



# **SNS COLLEGE OF TECHNOLOGY**

**(An Autonomous Institution)**



**COIMBATORE-35**

**Accredited by NBA-AICTE and Accredited by NAAC – UGC with A+ Grade  
Approved by AICTE, New Delhi & Affiliated to Anna University, Chennai**

**DEPARTMENT OF ELECTRICAL AND ELECTRONICS ENGINEERING**

**COURSE NAME: 23EET204/ ELECTRICAL MACHINES II**

**II YEAR / IV SEMESTER**

**Unit 1 – SYNCHRONOUS GENERATOR**

**Topic 7: Voltage regulation - EMF, MMF, and ZPF methods**



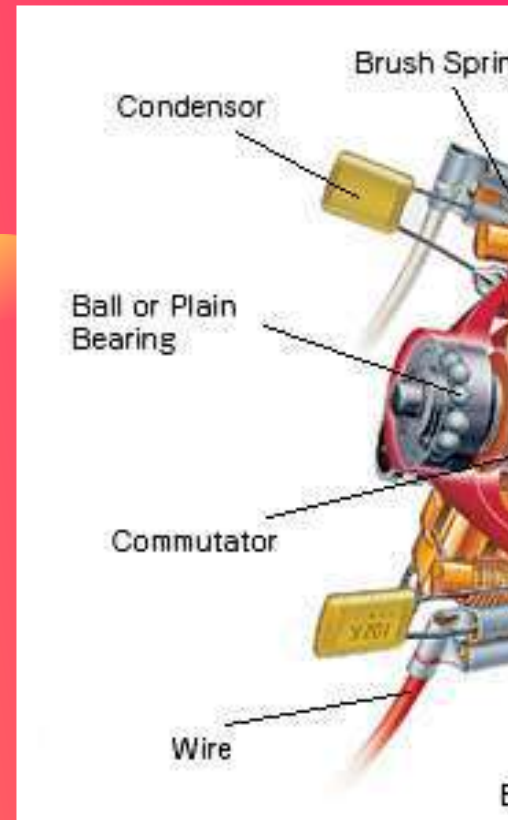


# VOLTAGE REGULATION

Voltage Regulation of an alternator is defined as the change in terminal voltage from **NO load** to **full load** divided by **full-load voltage**.

$$\% \text{ Voltage Regulation} = \frac{\text{NO load voltage} - \text{Full load voltage}}{\text{Full load Voltage}} \times 100$$

$$\% \text{ Voltage Regulation} = \frac{E_0 - V}{V} \times 100$$





# Methods

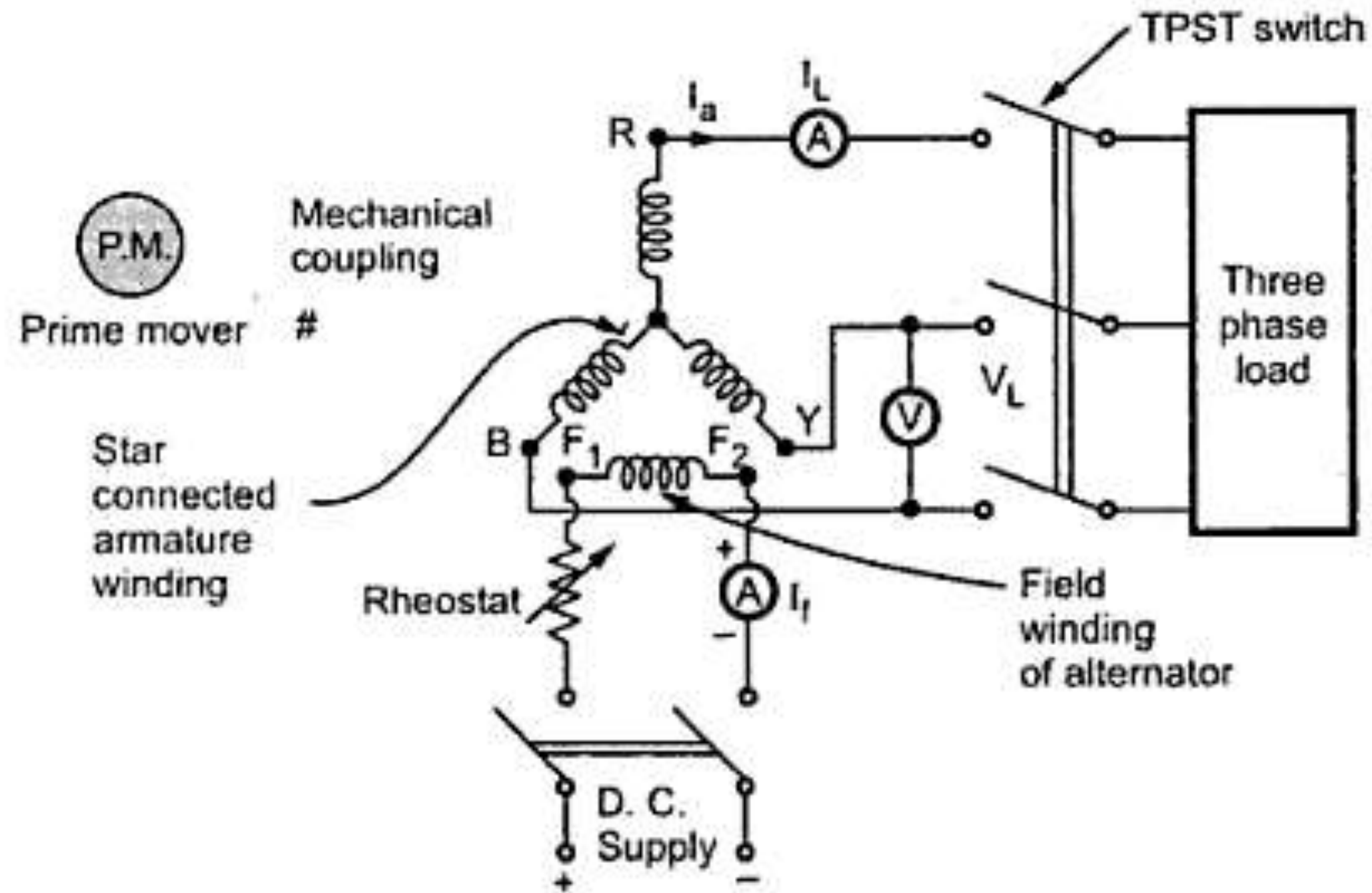
There are different methods available to determine the voltage regulation of an alternator,

