

# **SNS COLLEGE OF TECHNOLOGY**

**Coimbatore-35**  
**An Autonomous Institution**

Accredited by NBA – AICTE and Accredited by NAAC – UGC with 'A+' Grade  
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## **DEPARTMENT OF INFORMATION TECHNOLOGY**

### **16IT AUGMENTED REALITY AND VIRTUAL REALITY**

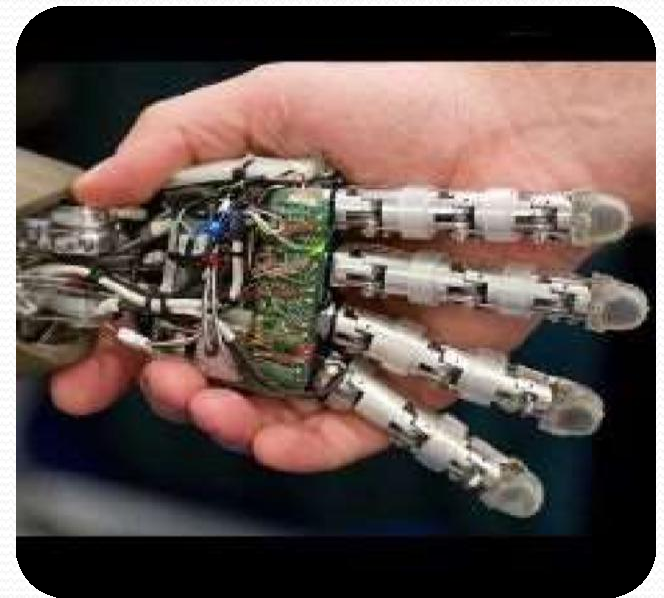
**III YEAR – V SEM**

**UNIT 4 – INTERACTIVE TECHNIQUES AND TOOLS**

**TOPIC 4 –Haptic feedback**

# HAPTICS: A TOUCH FEEDBACK

- ❑ ‘Haptics’ is derived from the Greek word ‘haptikos’ which means – ‘being able to come into contact’.
- ❑ Haptics is the science of applying touch (tactile) sensation and control to interact with computer applications.



# HISTORY

- ❑ In the early 20th century, psychophysicists introduced the word *haptics*, that addressed human touch-based perception and manipulation
- ❑ In the 1970s and 1980s, robotics also began to focus on manipulation and perception by touch.
- ❑ In the early 1990s a new usage of the word *haptics* began to emerge. The confluence of several emerging technologies made virtualized haptics, or computer haptics possible.

# Virtual Reality

Virtual reality is a form of human-computer interaction providing a virtual environment that one can explore through direct interaction with our senses.



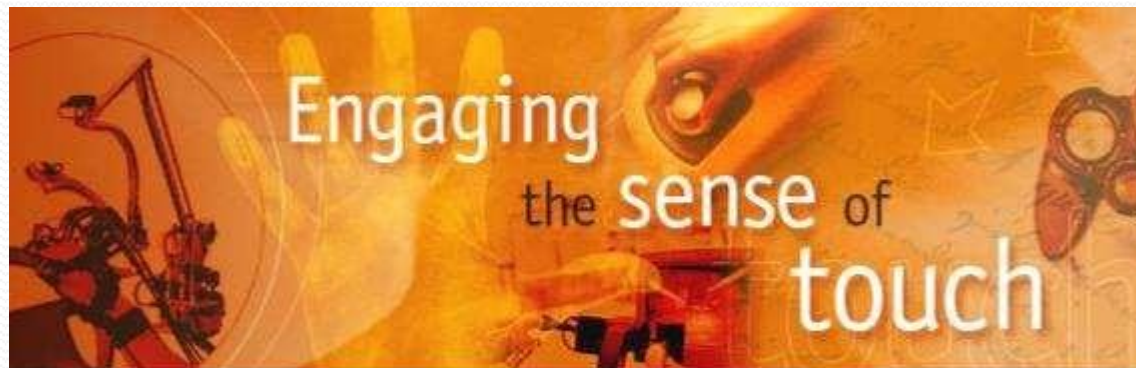
# The Real World

- User should be able to touch the virtual object and feel a response from it.
- In order to complete the imitation of the real world one should be able to interact with the environment and get a feedback.
- This feedback is called Haptic Feedback.

