



SNS COLLEGE OF TECHNOLOGY

Coimbatore-35
An Autonomous Institution

Accredited by NBA – AICTE and Accredited by NAAC – UGC with 'A+' Grade
Approved by AICTE, New Delhi & Affiliated to Anna University, Chennai



DEPARTMENT OF INFORMATION TECHNOLOGY

16IT AUGMENTED REALITY AND VIRTUAL REALITY

III YEAR – V SEM

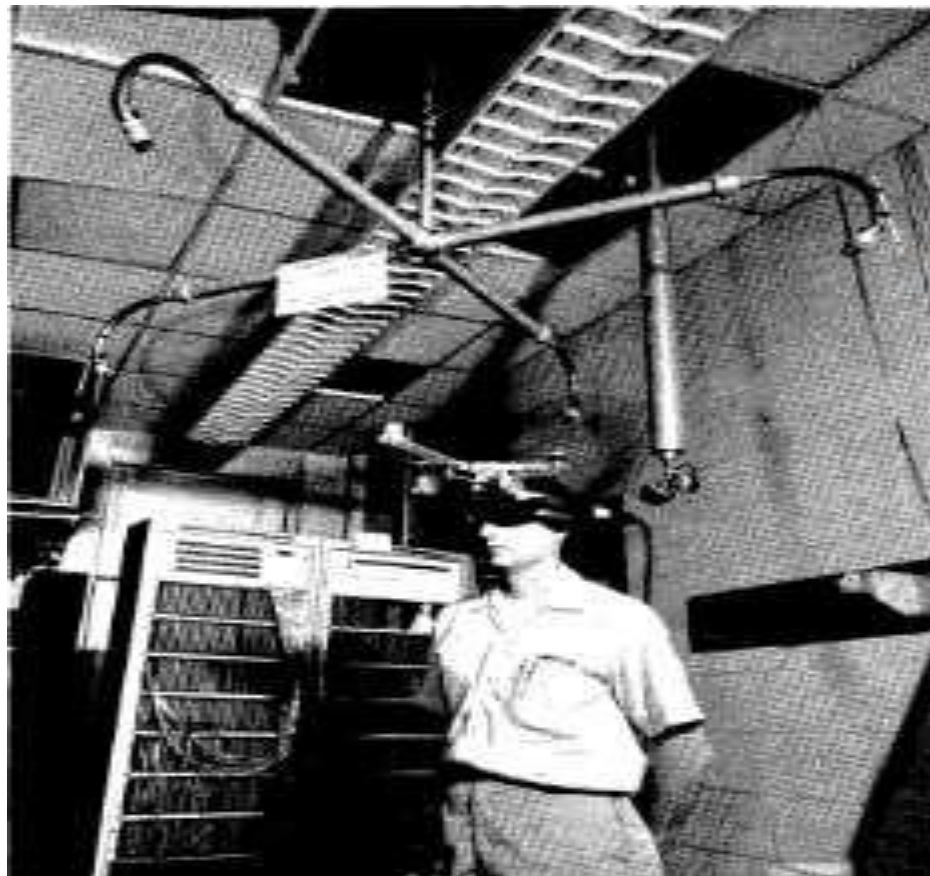
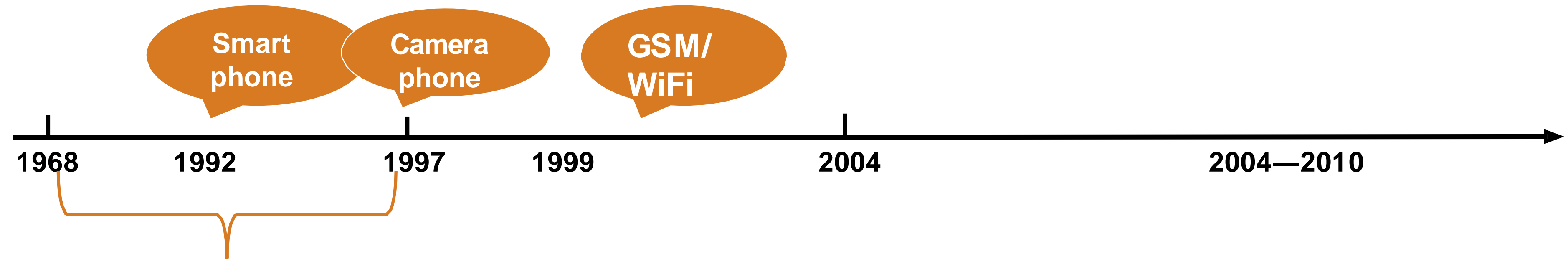
UNIT 2 – INTERACTION AND MOBILE AUGMENTED REALITY

