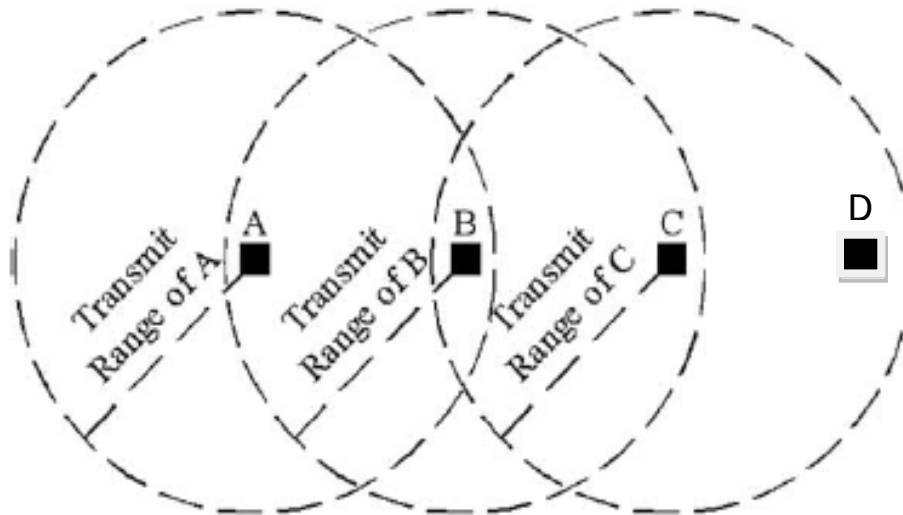


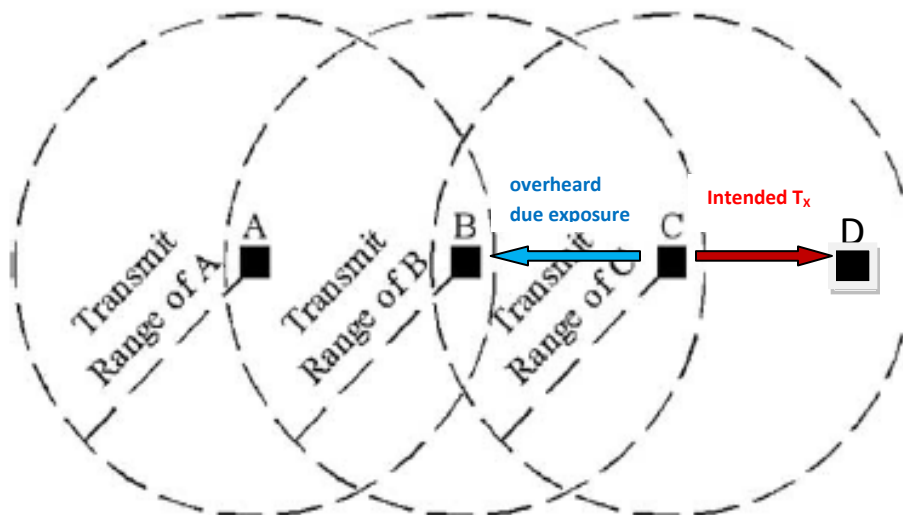
IEEE802.11 MAC Hidden/Exposed Stations Problems

Hidden Terminal Problem: (www.cs.virginia.edu/~cs851-2/course.htm)



- Node B can communicate with A and C both
- A and C cannot hear each other
- When A transmits to B, C cannot detect the transmission using the carrier sense mechanism
- If C transmits to D, collision will occur at B

Exposed Terminal Problem: (www.cs.virginia.edu/~cs851-2/course.htm)



- Node C can communicate with B and D both
- Node B can communicate with A and C
- Node A cannot hear C
- Node D cannot hear B
- When C transmits to D, B detects the transmission using the carrier sense mechanism and postpone **to transmit to A**, even though such transmission will not cause collision (**B can Tx while receiving**, but not receiving two or more at the same time). We say that B is **exposed** to C's traffic and stopped Tx, wasting Bandwidth.

Partial Solution: Virtual Carrier (VC)

Multiple Access Collision Avoidance MACA (1, 2, and 4 only)

