

# **SNS COLLEGE OF TECHNOLOGY**

**Coimbatore-35 An Autonomous Institution** 

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## **DEPARTMENT OF AEROSPACE ENGINEERING**

## **19ASZ301– ROBOTICS & AUTOMATION IN SPACE**

### **III YEAR VI SEM**

## **UNIT 3 – MOTION CONTROL AUTOMATION**

**TOPIC - Selection of Motors for Automation** 





# **CLASSFICATION OF MOTORS**

				Motor Type	Use Case & Features	Applications
				Output: A Constant Sector Motor	Reliable, robust, low-cost	Fans, pumps, conveyors (constant speed)
DC Motor BLDC Motor	bc Gear Motor	RC Servo motor	Stepper motor   Linear electric actuator	DC Motor	Speed control, simple, high torque	AGVs, actuators, light-duty drives
				Stepper Motor	Precise steps, open-loop control	3D printers, CNC, pick & place
				Servo Motor	High precision + feedback (closed-loop)	Robotics, CNC machines, automation arms
				🎸 BLDC Motor	Efficient, quiet, high-speed control	Drones, electric vehicles, compact robots
				🚄 Linear Motor	Direct linear motion without rotation	Actuators, transport lines, pick & place
				🔨 Torque Motor	High torque at low speeds	Indexing tables, direct-drive systems

MOTION CONTROL AUTOMATION/19ASZ301 ROBOTICS AND AUTOMATION IN SPACE/RAMESH M/AERO/SNSCT





## PROCESS



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### **Step-by-Step Motor Selection Process**

**V** Step 1: Define Application Requirements

- Load (static & dynamic)
- Required motion profile
- Speed and acceleration

Step 2: Calculate Load Torque and Speed

- Use formulas for rotational or linear systems:
  - Torque (T) = Force  $\times$  Radius
  - $\circ$  Speed (RPM) = Linear speed  $\times$  60 / (2 $\pi$   $\times$ Radius)
- **Step 3: Choose Motor Type** 
  - High precision?  $\rightarrow$  Servo or stepper
  - Simple motion?  $\rightarrow$  AC or DC motor
  - High efficiency and low noise?  $\rightarrow$  BLDC
  - Linear motion needed?  $\rightarrow$  Linear motor

### Step 5: Select Drive/Controller

### **Q** Example: Selecting Motor for Conveyor Belt

- Load: 20 kg
- Speed: 30 m/min
- Duty cycle: Continuous
- **Suggested motor:**



Step 4: Determine Control Method • Open-loop (simple, cheaper): Stepper, AC motor • Closed-loop (accurate, safer): Servo, BLDC with encoder

• Compatible with motor type and system logic • Supports required communication (EtherCAT, Modbus, etc.)

• Control: Basic ON/OFF with variable speed • AC induction motor with VFD (variable frequency drive)



Thank You

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