1. Direct loading method
2. Synchronous impedance method or E.M.F. method
3. Ampere-turns method or M.M.F. method
4. Zero power factor method or Potier triangle method
5. ASA modified from of M.M.F. method
6. Two reaction theory





# Direct loading method





# Direct loading method

The star connected **armature** is to be connected to a **three phase load**.  
The **field winding** is excited by separate **d.c. supply**.

To **control the flux** i.e. the current through field winding, a **rheostat is inserted in series** with the field winding.

The **prime mover** drives the alternator at its **synchronous speed**.

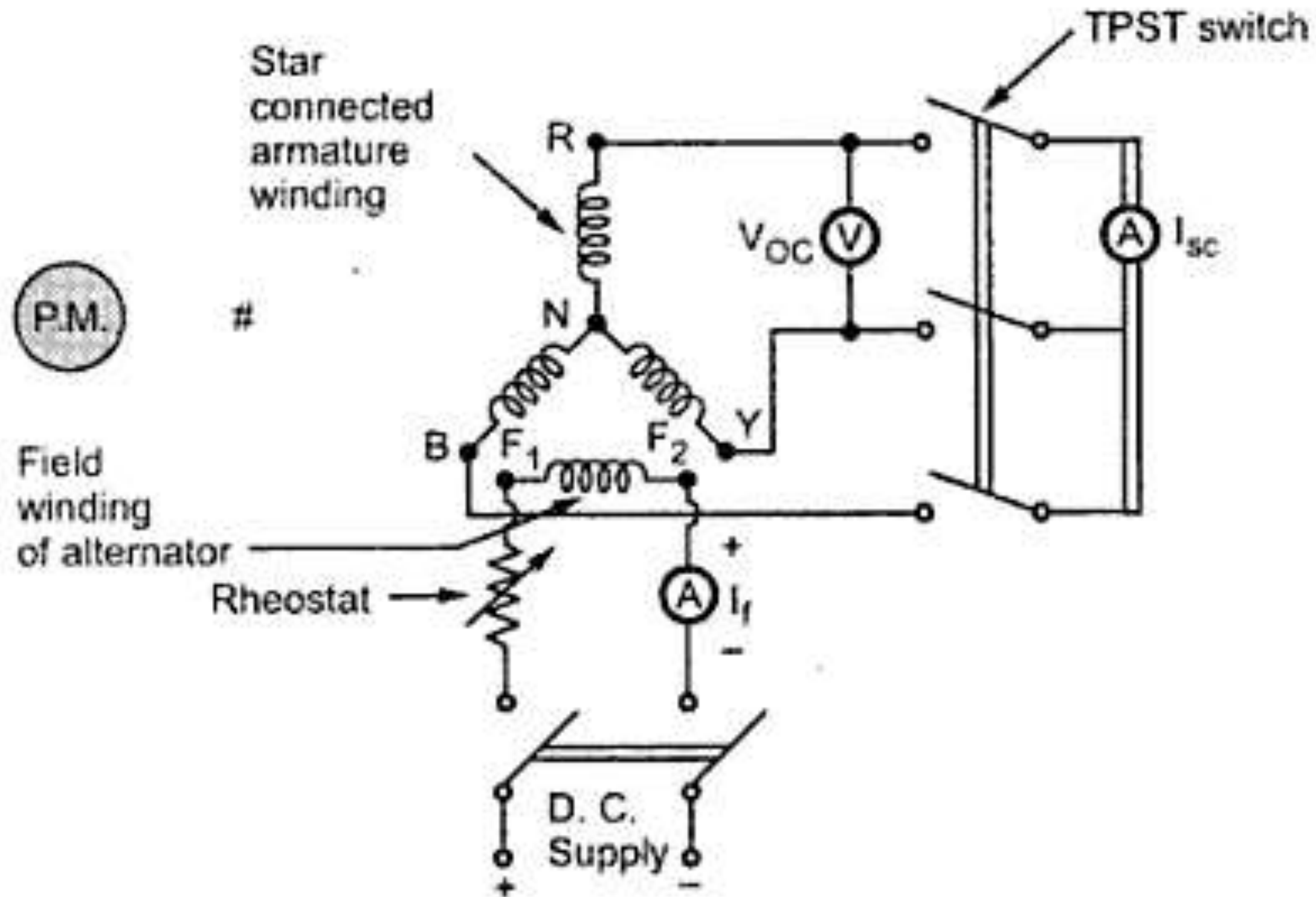
$$E_{ph} \propto \Phi \text{ ..... (From e.m.f. equation)}$$

$$\% \text{ Reg} = \frac{E_{ph} - V_{ph}}{V_{ph}} \times 100$$

For **high capacity** alternators, that much **full load** **can not** be simulated or directly connected to the alternator. Hence method is **restricted only for small capacity alternators**.