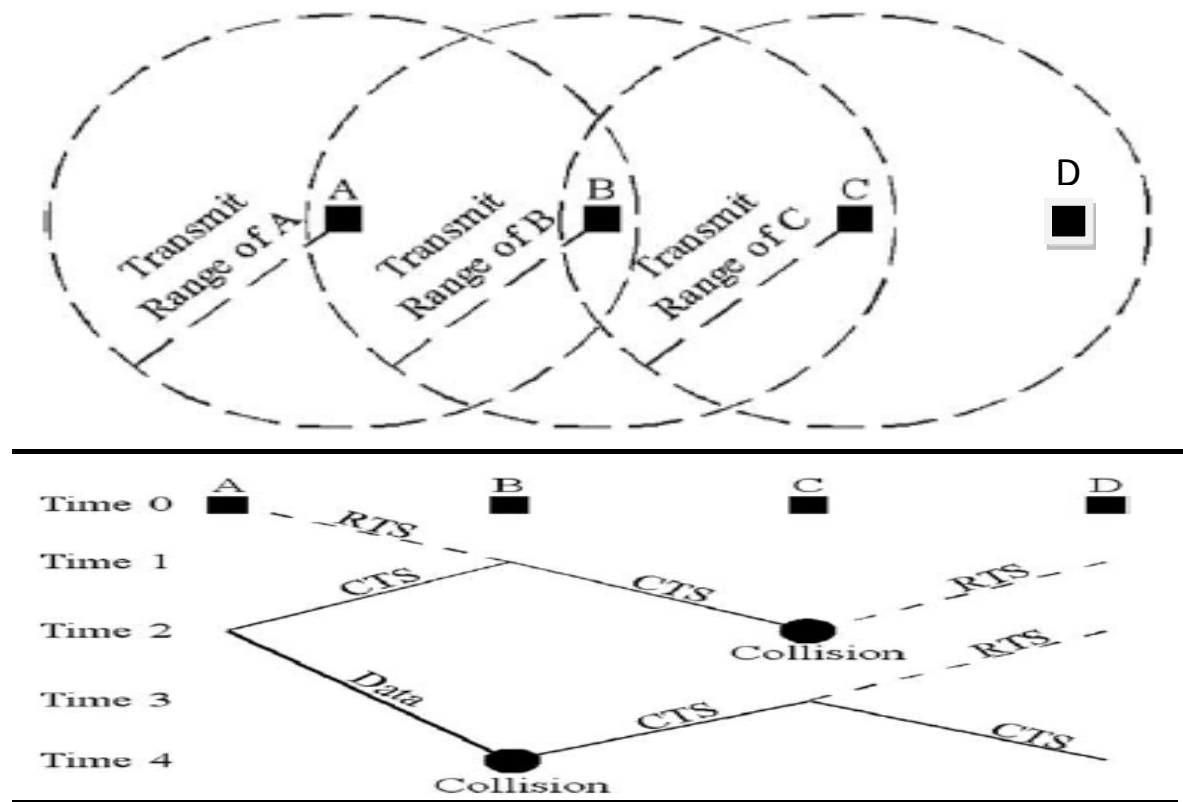
& MACA for Wireless (MACAW) (1-to-5)

Stations A&B communicate, via the following sequence of
handshaking VC steps:

1. “Request To Send” frame (**RTS**) from A to B. (All A’s neighboring stations are going to sleep for the session duration which is included in the RTS control frame)(Problem?!?! YES. WHY?!?!?) Assume node Y only with range of A, hears A's RTS to B, then blocks for the duration, which is unfair to Y in case of B never answers!
2. “Clear To Send” frame (**CTS**) from B to A. (All B’s neighboring stations are going to sleep for the session duration which is included in the CTS control frame)
3. “Data Sending” frame (**DS**) from A to B. (All neighboring stations are going efficiently to sleep for the session duration which is included in the control frame)[**NOT in MACA**]
4. **DATA** fragment frame from A to B, and (All detecting stations sleeps until ACK+ small random time)
5. Acknowledgement frame (**ACK**) from B to A. (all sleeping stations wakeup).

Now, when A transmits RTS to B, B will respond by CTS to A, which will be overheard by C. Hence, C will sleep on its own initialized NAV (CTS includes the time duration of the sleep), **NO collision scenario as before in CSMA above!!**
(Really?!)

The VC technique will solve the HS problem with special timing scenario, yet still, fails to handle the Hidden Station problem in general:



Hidden terminal problem after using RTS/CTS control packets

(paper.ijcsns.org/07_book/201010/20101020.pdf)

1. A wants to send **data** packet to B.
2. A sends **RTS** to B.
3. Upon receiving the **RTS**, B sends CTS to A, but C gets it too.
4. At the same time D sends **RTS** to C for transmitting data packet, which **collides** with B's **CTS** at C.
5. After receiving **CTS** from B, A transmits data to B and D times out and resends **RTS** to C.
6. When C gets the resubmitted D's **RTS** (no collision this time), C sends **CTS** to D, but B gets it anyway (wireless broadcast medium) while still receiving **data** from A, hence **collision** at B!!!

Does MACA fail also to handle the **Exposed Station problem**????!!! (left for you to research!!)

Hence IEEE802.11 MAC defines two modes:

1. DCF (Distributed Coordination Function) & PCF (Point Coordination Function)

2. DCF is based on CSMA + MACAW + NAV

✚ 4 steps handshaking (Virtual CS): RTS-CTS-DATA-ACK

✚ Physical CS + Virtual CS via the NAV (network allocation vector) containing time value that all overhearing station will await on (as obtained next) until medium is free again.

