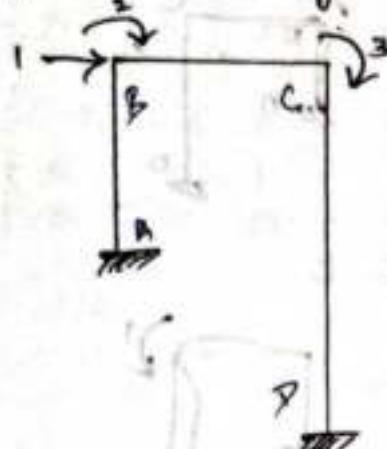


7. Analyze the frame as shown in figure by Stiffness matrix method.



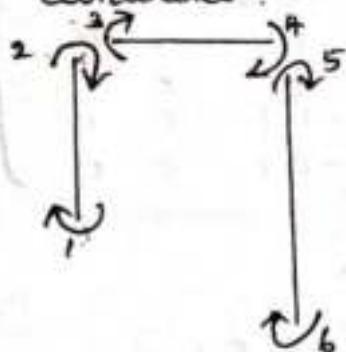
Soln:

3 kinematic indeterminacy:



This structure is kinematically indeterminate to 3 degree ($\theta_B, \delta_B, \theta_C$)

Element coordinates:



Element coordinates = 6.

fixed end moments:

$$MF_{AB} = MF_{CB} = MF_{CD} = MF_{DA} = 0.$$

$$MF_{BC} = -\frac{Wl^2}{12} = -\frac{20 \times 10^2}{12} = -166.67 \text{ kNm}.$$

$$MF_{CB} = \frac{Wl^2}{12} = \frac{20 \times 10^2}{12} = 166.67 \text{ kNm}.$$

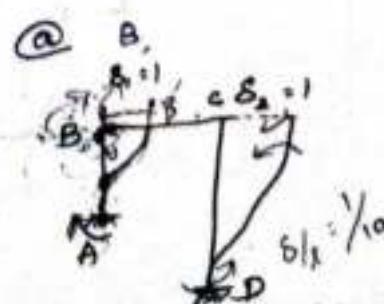
$$\rho^0 = \begin{bmatrix} 0 \\ 0 \\ -166.67 \\ 166.67 \\ 0 \\ 0 \end{bmatrix}$$

B matrix:

Applying unit displacement

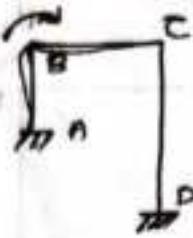
$$B_1 = \begin{bmatrix} -1/5 \\ -1/5 \\ 0 \\ 0 \\ -1/10 \\ -1/10 \end{bmatrix}$$

$$S/l_1^{1/6}$$



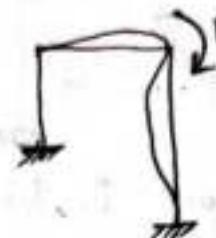
Applying unit rotation @ B.

$$\beta_2 = \begin{bmatrix} 0 \\ 1 \\ 1 \\ 0 \\ 0 \\ 0 \end{bmatrix}$$



Applying unit rotation @ C

$$\beta_3 = \begin{bmatrix} 0 \\ 0 \\ 0 \\ 1 \\ 1 \\ 0 \end{bmatrix}$$



$$\beta_1 = \begin{bmatrix} -0.2 \\ -0.2 \\ 0 \\ 0 \\ -0.1 \\ 0.1 \end{bmatrix}$$

$$\beta = \begin{bmatrix} -0.2 & 0 & 0 \\ -0.2 & 1 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \\ -0.1 & 0 & 1 \\ -0.1 & 0 & 0 \end{bmatrix}$$

Element Stiffness Matrix:

$$k_1 = \frac{EI}{5} \begin{bmatrix} 4 & 2 \\ 2 & 4 \end{bmatrix} = EI \begin{bmatrix} 0.8 & 0.4 \\ 0.4 & 0.8 \end{bmatrix}$$

$$k_2 = \frac{EI_{22}}{10} \begin{bmatrix} 4 & 2 \\ 2 & 4 \end{bmatrix} = EI \begin{bmatrix} 0.8 & 0.4 \\ 0.4 & 0.8 \end{bmatrix}$$

$$k_3 = \frac{EI_{22}}{10} \begin{bmatrix} 4 & 2 \\ 2 & 4 \end{bmatrix} = EI \begin{bmatrix} 0.8 & 0.4 \\ 0.4 & 0.8 \end{bmatrix}$$

$$[k] = EI \begin{bmatrix} 0.8 & 0.4 & 0 & 0 & 0 & 0 \\ 0.4 & 0.8 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0.8 & 0.4 & 0 & 0 \\ 0 & 0 & 0.4 & 0.8 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0.8 & 0.4 \\ 0 & 0 & 0 & 0 & 0.4 & 0.8 \end{bmatrix}$$

