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DEPARTMENT OF MECHATRONICS ENGINEERING

Radial Basis Function Networks (RBFNs) are widely used for **function interpolation** and **approximation** due to their ability to model complex, high-dimensional functions.

- Interpolation: RBFNs can be trained to pass exactly through given data points.
- **Approximation:** RBFNs can be used to **approximate** a function when there is noise or when exact fitting is unnecessary.

Applications:

- ✓ Engineering (surface fitting, robotics)
- ✓ Finance (trend prediction)
- ✓ Medical imaging (image reconstruction)
- ✓ Machine learning (data classification, regression)

2. Understanding Function Interpolation with RBFNs

Definition of Interpolation

Given a dataset of N points (x_i, y_i) , interpolation constructs a function f(x) such that:

 $f(x_i)=y_i \hspace{1em} orall i \in \{1,2,...,N\}$

This means the function **exactly** passes through the given data points.

Using RBFNs for Interpolation

An RBFN models the function as:

$$f(x)=\sum_{i=1}^N w_i \phi(\|x-c_i\|)$$

where:

- c_i are **centers** (typically chosen as data points).
- w_i are weights to be determined.
- $\phi(r)$ is a radial basis function (commonly Gaussian):

$$\phi(r) = \exp\left(-rac{r^2}{2\sigma^2}
ight)$$

Solving for Weights (w_i)

Since interpolation requires exact fitting, we set up the system:

$$\Phi W = Y$$

where:

- Φ is the activation matrix with entries $\Phi_{ij} = \phi(\|x_i c_j\|)$.
- W is the vector of unknown weights.
- Y is the vector of target outputs.

3. Understanding Function Approximation with RBFNs

Definition of Approximation

In **approximation**, we do not require an exact fit but instead minimize the **error** between predicted values and true values:

$$E=\sum_{i=1}^N(y_i-f(x_i))^2$$

This is useful when:

- Data contains noise.
- An exact fit leads to overfitting.
- The number of centers c_i is smaller than the number of data points.

Using RBFNs for Approximation

$$f(x)=\sum_{i=1}^M w_i \phi(\|x-c_i\|)$$

where M < N (fewer centers than data points).

To find the weights, we use Least Squares Approximation instead of exact matrix inversion:

$$W = (\Phi^T \Phi)^{-1} \Phi^T Y$$

This finds the **best approximation** in a **least squares sense**.

Choosing Centers for Approximation

- Clustering methods (K-Means, Random Selection) to select a subset of data points as centers.
- Regularization (Ridge Regression, L2 norm) to avoid overfitting.
- Cross-validation to tune spread parameter σ .

Key Properties of RBFN for Approximation

- Handles noisy data better.
- Less prone to overfitting.
- Faster computation than exact interpolation.
- Generalizes well to unseen data.