TOPIC 2 – Mobile Augmented Reality Systems



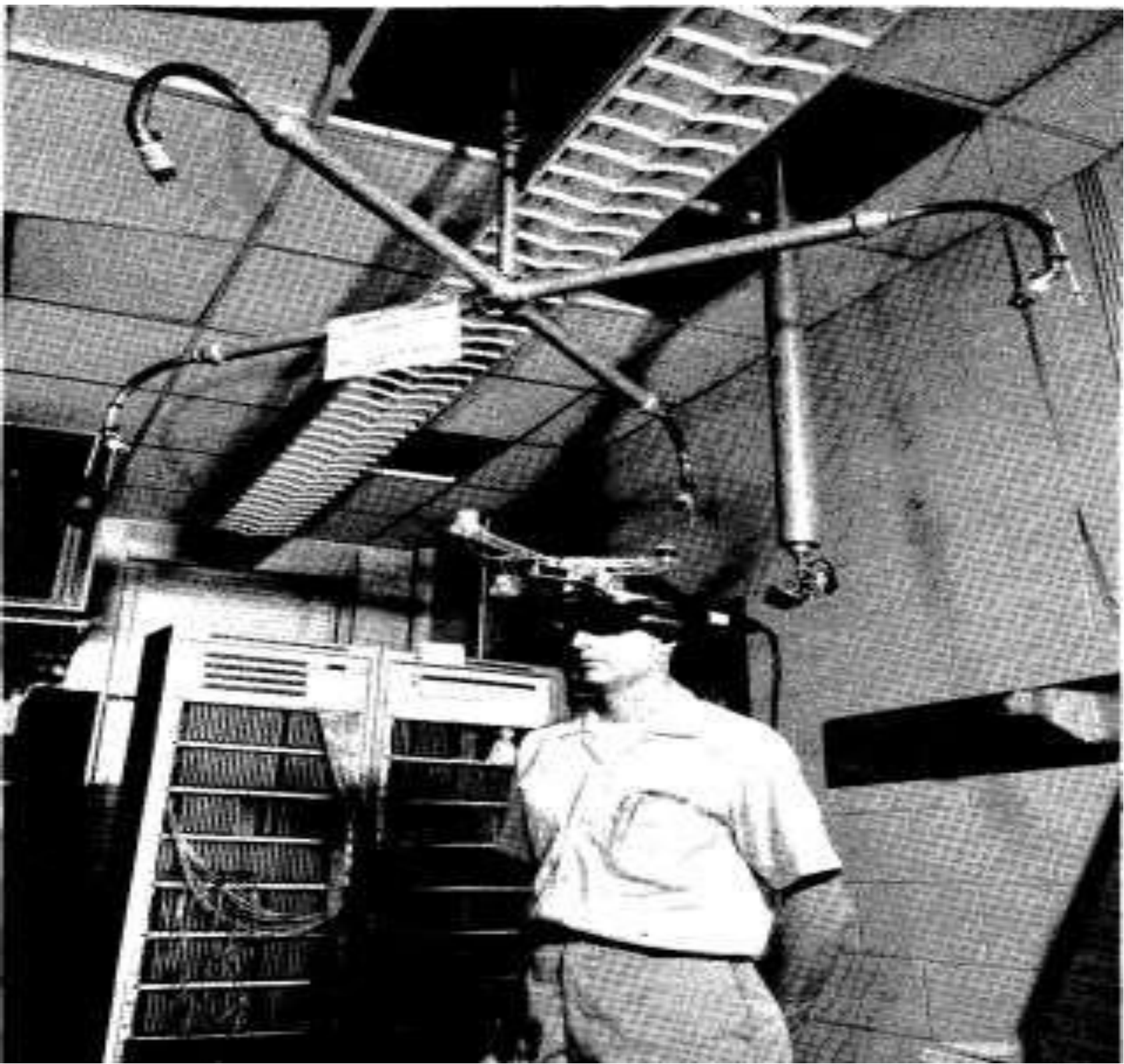


History of Mobile AR





1st AR System

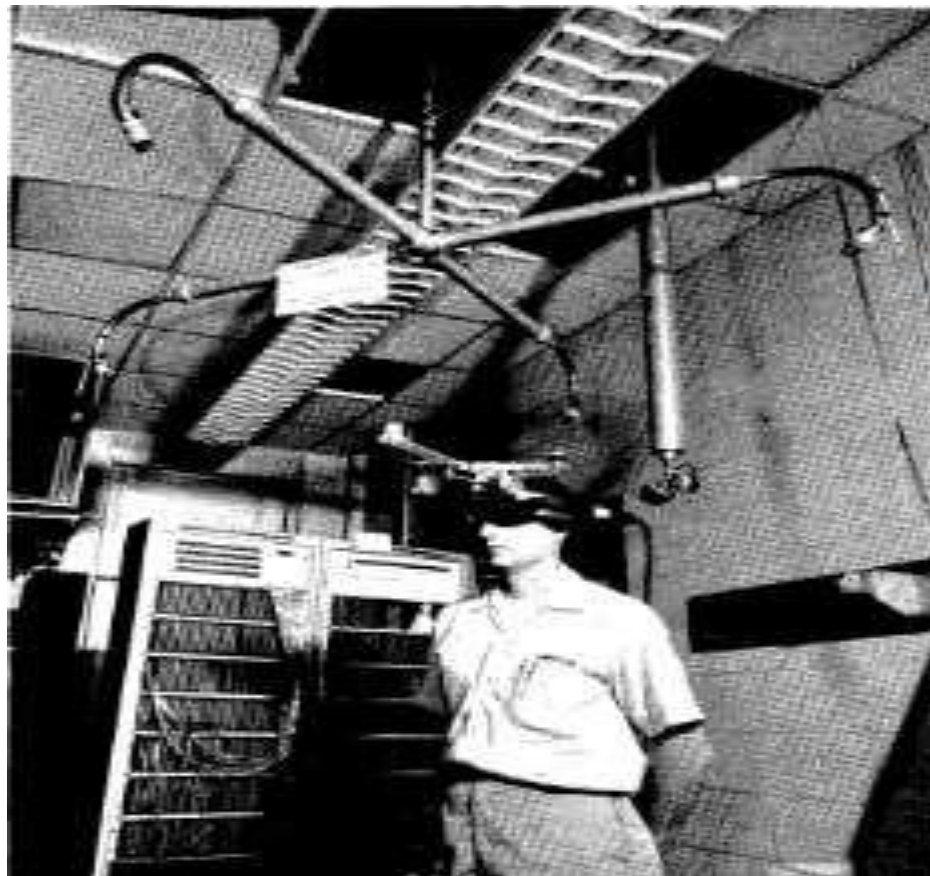
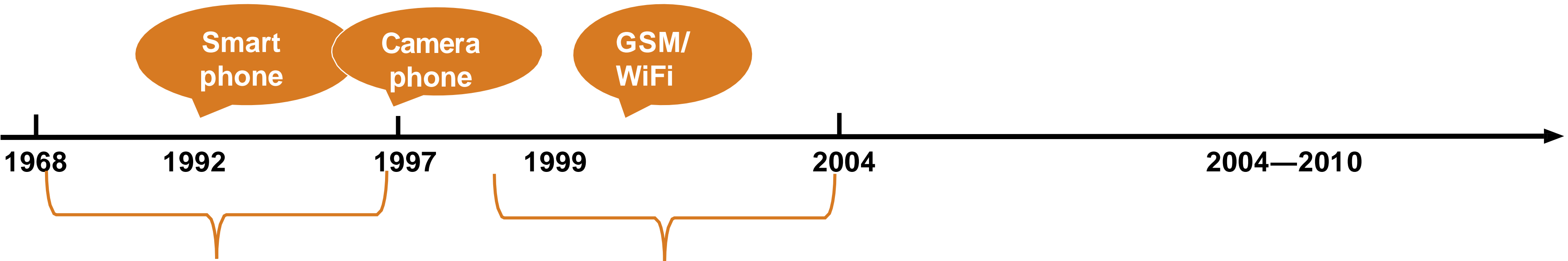


- **Optical see-through HMD**
- **Two different 6 DOF trackers**

(1968)



History of Mobile AR





1st Mobile AR System



- **1st Mobile AR System**
 - **See-through head-worn display with integral orientation tracker**
 - **Backpack holding computer & hand-held computer**
- (1997)**





Multi-User AR



- **A mobile, multi-user AR system**
- **Collaborate in augmented shared space (2001)**

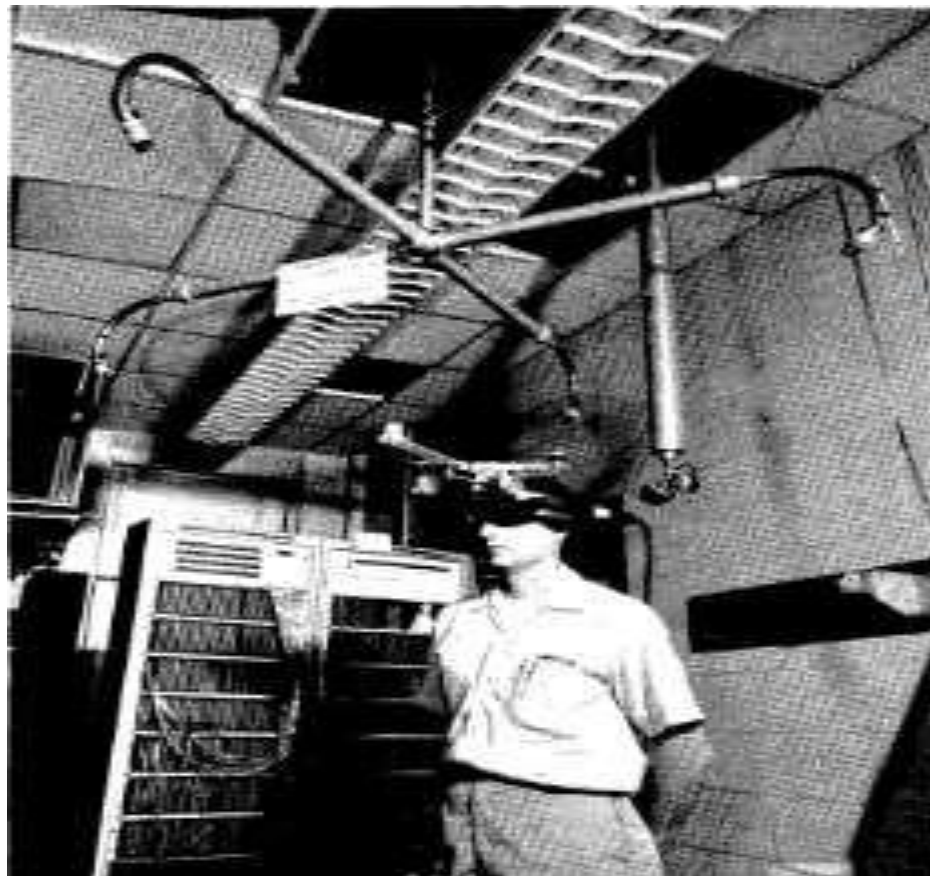
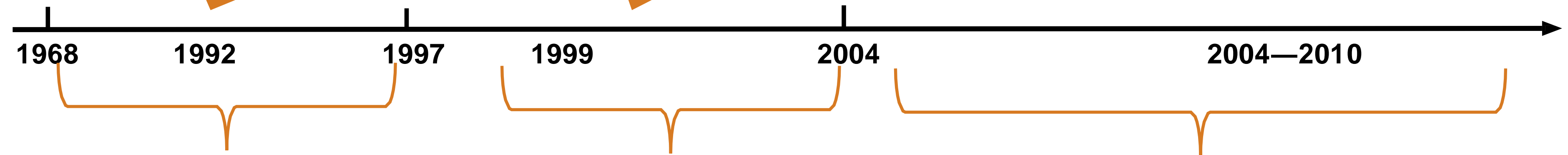


History of Mobile AR

Smart
phone

Camera
phone

GSM/
WiFi





Mobile Phone AR



- **A system for tracking 3D markers on a mobile phone**
- **1st Video see-through AR system on consumer cell phones (2004)**



PDA AR

- **1st multi-user AR application for PDAs**
- **video see-through**

(2004)





Better Graphics...Better AR!

ARhrrrr!

- A mobile AR game with high quality content

(2009)





Markerless Mobile AR - PTAM

- **PTAM system running in real-time on an iPhone**

(2009)

Parallel Tracking and Mapping (PTAM)
running on an iPhone 3G - early results

June 2009
Georg Klein, David Murray
Active Vision Lab, Oxford



Challenges & Issues

Photorealistic Rendering Of Virtual Objects



<https://www.youtube.com/watch?v=odKePqcfDDE>



Challenges & Issues

User-Perspective Rendering (Phone/Tablet as Transparent Glass)



<https://www.youtube.com/watch?v=C9UgJmmE7xk>



Challenges & Issues

Occlusion Handling (Depth Camera, Real Time)





Combines Real World & Virtual Objects



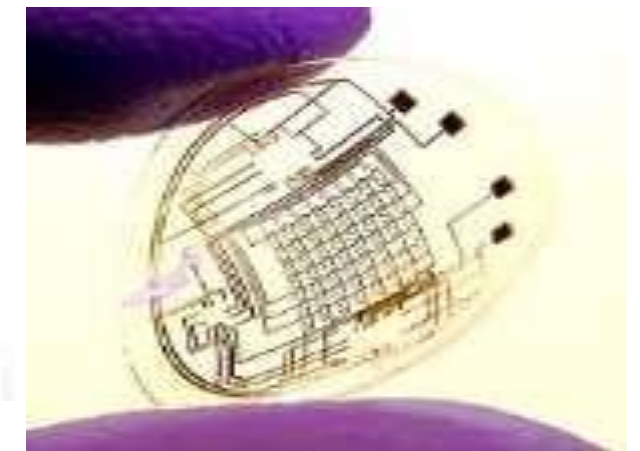
Allows Real-Time Interaction



3D Registration using Tracking



Display Technology



Currently:

- **Handheld**
- **lightweight head-mounted**

Future:

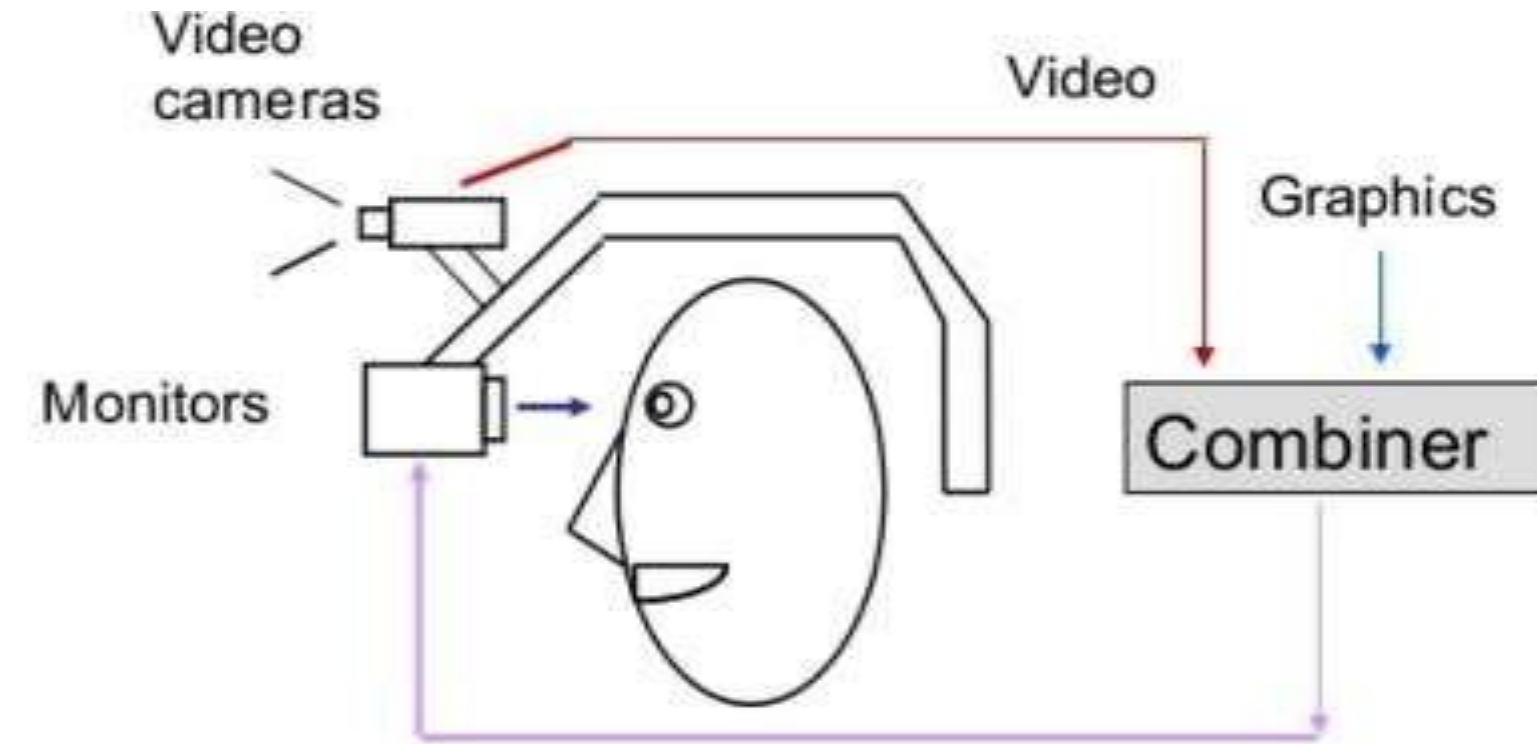
- **Projected AR**
- **Virtual Retinal Displays**
- **Contact Lens**





Video-See Through HMD

- Camera Captures Real scene
- Digital content is added
- Better registration
- Wide FOV (depends on cameras)





Handheld Displays



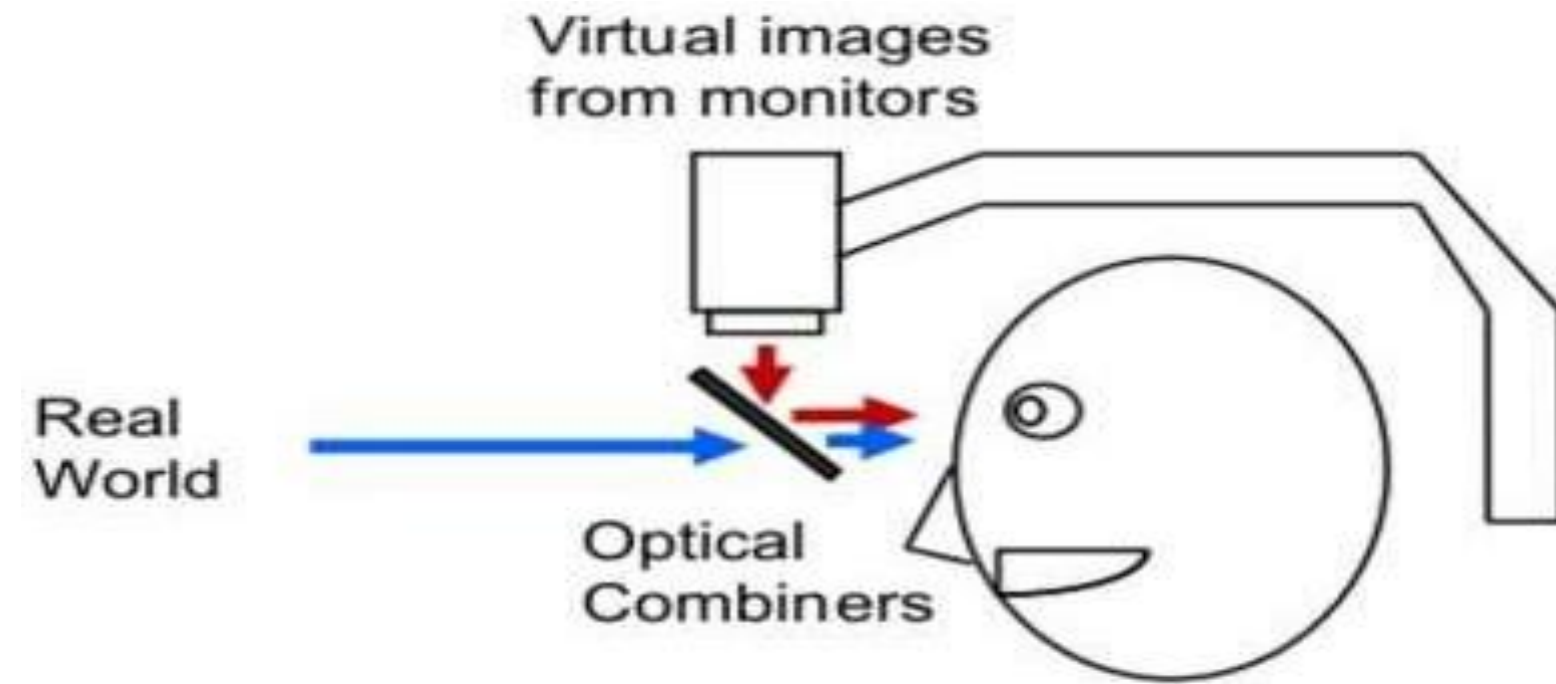


Optical See-Through HMD

User sees directly through display

- Direct view of the world
- Full resolution, no time delay

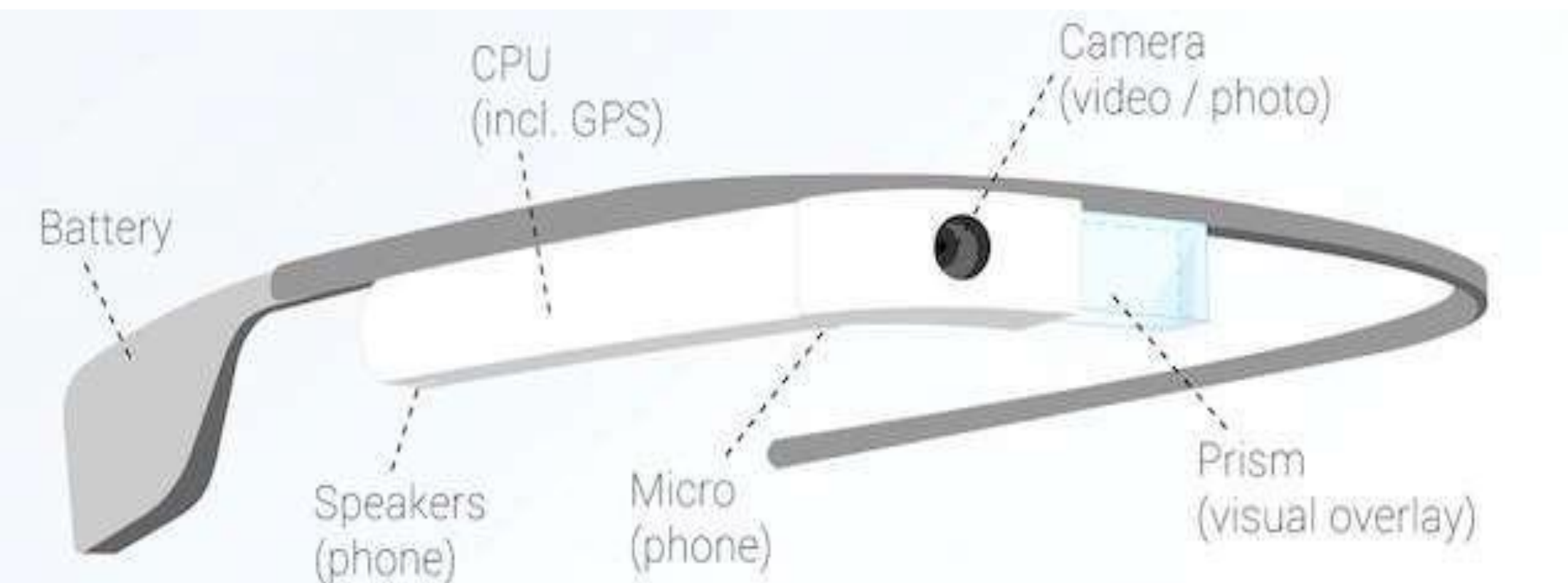
- Safer
- Lower distortion
- No eye displacement