System stiffness matrix:

$$K = [\beta]^T [k] [\beta]$$

$$= \begin{bmatrix} -0.2 & -0.2 & 0 & 0 & -0.1 & -0.1 \\ 0 & 1 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & 1 & 0 \end{bmatrix} E_2 \begin{bmatrix} 0.8 & 0.4 & 0 & 0 & 0 & 0 \\ 0.4 & 0.8 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0.8 & 0.4 & 0 & 0 \\ 0 & 0 & 0.4 & 0.8 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0.8 & 0.4 \\ 0 & 0 & 0 & 0 & 0.4 & 0.8 \end{bmatrix} \begin{bmatrix} -0.2 & 0 & 0 \\ -0.2 & 1 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \\ -0.1 & 0 & 1 \\ -0.1 & 0 & 0 \end{bmatrix} \begin{bmatrix} 0.12 & -0.24 & -0.12 \\ -0.24 & 1.6 & 0.4 \\ -0.12 & 0.4 & 1.6 \end{bmatrix}$$

System displacement $[U]$:

$$[U] = [K]^{-1} \{ f^t - f^o \} \quad A^{-1} = \frac{1}{|A|} \text{adj } A$$

$$[K]^{-1} = \frac{1}{EI} \begin{bmatrix} 12.25 & 1.715 & 0.490 \\ 1.715 & 0.906 & -0.098 \\ 0.490 & -0.098 & 0.686 \end{bmatrix} \quad F^o = (\beta)^T [P^o]$$

$$F^o = \begin{bmatrix} 0 \\ -166.67 \\ 166.67 \end{bmatrix}$$

$$[U] = \frac{1}{EI} \begin{bmatrix} 12.25 & 1.715 & 0.490 \\ 1.715 & 0.906 & -0.098 \\ 0.490 & -0.098 & 0.686 \end{bmatrix} \begin{bmatrix} 0 \\ 166.67 \\ -166.67 \end{bmatrix}$$

$$= \frac{1}{EI} \begin{bmatrix} 204.17 \\ 167.33 \\ -130.66 \end{bmatrix}$$

Element displacement (δ):

$$\delta = [\beta][U]$$

$$= \begin{bmatrix} -0.2 & 0 & 0 \\ -0.2 & 1 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \\ -0.1 & 0 & 1 \\ -0.1 & 0 & 0 \end{bmatrix} \frac{1}{EI} \begin{bmatrix} 204.17 \\ 167.33 \\ -130.66 \end{bmatrix}$$

$$\delta = \frac{1}{EI} \begin{bmatrix} -40.83 \\ 126.496 \\ 167.33 \\ -130.66 \\ -151.07 \\ -20.47 \end{bmatrix}$$

Element Forces:

$$P' = [k][\delta]$$

$$= EI \begin{bmatrix} 0.8 & 0.4 & 0 & 0 & 0 & 0 \\ 0.4 & 0.8 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0.8 & 0.4 & 0 & 0 \\ 0 & 0 & 0.4 & 0.8 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0.8 & 0.4 \\ 0 & 0 & 0 & 0 & 0.4 & 0.8 \end{bmatrix} \begin{bmatrix} -40.83 \\ 126.496 \\ 167.33 \\ -130.66 \\ -151.07 \\ -20.47 \end{bmatrix}$$

$$= \begin{bmatrix} 17.93 \\ 84.86 \\ 81.60 \\ -37.59 \\ -129.04 \\ -76.80 \end{bmatrix} \quad (6 \times 1) \quad (6 \times 1)$$

Final Forces:

$$P^f = P^e + P'$$

$$= \begin{bmatrix} 0 \\ 0 \\ -166.67 \\ 166.67 \\ 0 \\ 0 \end{bmatrix} + \begin{bmatrix} 17.93 \\ 84.86 \\ 81.60 \\ -37.59 \\ -129.04 \\ -76.80 \end{bmatrix}$$

$$= \begin{bmatrix} 17.9 \\ 85 \\ -85 \\ 129 \\ -129 \\ -76.80 \end{bmatrix}$$

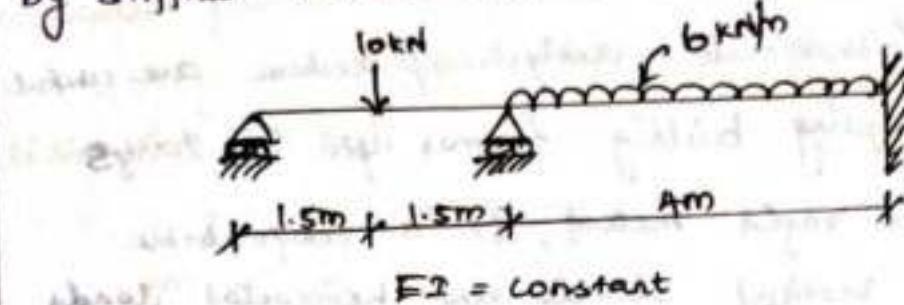
Maximum Bending moment:

$$M_{AB} = M_{EP} = 0$$

$$M_{AC} = \frac{wl^2}{8} = \frac{20 \times 10^2}{8} = 250 \text{ kNm}$$

Assignment - a Problems:

1. Analyse the continuous beam as shown in figure by stiffness matrix method and sketch the BMD.



2. Analyse the portal frame ABCD shown in figure by stiffness matrix method and also sketch the BMD.