✚ Every of the above handshaking control packets contains the time duration *remaining* in the communication session.

✚ NAV is continuously updated via any new *overhearing*.

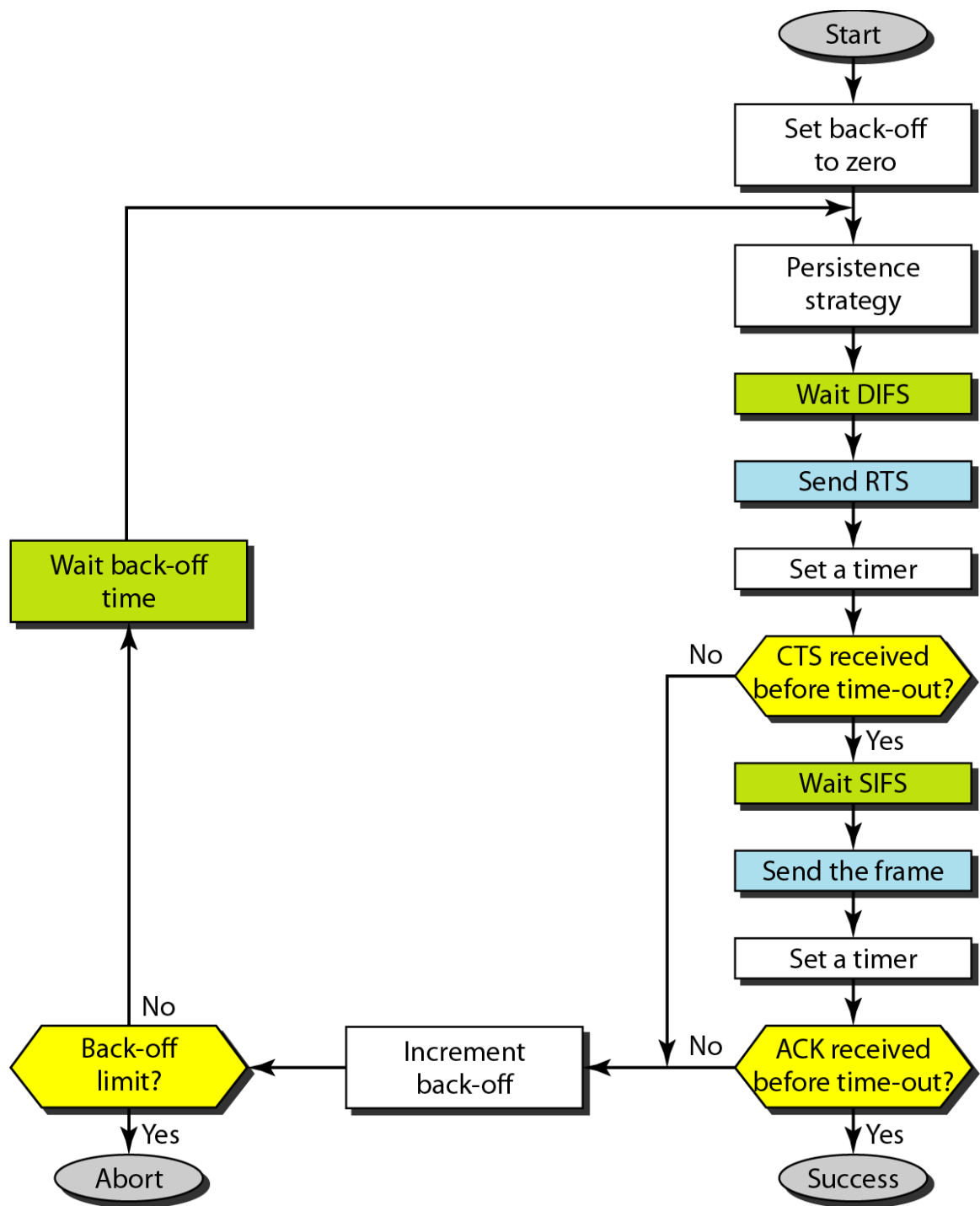
➤ IFS (inter frame spacing)

– Short IFS (SIFS), PCF IFS (PIFS), DCF IFS (DIFS), Extended IFS (EIFS)

The IEEE802.11 MAC' DCF combines a mix of features from the following: CSMA & MACAW (-DS) + NAV (Network Allocation Vector).

The NAV counter is established by other noninvolved stations (neighbors of A&B) to await on! (for VC Virtual Sensing).

The NAV initial value depends on when a station gets into the action, i.e., overhearing: RTS, CTS, DATA, ACK.



IEEE802.11 MAC (DCF) [ad-hoc]Protocol

It is a mix of CSMA & MACAW (-DS) with NAV (virtual sensing [VC](#)).