# Synchronous Impedance Method or E.M.F. Method







# Synchronous Impedance Method or E.M.F. Method

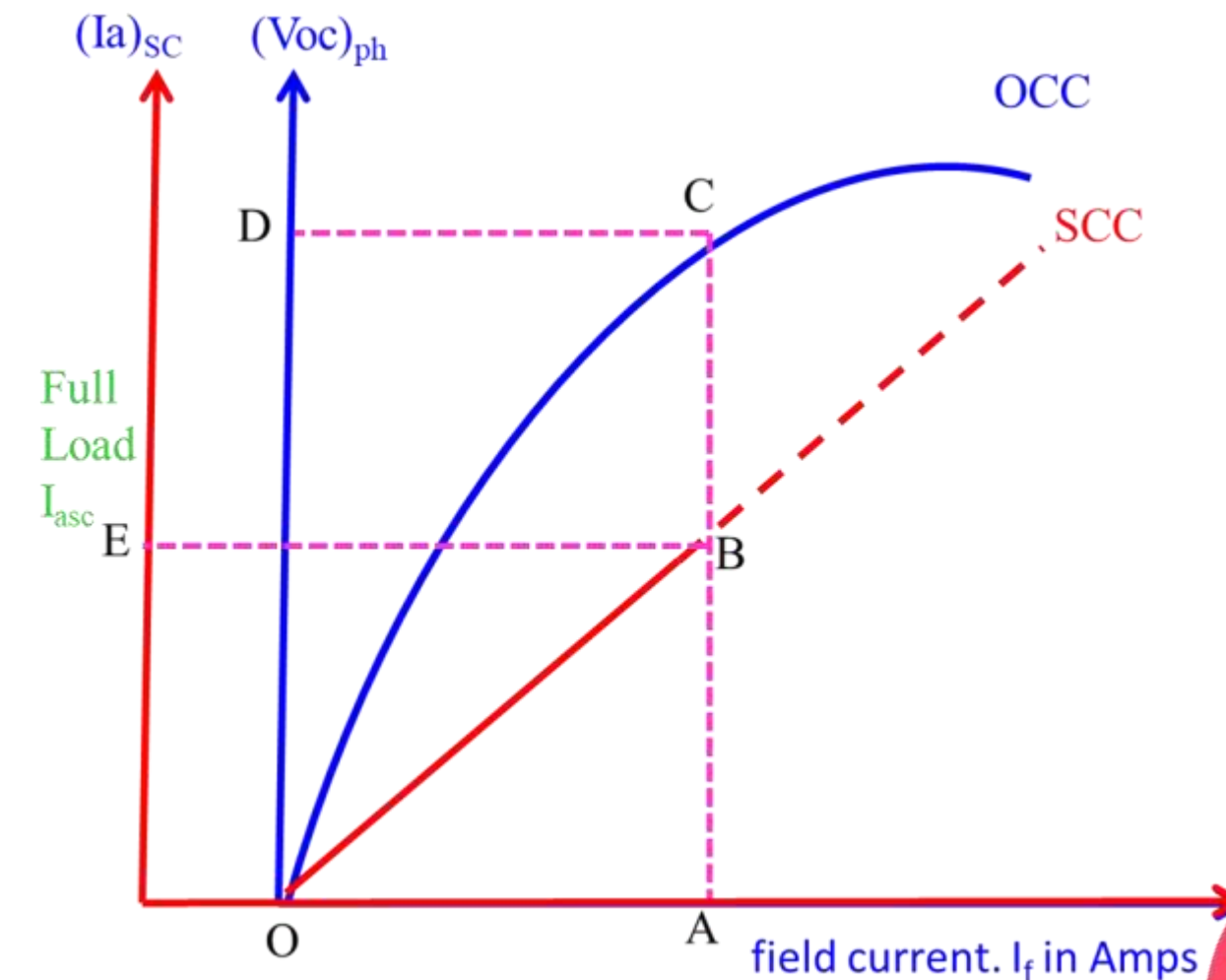
The method requires following data to calculate the regulation.

1. The **armature resistance per phase ( $R_a$ )**.
2. Open circuit characteristics which is the graph of **open circuit voltage** against the **field current**. This is possible by conducting **open circuit test** on the alternator.
3. Short circuit characteristics which is the graph of **short circuit current** against **field current**. This is possible by conducting **short circuit test** on the alternator.

$Z_s$  is calculated.

$R_a$  measured and  $X_s$  obtained.

For a given armature current and power factor,  $E_{ph}$  determined - regulation is calculated.





# Synchronous Impedance Method or E.M.F. Method

Synchronous Impedance

$$Z_s = \frac{(V_{oc})_{ph}}{I_{asc}}$$

$$Z_s = \frac{\text{Phase emf on Open Circuit}}{\text{Phase Current on Short Circuit}}$$