See-Through Multiplexed Display

- Above or below line of sight
- Unobstructed view of real world





Projected AR

Stereo Head-Mounted Projectors

Rollable retro-reflective Sheet



Wide FOV

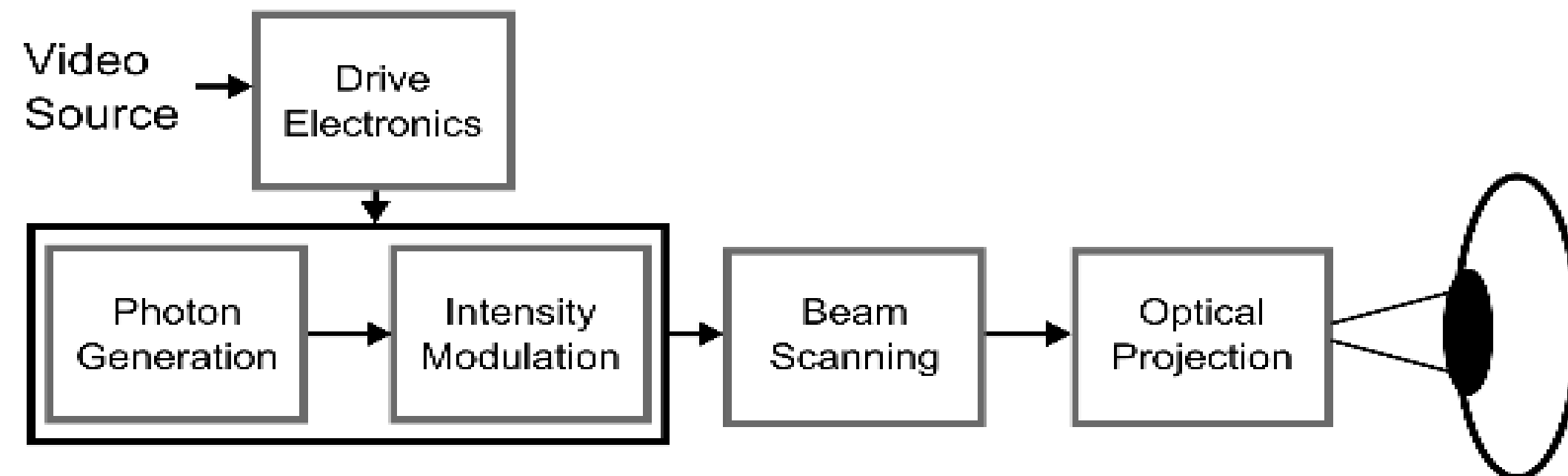
Shared Interaction



Virtual Retinal Displays

Everything we see is reflected light!

- Projects light directly into eyes
- Smaller size (no intermediate screen present)
- Highly portable
- Less power



**We can see virtual objects
registered in space...**



...but how can we interact with them?



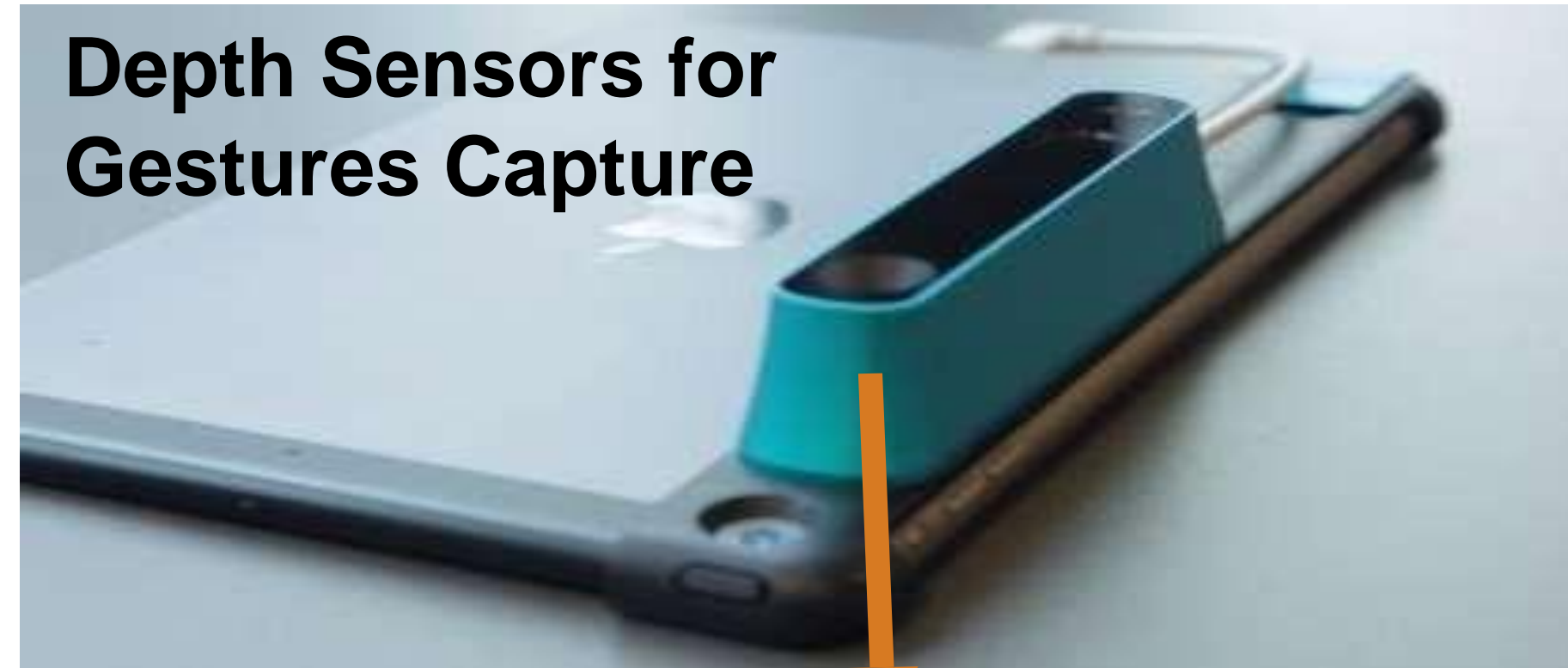
Touch Gestures





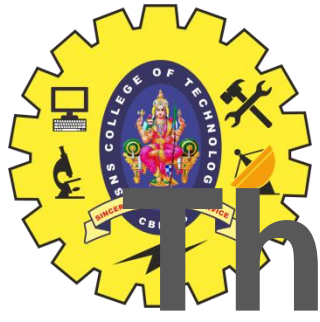
Natural Gestures

Tracking the user's hand(s) can provide a 6DOF interaction technique.