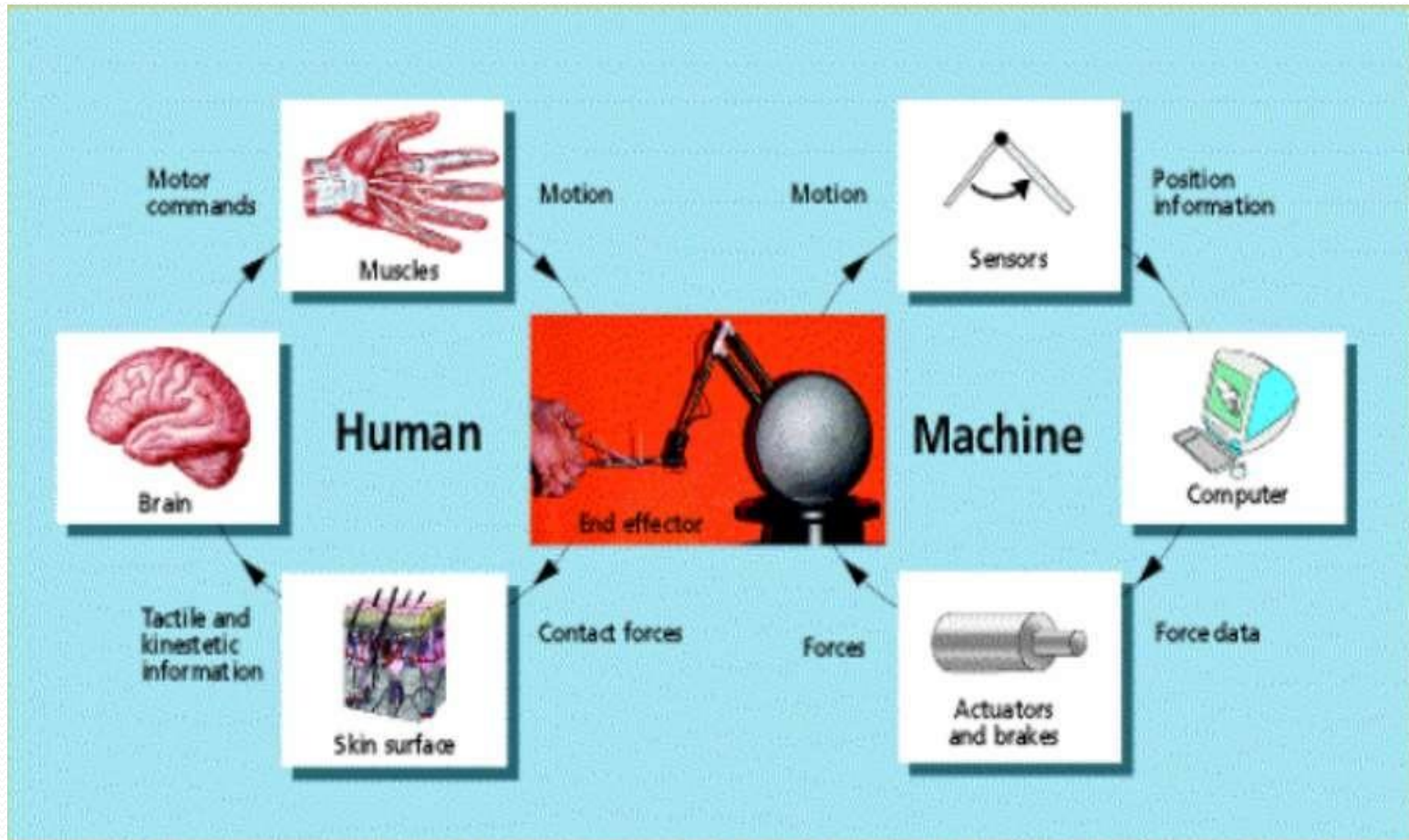


# Haptics Technology

- **Haptic technology** is a tactile feedback technology which takes advantage of the sense of touch by applying forces, vibrations, or motions to the user.
- A haptic device gives people a sense of touch with computer-generated environments, so that when virtual objects are touched, they seem real and tangible.