$$Z_s = \frac{OD (V_{oc})_{ph}}{OE (I_{asc})}$$

Regulation Calculation

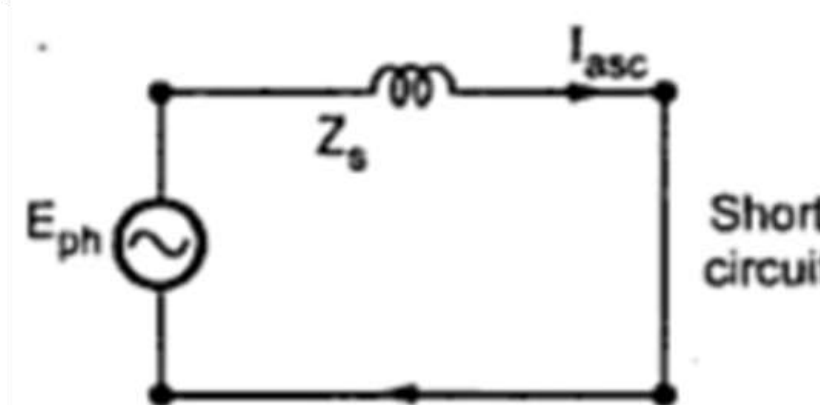
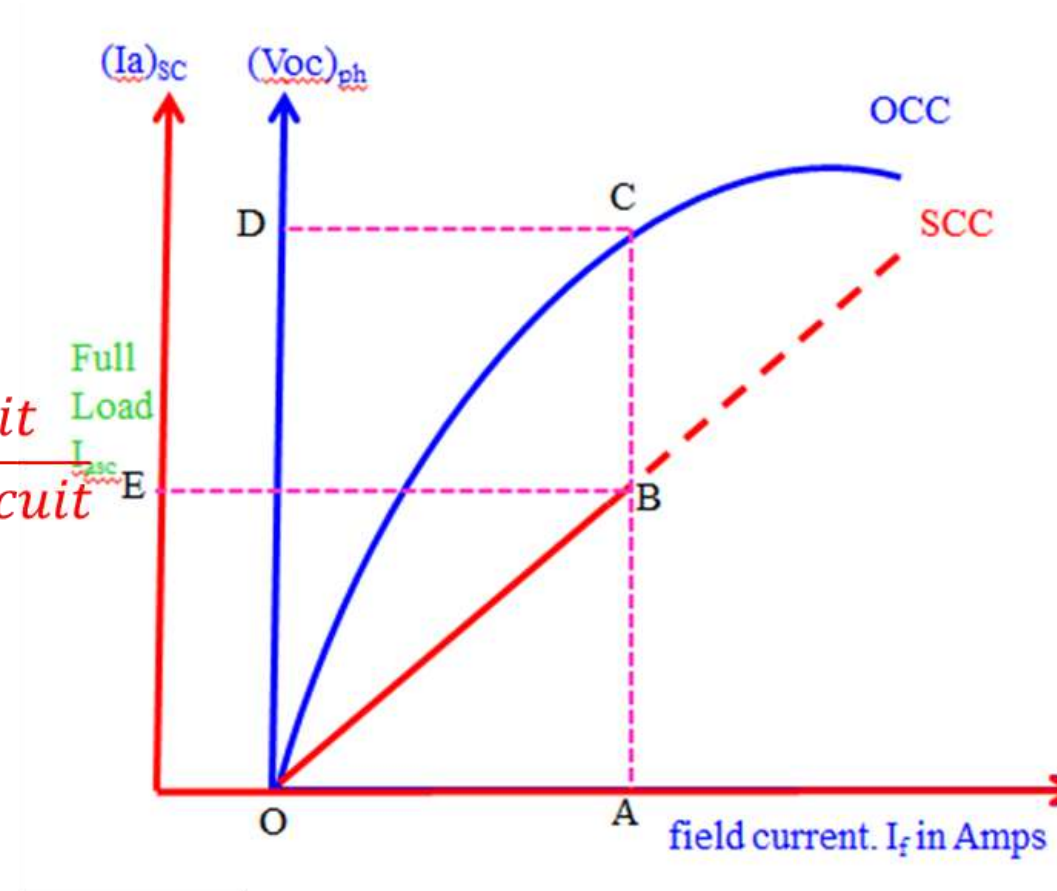
$$Z_s = \sqrt{(R_a)^2 + (X_s)^2}$$

$X_s$

$$X_s = \sqrt{(Z_s)^2 - (R_a)^2}$$

$$E_{ph} = \sqrt{(V_{ph} \cos \Phi + I_a R_a)^2 + (V_{ph} \sin \Phi \pm I_a X_s)^2}$$

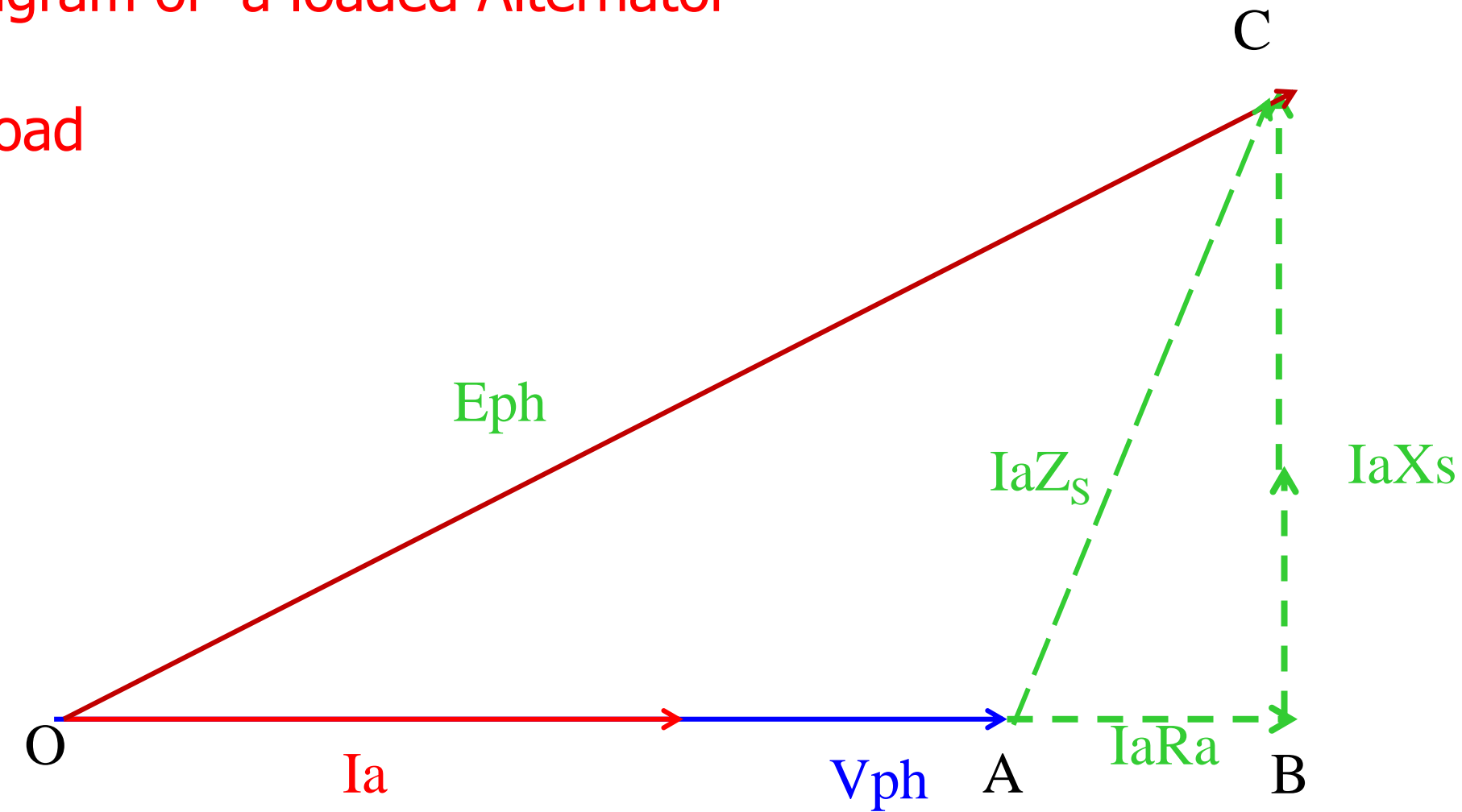
$$\% \text{ Regulation} = \frac{E_{ph} - V_{ph}}{V_{ph}} \times 100$$