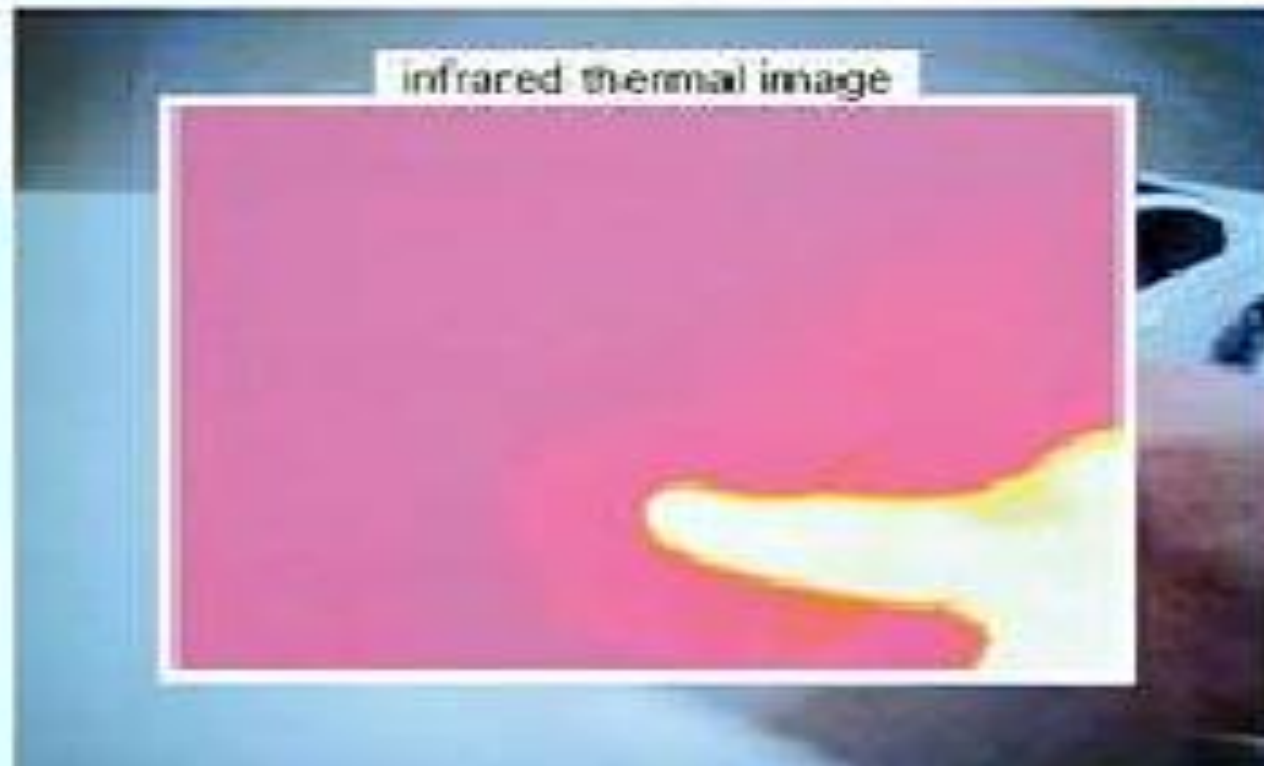


Depth Sensors for Gestures Capture





Thermal Touch

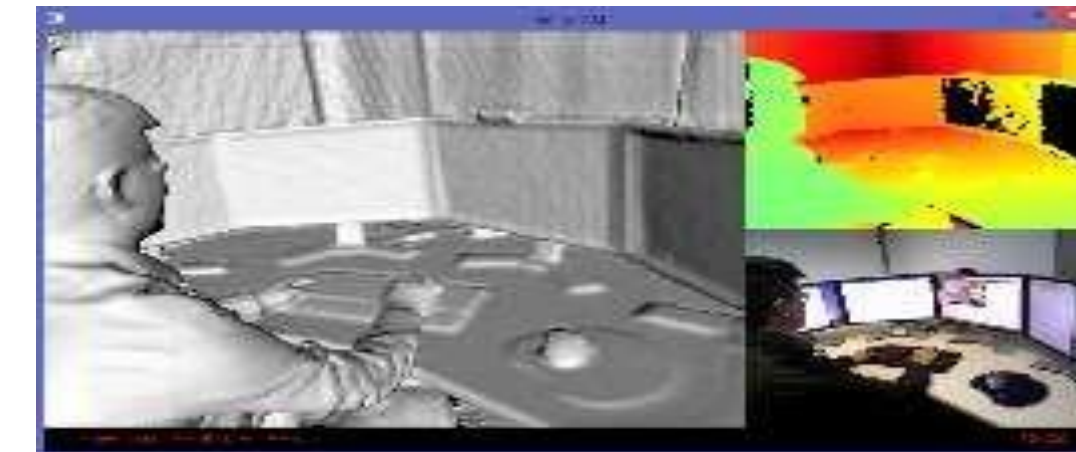
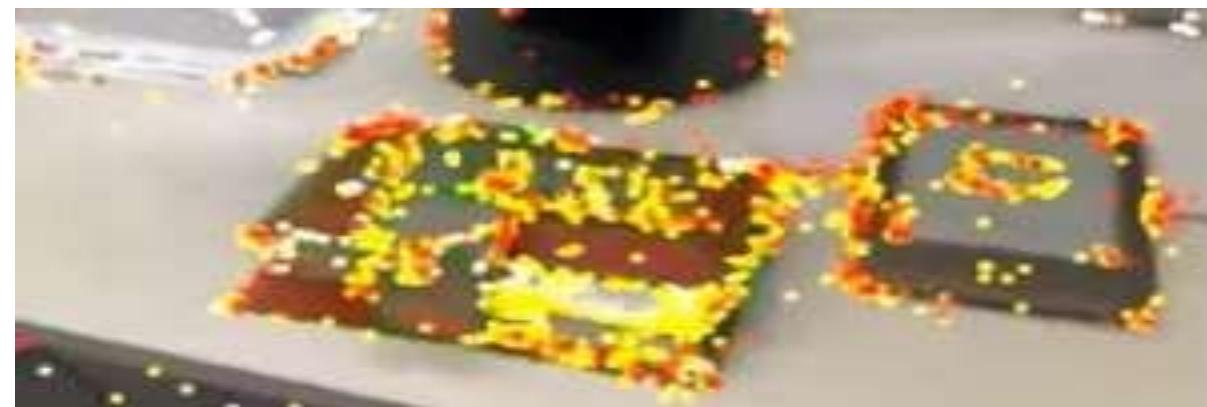


Thermal Touch: Thermography-Enabled Everywhere Touch Interfaces for Mobile Augmented Reality Applications Kurz, ISMAR 2014



Tracking

Recover position and orientation of viewpoint at each frame.



Past:

- Location Based (GPS)
- Marker based
- Magnetic, etc.

Currently:

- Image based
- Hybrid Tracking

Future:

- Model-based
- Environmental





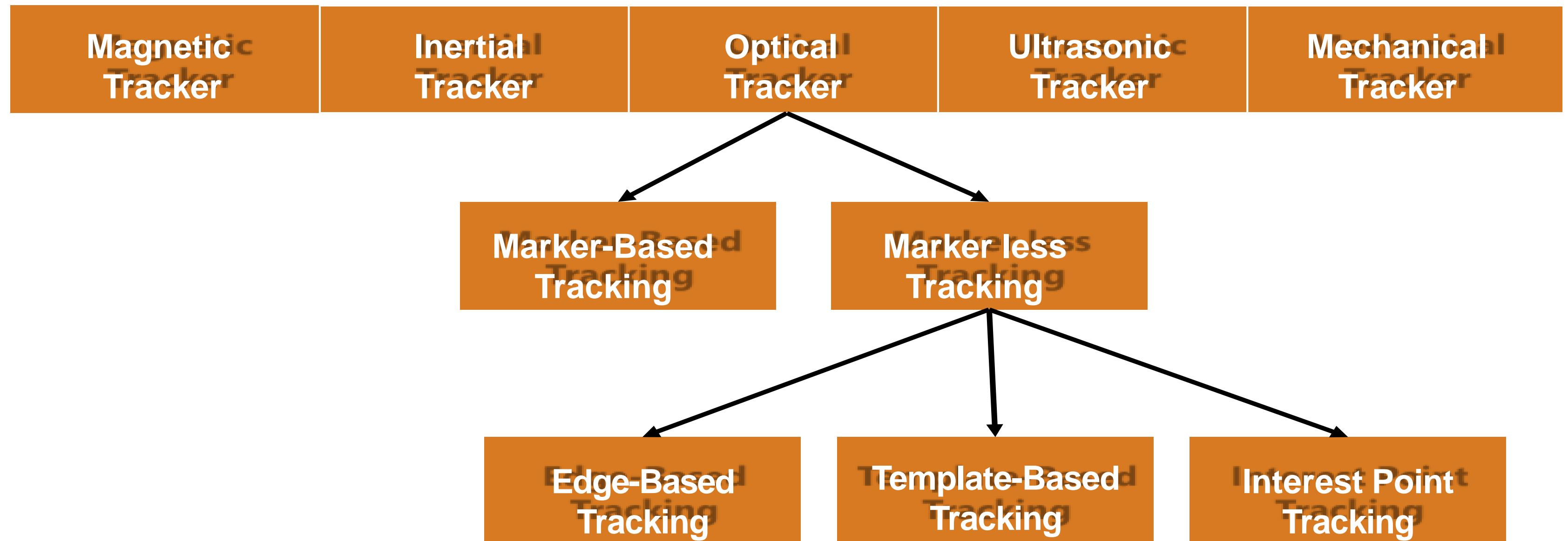
Optimal Tracking System

An ideal tracking system should have:

- perfect instantaneous 6 DOF measurements of the sensor pose in any environment and under any motion.**
- Robustness against observation from different viewing angles.**
- Robustness w.r.t changing lighting condition.**
- Low cost, be fast and reliable**