# Basic system configuration



# Haptic information

□ It is the combination of:

➤ Tactile information

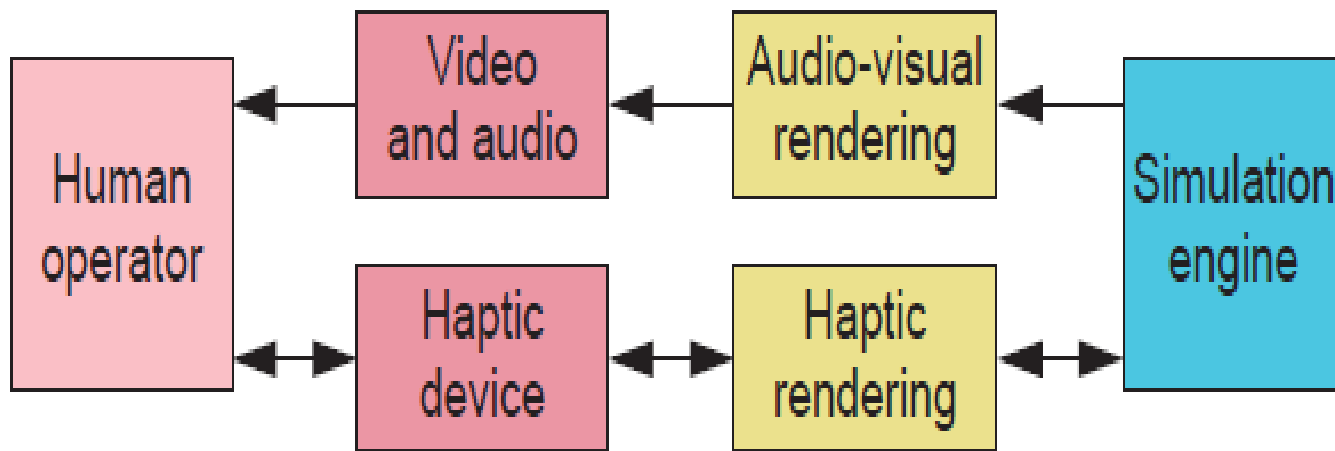
➤ Kinesthetic information

□ *Tactile Information*: It refers to the responses of the receptors of the skin in contact with an object.

□ *Kinesthetic Information*: It refers to the information acquired through the sensors in the joints.



# Haptics Feedback



The human operator typically holds or wears the haptic interface device and perceives audiovisual feedback from audio and visual displays

# The technology

- Haptics is implemented through different type of interactions with a haptic device communicating with the computer. These interactions can be categorized into the different types of touch sensations a user can receive:
  - Tactile Feedback
  - Force Feedback

# Tactile feedback (touch)

- Refers to the sensations felt by the skin.
- It allows the user to feel things such as the texture of surfaces, temperature and vibration.



# Force feedback (kinesthetic)

- It reproduces the directional forces that can result from solid boundaries.
- E.g. the weight of virtual objects, inertia, etc.





# Sense of touch in haptic feedback technology

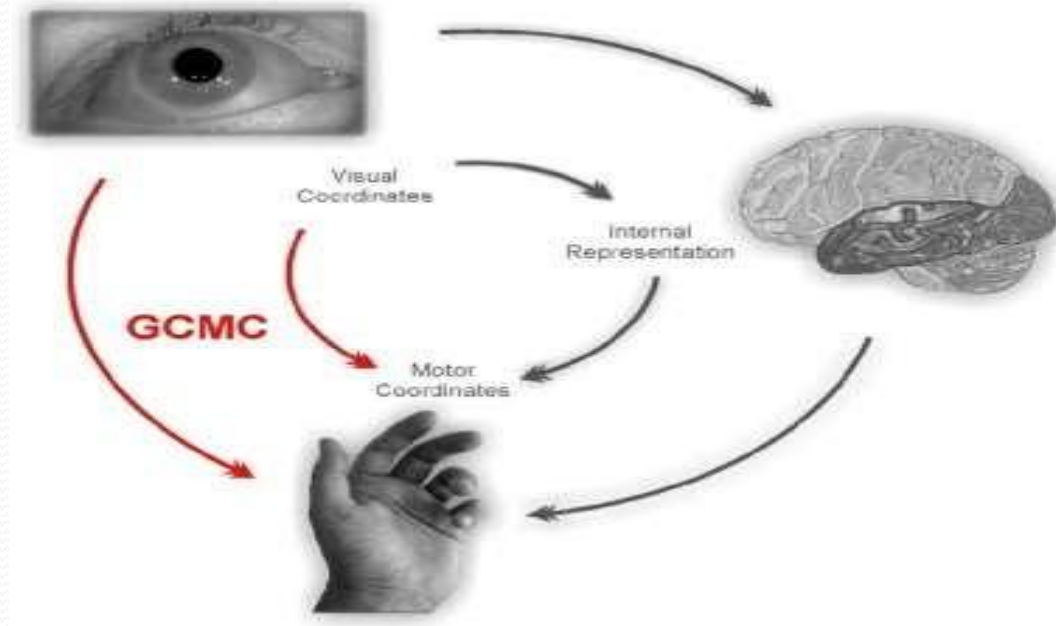
- In *Haptic Feedback* there are three types of *Haptic Sensations* to feel with our *Sense of Touch* and that is why we call that technology as the *Science of Touch*.