## Phasor Diagram of a loaded Alternator

Unity PF Load



Reference as Voltage (V)

$OA - V_{ph}$

$AB - I_a R_a$

$BC - I_a X_s$

$AC - I_a Z_s$

$OC - E_{ph}$

Consider  $\Delta OBC$

$$(OC)^2 = (OB)^2 + (BC)^2$$

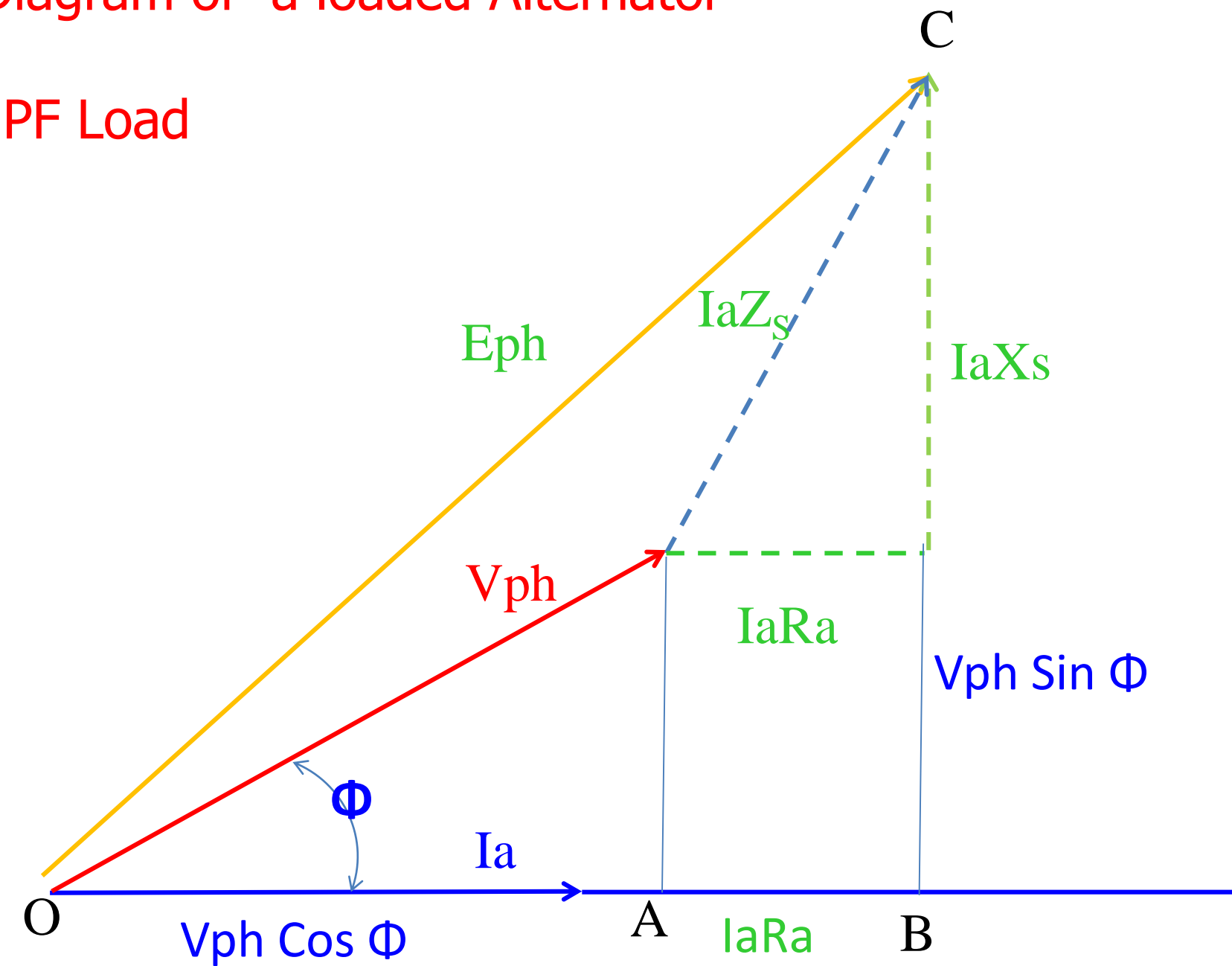
$$(E_{ph})^2 = (OA + AB)^2 + (BC)^2$$

$$(E_{ph})^2 = (V_{ph} + I_a R_a)^2 + (I_a X_s)^2$$

$$E_{ph} = \sqrt{(V_{ph} + I_a R_a)^2 + (I_a X_s)^2}$$

## Phasor Diagram of a loaded Alternator

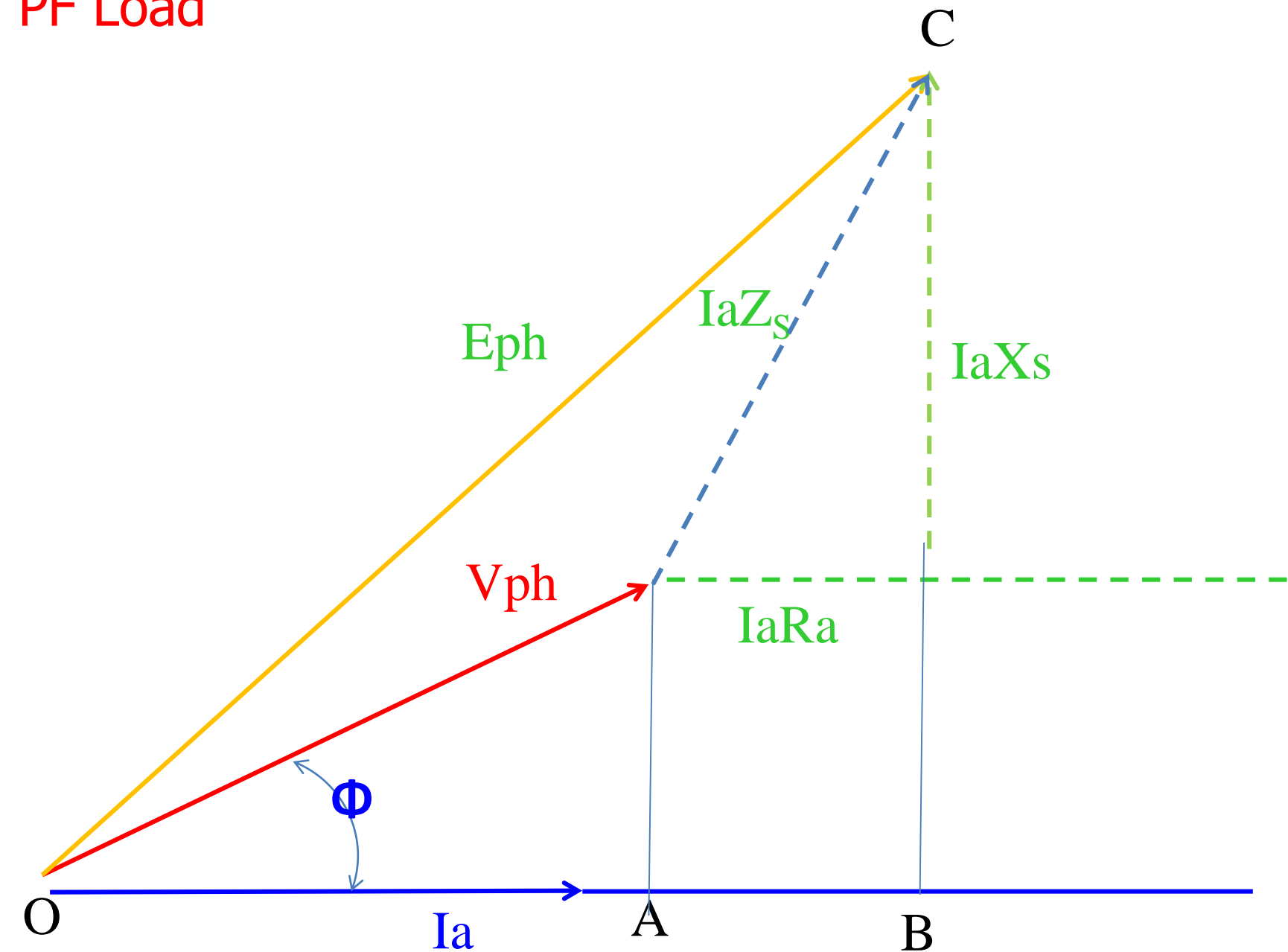
Lagging PF Load



$$E_{ph} = \sqrt{(V_{ph} \cos \Phi + I_a R_a)^2 + (V_{ph} \sin \Phi + I_a X_s)^2}$$

## Phasor Diagram of a loaded Alternator

Leading PF Load



$$E_{ph} = \sqrt{(V_{ph} \cos \Phi + I_a R_a)^2 + (V_{ph} \sin \Phi - I_a X_s)^2}$$





# Synchronous Impedance Method or E.M.F. Method



## Advantages of Synchronous Impedance Method

The main advantages of this method is the value of **synchronous impedance  $Z_s$**  for **any load condition** can be calculated.

Regulation of the alternator at **any load condition and load power factor** can be determined.

Actual **load need not be connected** to the alternator

This method can be **used for very high capacity alternators**

## Limitations of Synchronous Impedance Method

The **main limitation** of this method is that this method gives **large values of synchronous reactance**.

This leads to **high values of percentage regulation** than the actual results.

Hence this method is called **pessimistic method**.



# MMF method (Ampere turns method)



This method of determining the regulation of an alternator is also called **Ampere-turn method or Rothert's M.M.F. method.**

The method is based on the results of open circuit test and short circuit test on an alternator.

For any synchronous generator i.e. alternator, it requires M.M.F. which is product of field current and turns of field winding for two separate purposes.

1. It must have an M.M.F. necessary to induce the rated terminal voltage on open circuit.
2. It must have an M.M.F. equal and opposite to that of armature reaction m.m.f.