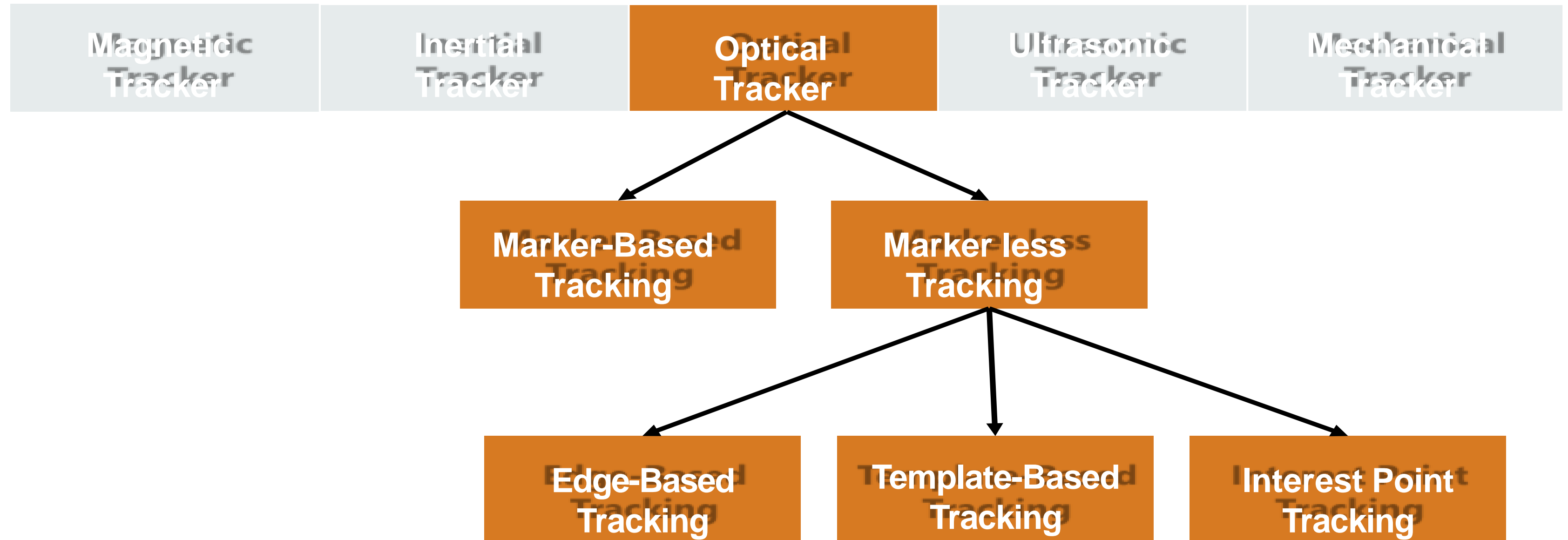


Tracking Types



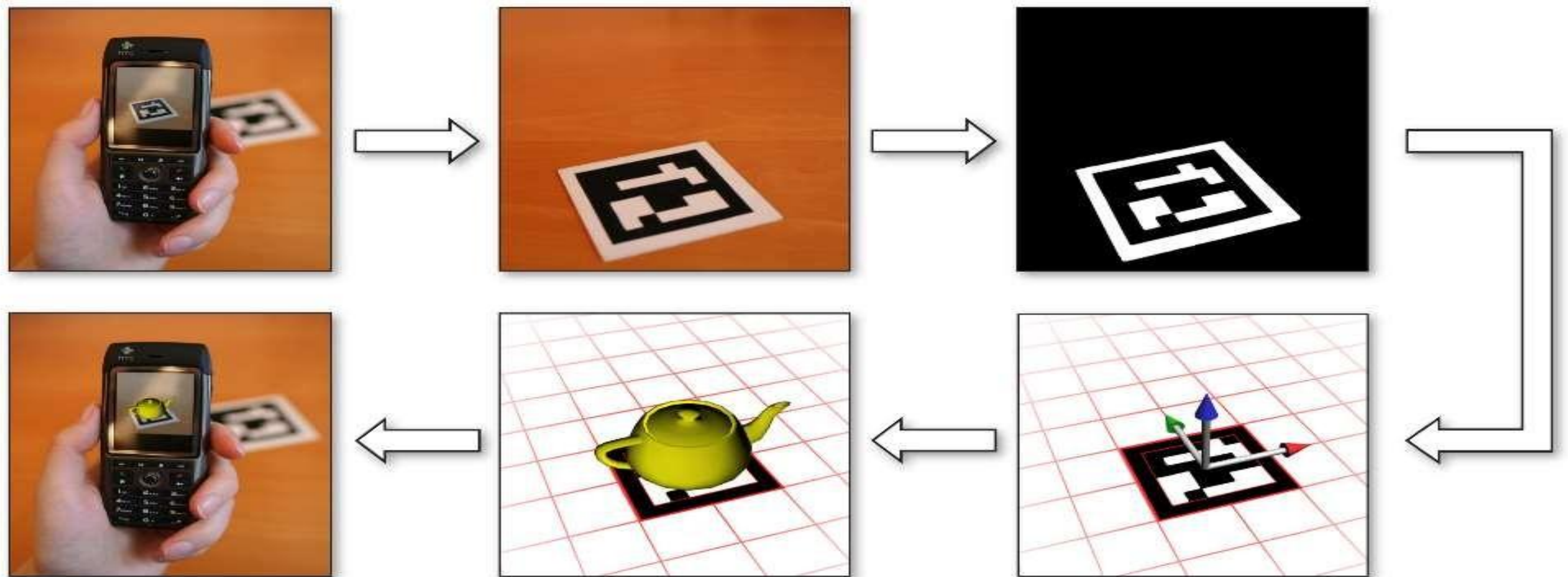


Tracking Types





Marker Tracking





Markerless Tracking

- **3D tracking techniques that tracks natural features.**
- **It extracts features from the surrounding environment (i.e. corners, edges, textures).**
- **Markerless AR system use natural features instead of fiducial markers in order to perform tracking.**

Main techniques used are:

- **Template based tracking.**
- **Edge based tracking.**
- **Tracking by object detection.**



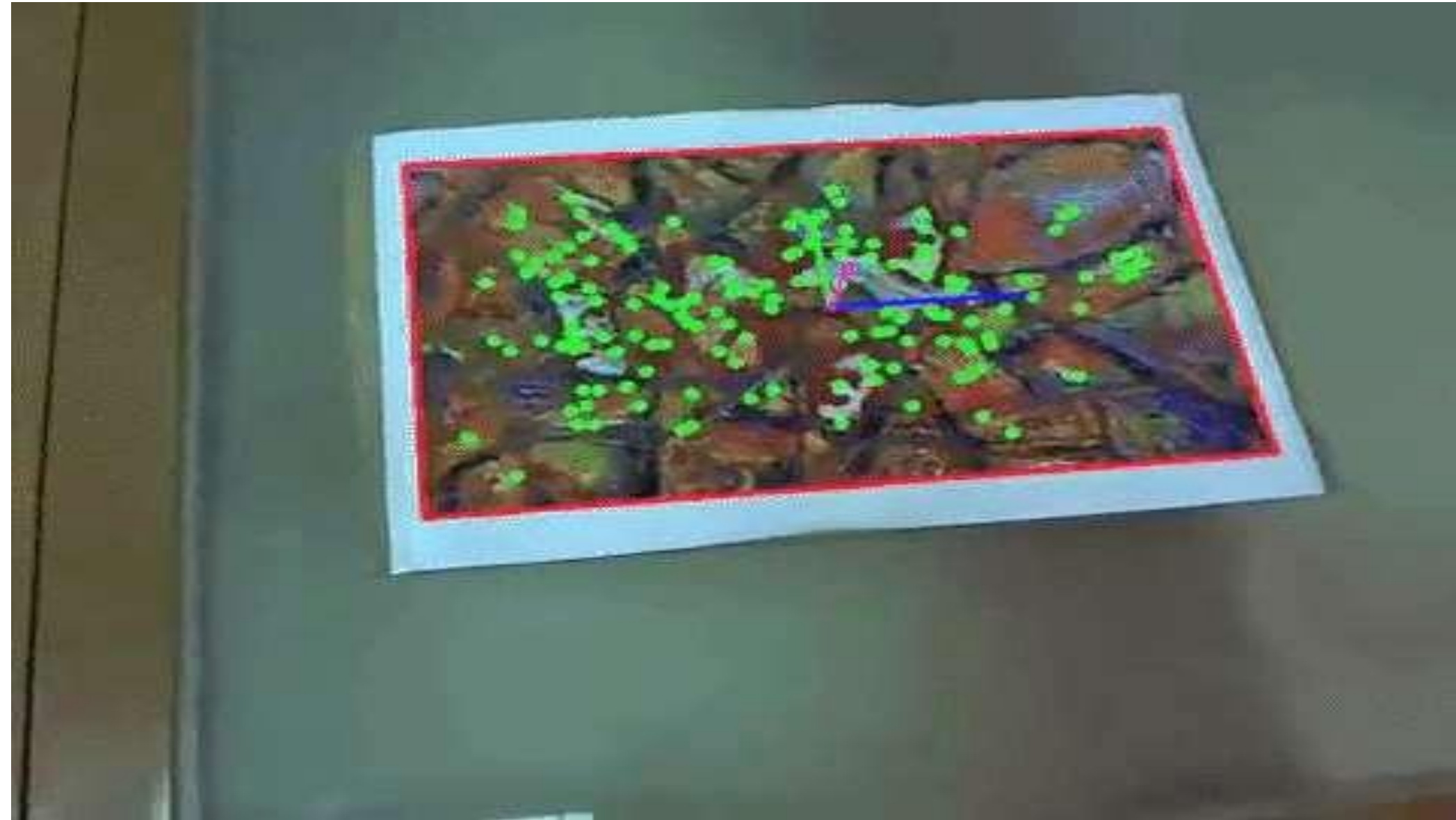
Template-based Tracking

- Also called **Texture Tracking.**
- Looks for features in images.



With enough features it can be highly accurate.

- **Sensible to fast camera movements.**
- **Sensible to light changes.**
- **Sensible to occlusion.**