Sense of touch

# 1. Kinesthetic (Force) Sense :

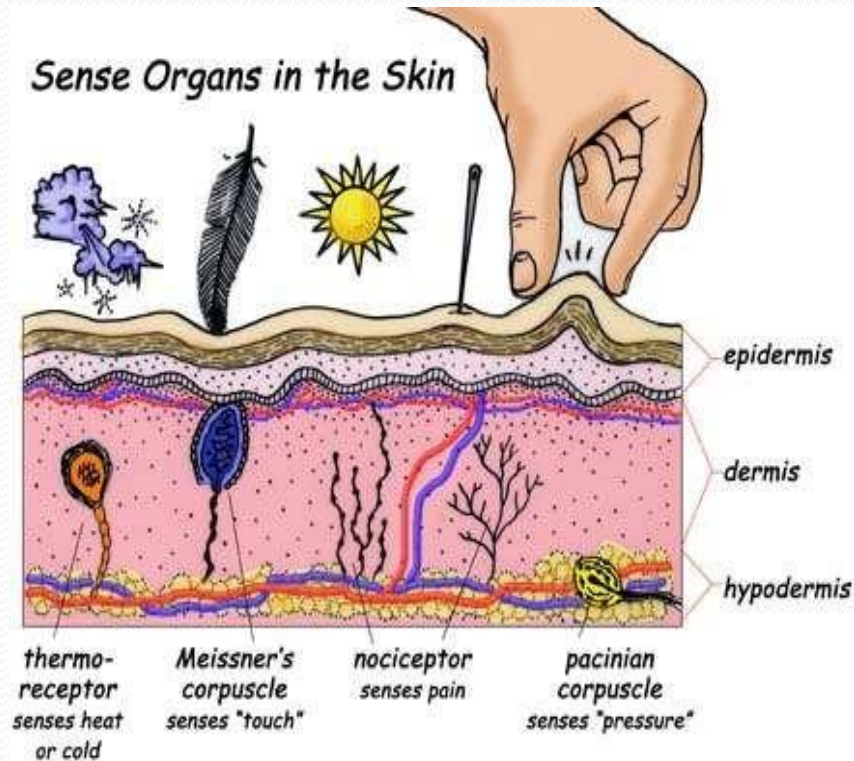
- It is the feeling of power and force.
- The motor system constantly informs about the position of arms, and the efforts made to move them.



MOTOR SYSTEM

## 2. Tactile (Touch) Sense :

- This is the sensation of textures.
- At our fingertips (and more broadly on our skin), we have pressure sensors which gives us information on the relief of the object.
- This is what allows us to easily differentiate a smooth object of a rugged object.



Touch Sense

### 3. *Temperature (Thermal) Sense :*

- It is the sensation of cold or heat.
- This sensation tells us about two points:
  - First, the temperature of the relative object to our finger (when our finger is cold, warmer objects appear to us).
  - Second, the nature of the object. Even if a piece of wood and a piece of metal are at the same temperature, we perceive them differently



Temperature sense





## *Key advantages of touch feedback*

- Creates the perception of touching physical buttons and switches.
- Works with a wide range of touch screen sizes and technologies.
- Provides fast, tactile response synchronized with sound and graphics.
- Enhances usability, particularly for noisy or distracting environments.
- Helps improve user performance, productivity, and safety.
- Programmability can be used to further enhance usability.