# MMF method (Ampere turns method)



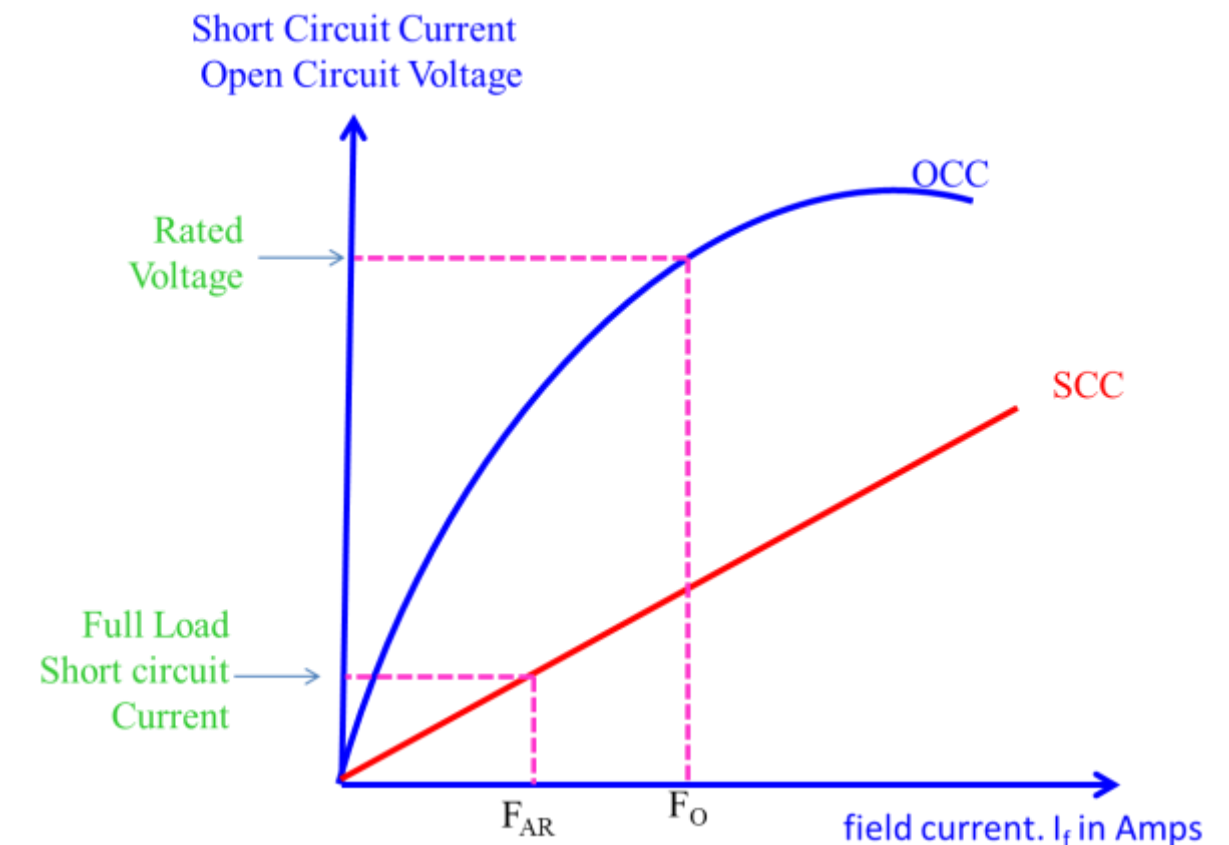
## OC & SC tests conducted

field currents

$I_{f1}$  (field current required to **produce a voltage** of  $(V_{ph} + I_{aph} R_a \cos\Phi)$  on **OC**)

$I_{f2}$  (field current required to produce the given **armature current** on SC) are added at an angle of  $(90 \pm \Phi)$ .

For this total field current,  $E_{ph}$  found from OCC and regulation calculated.





## Zero Power Factor Method (ZPF Method) or Potier method

This method is also called **Potier method**.

In the operation of any alternator, Voltage drop occurs in

**Armature resistance drop ( $IR_a$ )**

**Armature leakage reactance drop  $IX_L$**

Mainly due  
**EMF** quantity

**Armature reaction.**

→ is basically **M.M.F.** quantity

In the **synchronous impedance** method all the quantities are treated as **E.M.F. quantities**

In the **MMF Method** all the quantities are treated as **M.M.F. quantities**

The ZPF method is based on the Separation of  
**Armature leakage reactance ( $X_L$ )** and  
**Armature reaction effect**