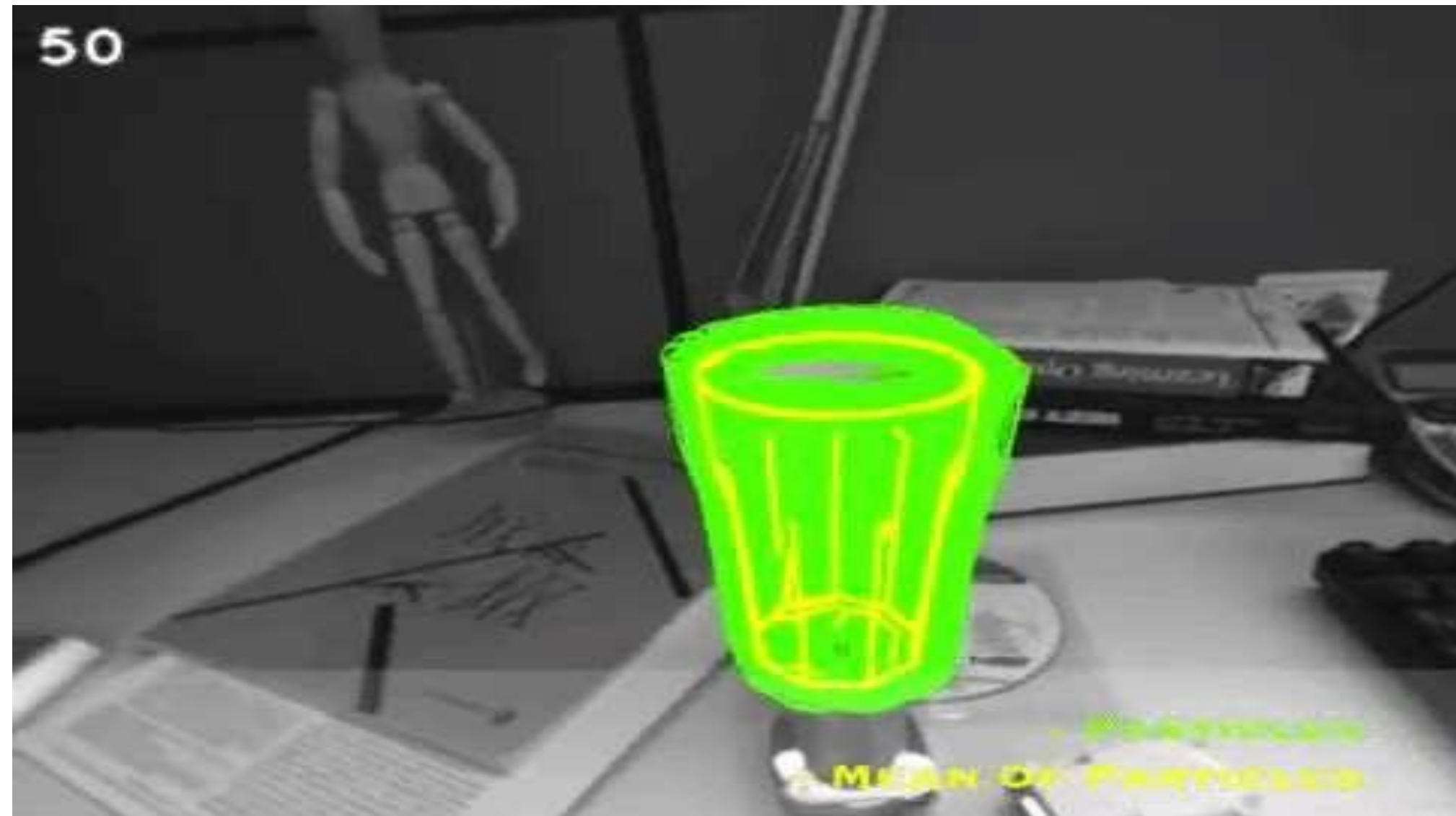


Multi-Texture Tracking AR



Edge-based Tracking

- **It requires depth cameras.**
- **Sensible to fast camera movements.**
- **Cluttered background.**
- **Tracking accuracy is jitter.**

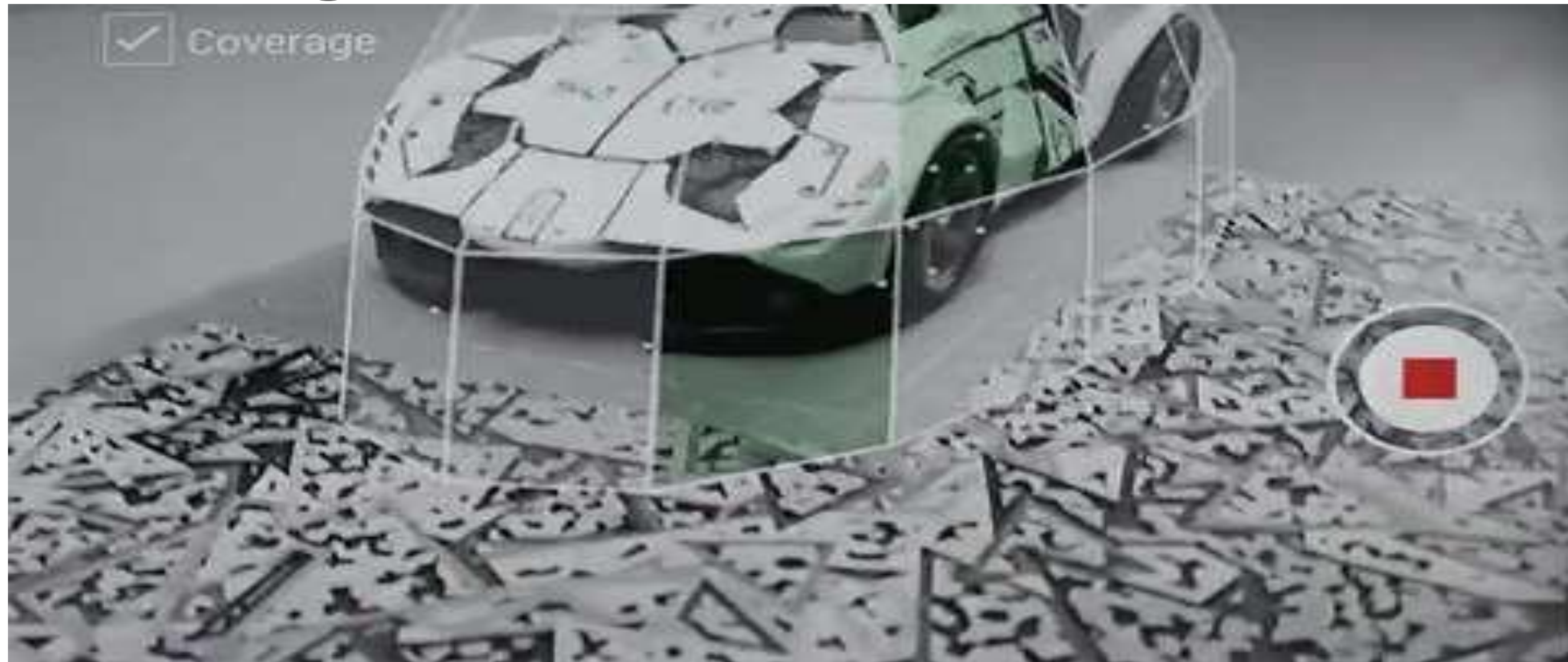


3D Texture less Tracking - AR



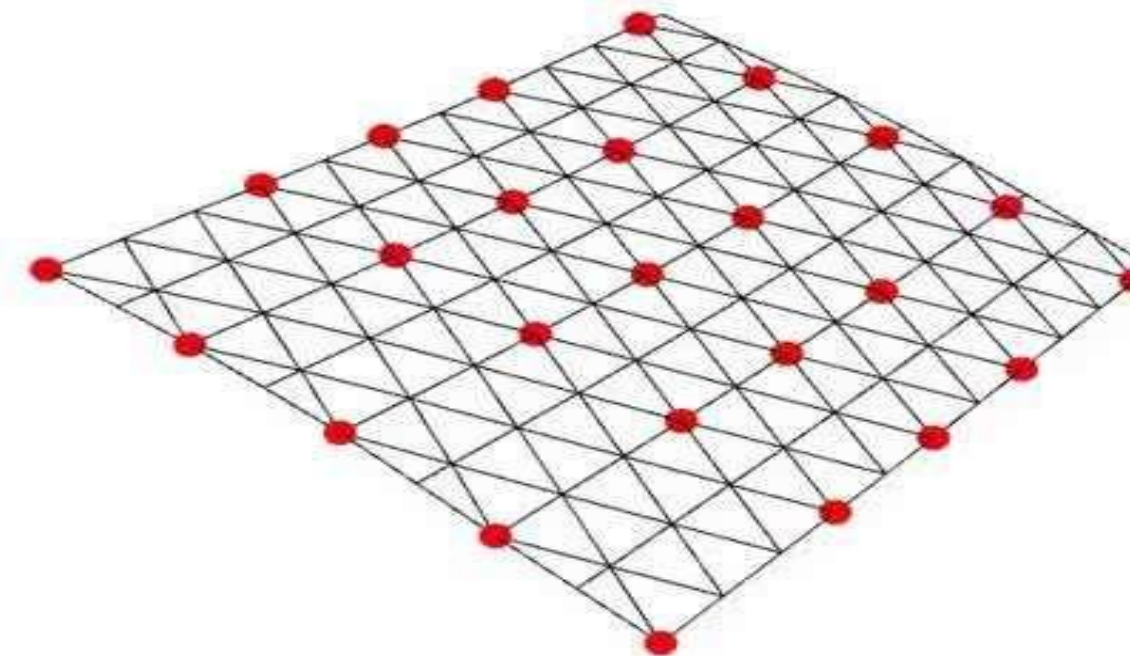
Object-based Tracking

- **Tracking might be restricted to limited range of poses.**
- **Stable tracking under fast motion.**





Track from Deformable Objects





Parallel Tracking & (Multiple) Mapping (PTAM – PTAMM)