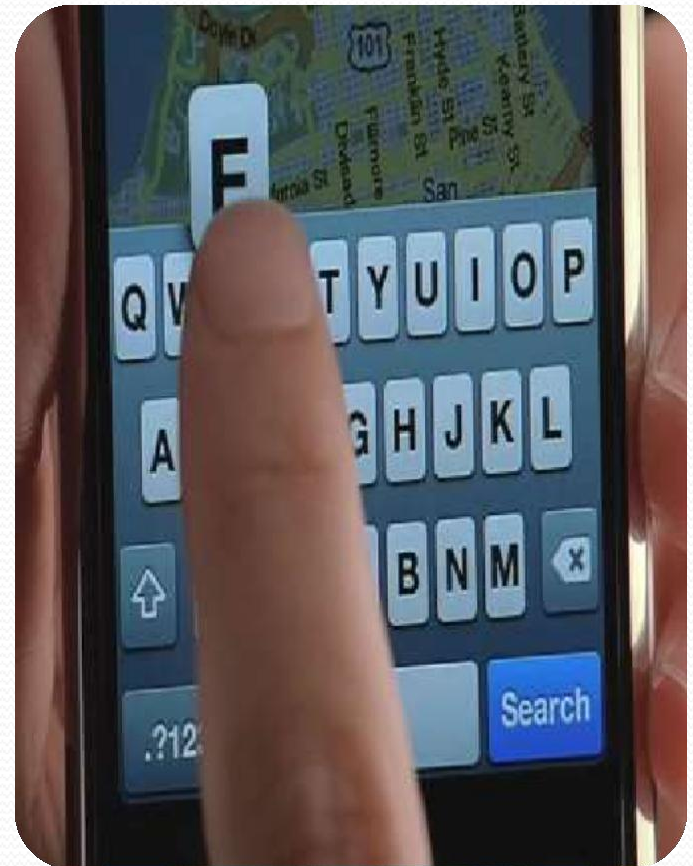
# Design of Haptic System

- Haptics are enabled by **actuators** that apply forces to the skin for touch feedback.
- Haptic feedback use electromagnetic technologies such as **vibratory motors**, like a vibrating alert in a cell phone or a voice coil in a speaker, where a central mass is moved by an applied magnetic field.



# Design of Haptic System

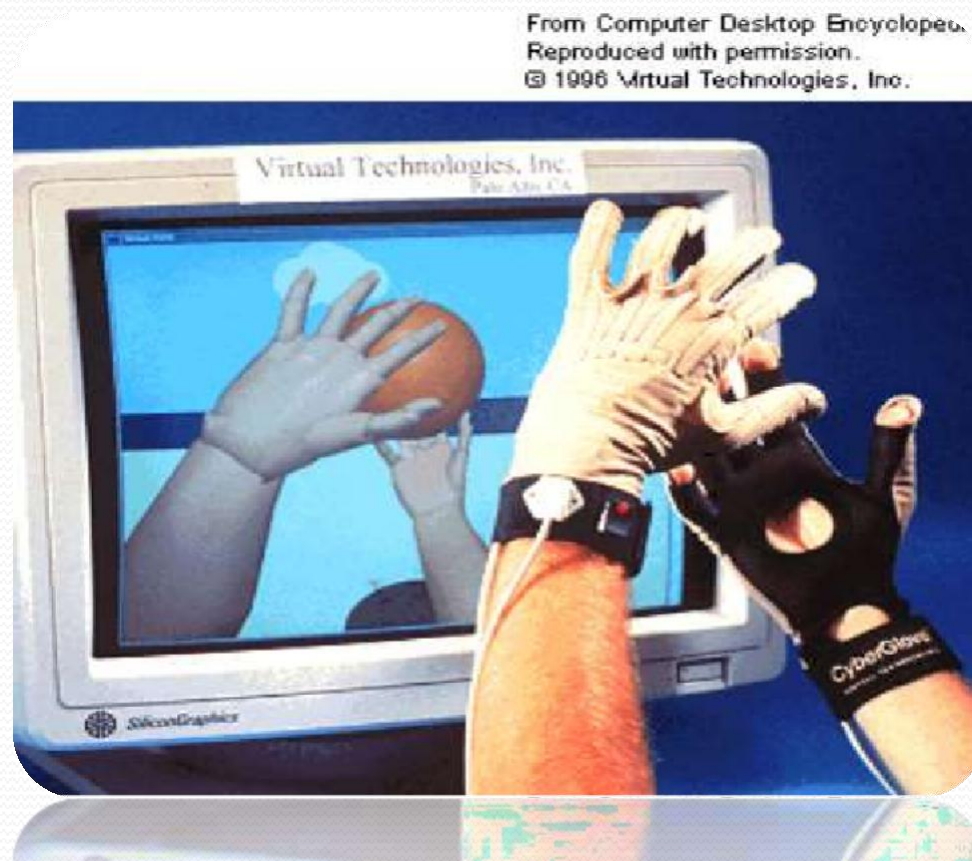
- The actual process used by the software to perform its calculations is called **haptic rendering**. A common rendering method uses polyhedral models to represent objects in the virtual world.
- The job of conveying haptic images to the user falls to the interface device.