The armature leakage reactance  $X_L$  is called **Potier reactance**

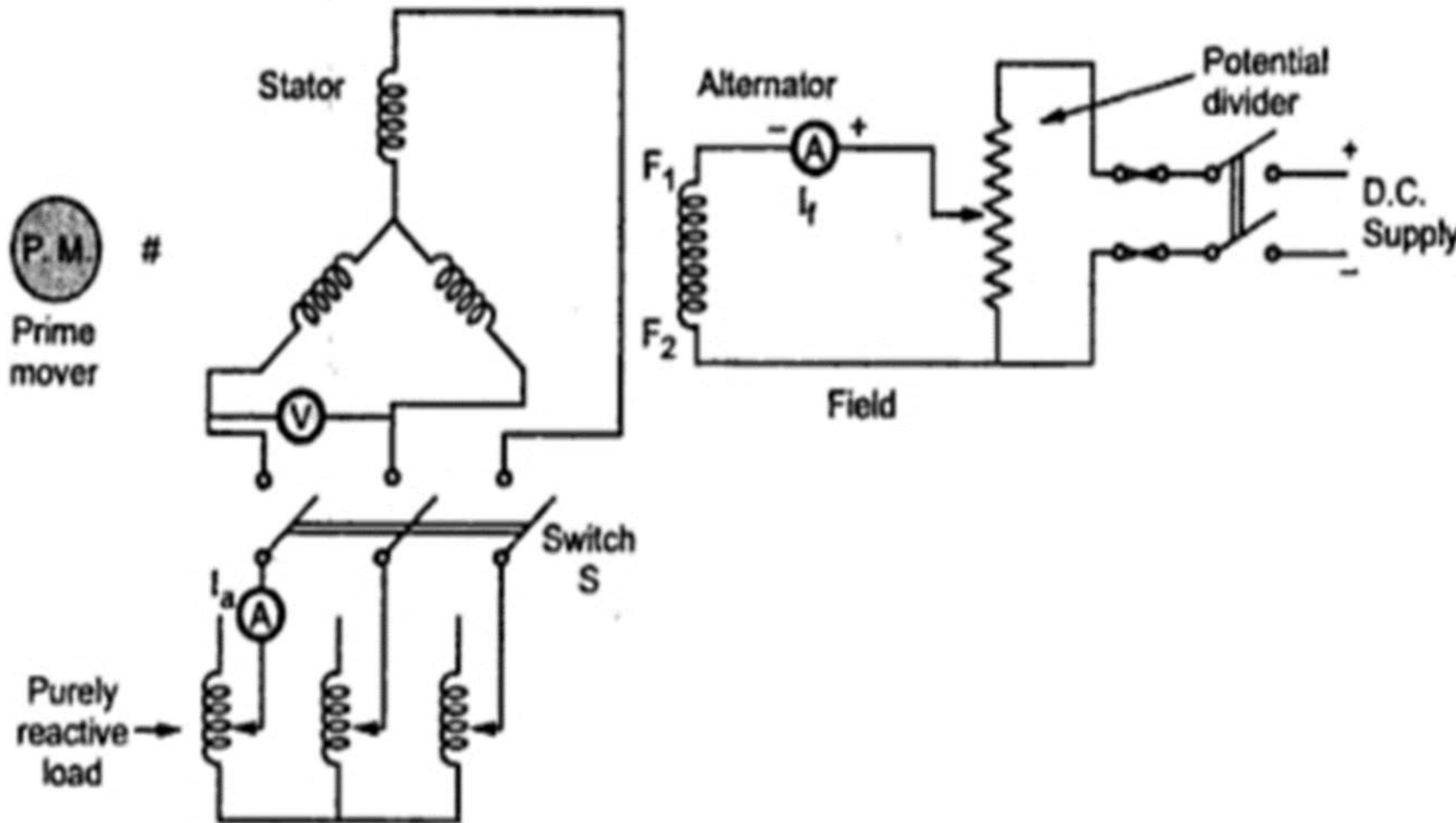


# Zero Power Factor Method (ZPF Method) or Potier method



To determine **armature leakage reactance (EMF)** and **armature reaction (MMF) separately**, two tests are performed on the alternator

1. Open circuit test
2. Zero power factor test



## Open circuit test

Switch Open

P.M. to drive  $N_s$

Potential Divider from 0 to Rated Value

## Zero power factor test

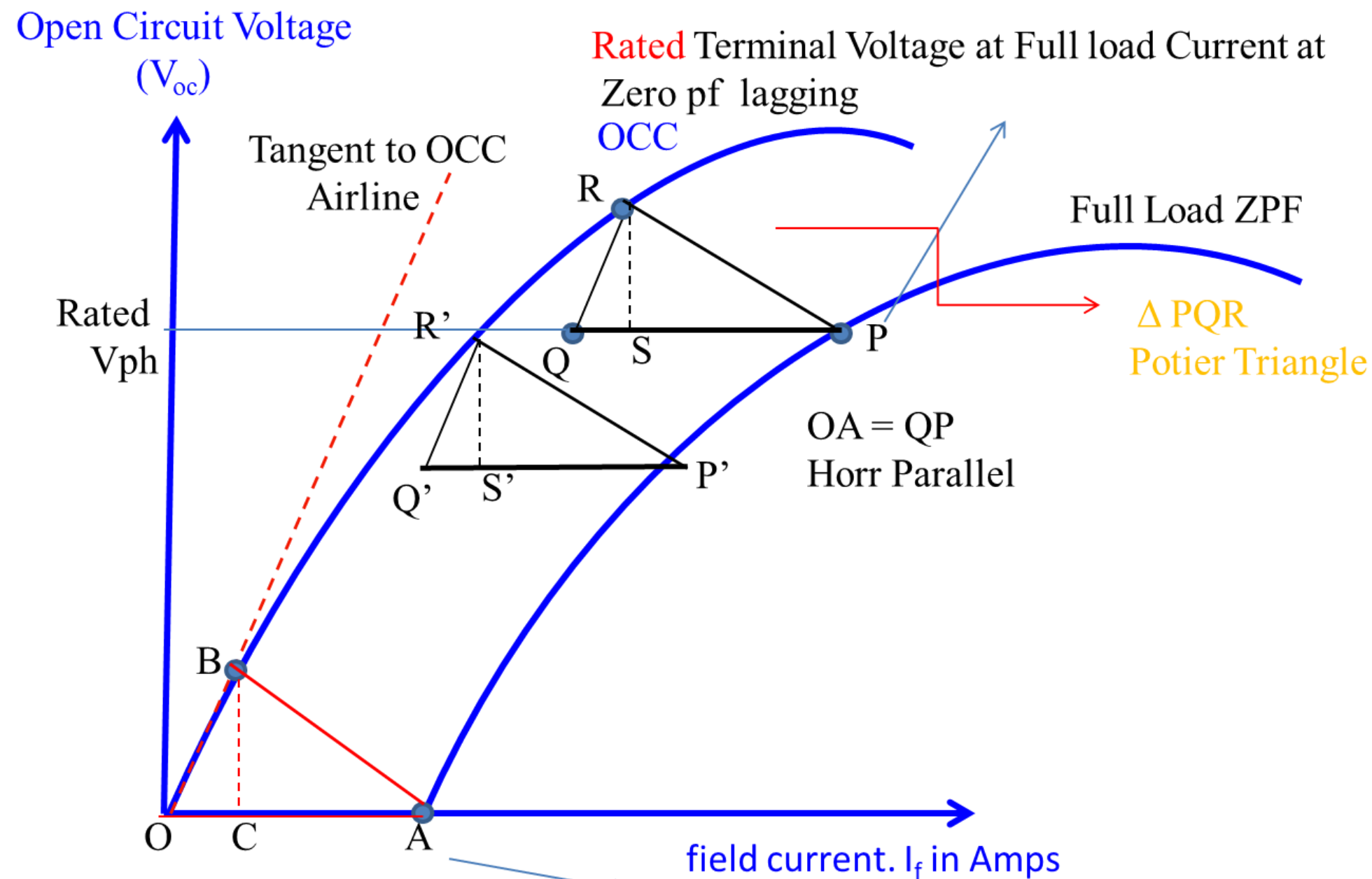
Switch Closed

Purely Inductive Load

Purely Inductive Load has  $\text{PF } \cos 90^\circ$



# Zero Power Factor Method (ZPF Method) or Potier method



RS Voltage Drop Armature Leakage Reactance ( $IX_L$ )

PS Gives  $I_f$  necessary to overcome Demagnetizing Armature Reaction

SQ rep  $I_f$  required to induce an EMF balancing of leakage reactance (RS)