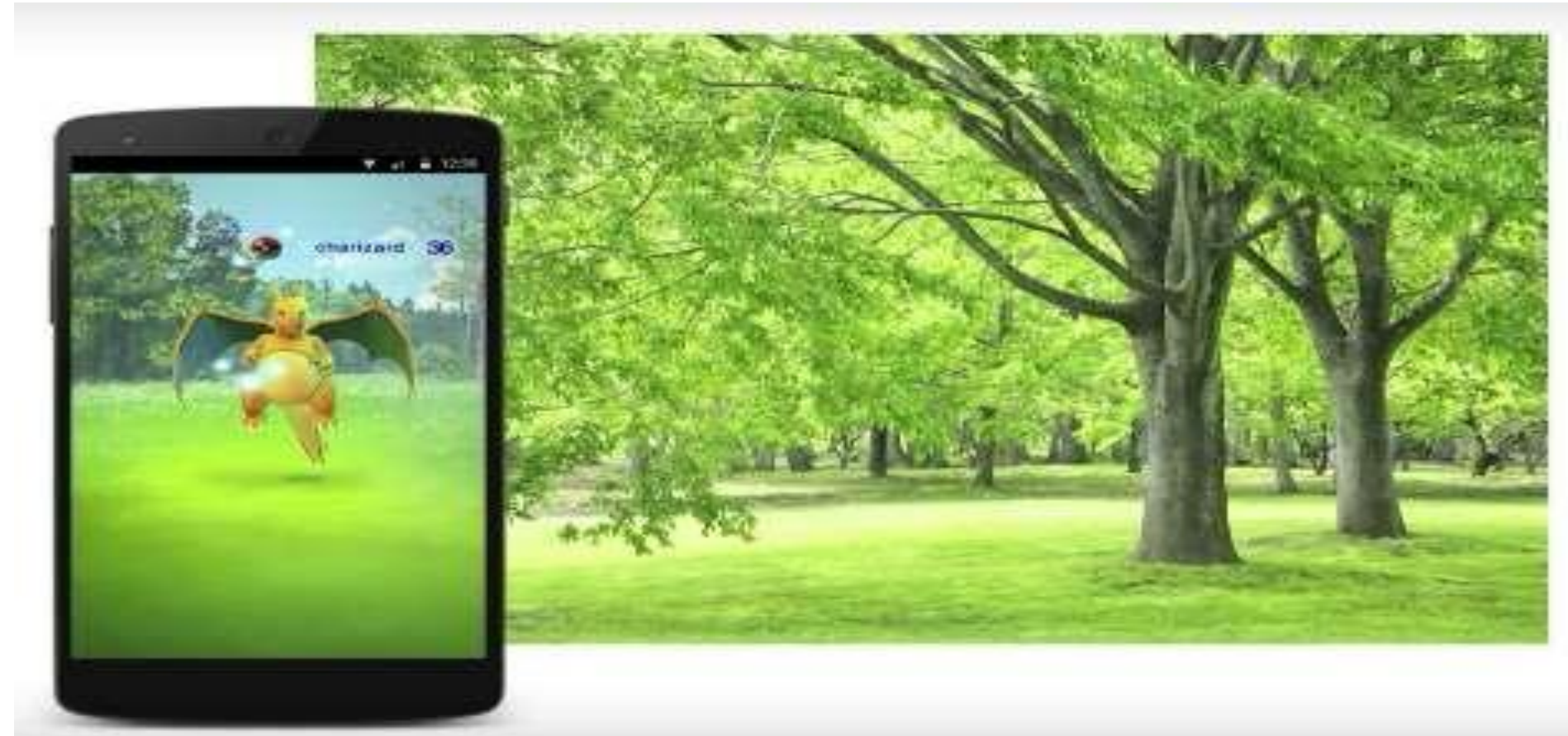
- **Estimating camera pose in an unknown scene.**
- **Tracking and Mapping are 2 separate tasks.**
- **Produces detailed maps which can be tracked at frame-rate.**



Parallel Tracking and Mapping (PTAM - PTAMM)



Current Products





EPSON Moverio



EPSON
MOVERIO



BT-100



BT-200

EPSON

- **Binocular see through display**
- **Camera, gyroscope, GPS, accelerometer, and microphone.**
- **£519.99**
- **Optical See-Through**

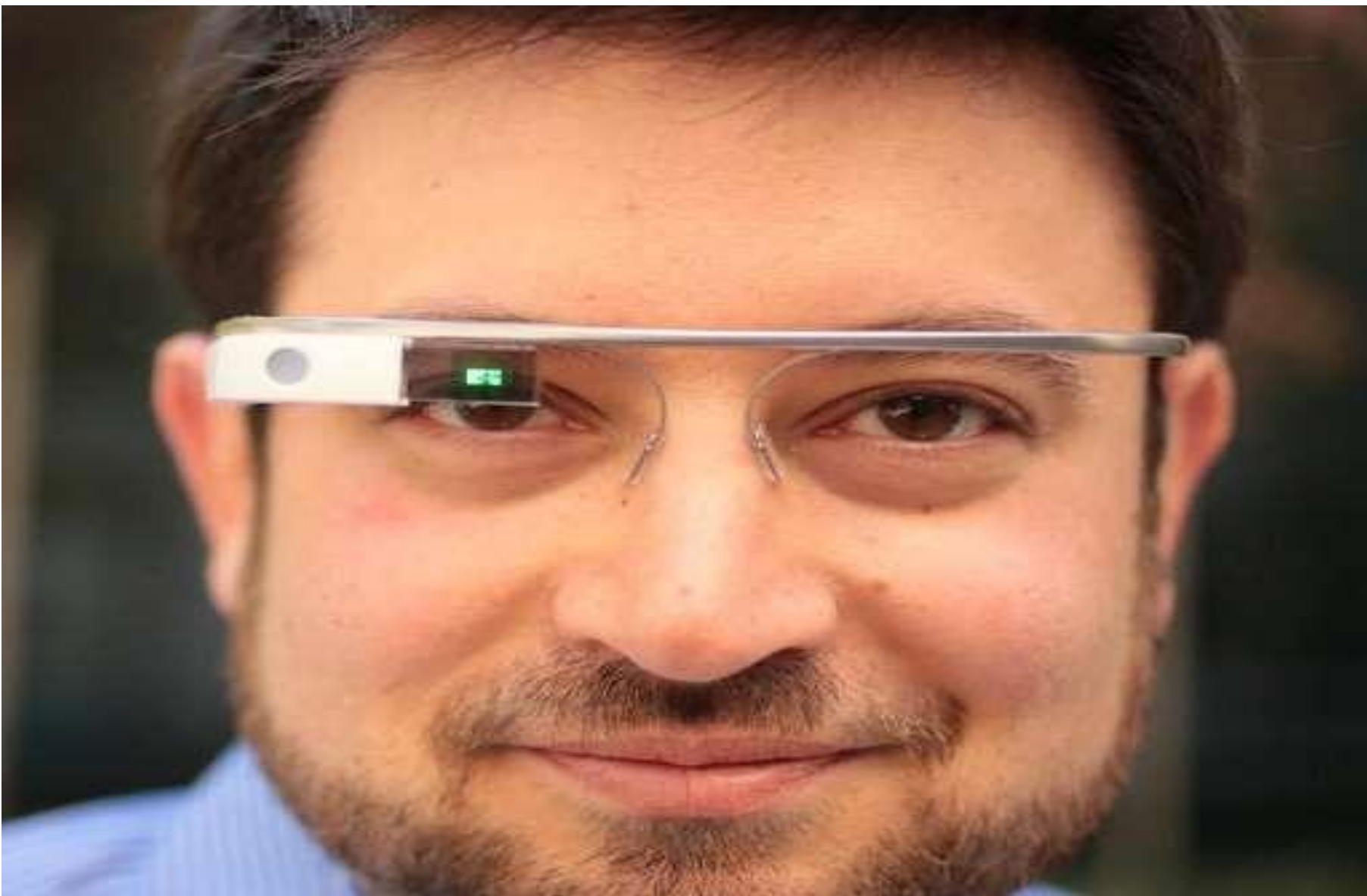


- **Projected AR**
- **\$400**
- **Q1 2016**





Google Glass



- **Touchpad**
- **Camera – record 720p video**
- **Single screen**
- **\$1,500**
- **Version 2 ~ 2016**
- **Optical see through**



Meta Spaceglasses+Meta Pro



- **3D See-through Display**
- **3D depth Camera-320x240 + RGB Camera-1280x720**
- **Head tracking**
- **23-35° FOV**
- **9-axis accelerometer**
- **\$667, \$3000**

- **40° FOV**
- **Comes with sidekick PC with a 1.5GHz Core i5 processor, 4GB of RAM, and a 128GB SSD**



Microsoft Hololens

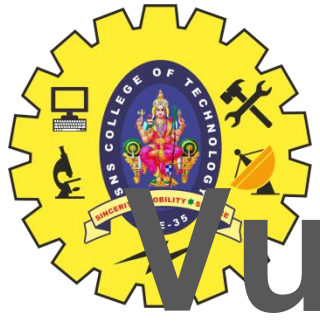




Microsoft Hololens



- **Expected 1st quarter 2016**
- **3 Processors - CPU, GPU, HPU**
- **\$3,000**



Vuzix AR Glasses



- **Several Different products.**
- **Stereo video see through**
- **\$1500**



DAQRI Smart Helmet



- **AR for the construction industry**
- **With developers already**
- **4D display**
- **\$ “thousands”**
- **Optical see through AR**



Rideon Vision Ski Goggles



- **AR Ski Goggles**
- **\$899**
- **Uses smartphone**
- **See through AR screen.**

<https://www.youtube.com/watch?v=EL4zvDcpIMc>



All Smartphones



- **Camera**
- **GPS**
- **Accelerometer**
- **Everyone has one**
- **Handheld – Video see-through**



Structure Sensor for Tablets



D
s
c
a
n
n
e
r
f
o



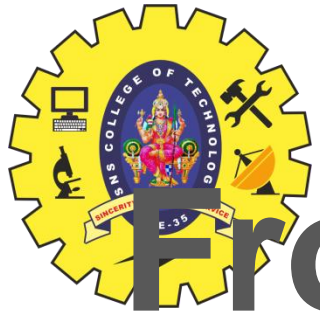
Arachnophobia Treatment

- **Uses Microsoft Kinect**
- **Treats arachnophobia**

**Interactive Augmented Reality
With Microsoft's Kinect**

Sam Corbett-Davies
Andreas Dünser Adrian Clark

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From Devices...





Wearable to Deviceless!