# Haptic devices

- It allows users to touch, feel and manipulate 3-D objects in virtual environments.





## How are Haptic Devices Different?

- Common interface devices like mouse and joystick are only input devices. No feedback.
- Haptic devices are input-output devices.



# Classification of haptic devices

## 1) *Virtual reality/ Telerobotics based devices*

- i) Exoskeletons and Stationary device
- ii) Gloves and wearable devices
- iii) Point-sources and Specific task devices
- iv) Locomotion Interfaces

## 2) *Feedback devices*

- i) Force feedback devices
- ii) Tactile displays

# Exoskeletons

- Large and immobile systems that the user must attach him or herself to.
- Their large size and immobile nature allow for the generation of large and varied force information.



## Gloves and wearable devices

- The user can move naturally without being weighed down by a large exoskeleton or immobile device
- E.g. Hand Master





# FORCE FEEDBACK DEVICES

- Connected to computer systems applying forces to simulate the sensation of weight and resistance providing information to the user.
- Input from the user in the form of hand, or other body segment whereas feedback from the computer or other is in the form of force or vibration.



## TECTILE DISPLAYS

- Tactile feedback tells us the texture of the surfaces.
- Using this we can feel different surfaces and slipping sensations can be produced

# Areas of Haptics

- **Computer Haptics-** It helps to enable a user to feel something happening in the computer's mind through a typical interface.
- **Human Haptics-** It tells us how humans and living beings experience touch.
- **Machine Haptic-** It tells us how mechanical devices touch and feel their environment

# Applications of Haptics Technology

❑ **Computer and video games:** Haptic feedback is commonly used in arcade games, especially racing video games.



❑ **Mobile devices:** Tactile haptic feedback is becoming common in cellular devices.



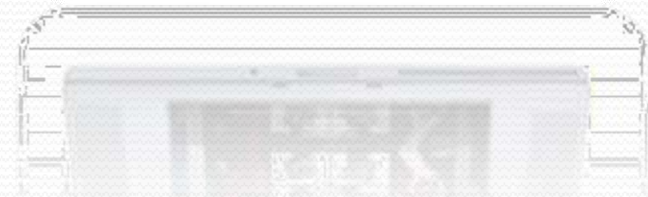


## Applications of Haptics Technology

### ❑ *Personal computers:*

Apple's MacBook and MacBook Pro started incorporating a "Tactile Touchpad" design.

### ❑ *Virtual reality:* Haptics are gaining widespread acceptance as a key part of virtual reality systems.



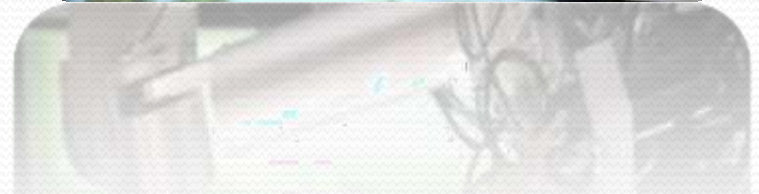
# Applications Of Haptics Technology

- ❑ **Medicine:** Haptic interfaces for medical simulation may prove especially useful for training in minimally invasive procedures such as laparoscopy and interventional radiology as well as for performing remote surgery



## Applications of Haptics Technology

- ❑ **Robotics:** Haptic technology is also widely used in teleoperation, or telerobotics.
- ❑ **Arts and design:** Haptics is used in virtual arts, such as sound synthesis or graphic design and animation







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# Future of haptic technology

- Future applications of haptic technology cover a wide spectrum of human interaction with technology.
- Current research focuses on the mastery of tactile interaction with holograms and distant objects.
- Which if successful may result in applications and advancements in gaming, movies, manufacturing, medical, and other industries.<sup>1</sup>



[Future of Haptic Technology](#)



[What the world is waiting for?](#)

# Future of haptic technology

- The medical industry stands to gain from virtual and telepresence surgeries, which provide new options for medical care.
- The clothing retail industry could gain from haptic technology by allowing users to "feel" the texture of clothes for sale on the internet
- Future advancements in haptic technology may create new industries that were previously not feasible or realistic.


# conclusion

- Haptic devices must be miniaturized so that they are lighter, simpler and easier to use.
- Large potential for applications in critical fields as well as for leisurely pleasures.
- Haptics is the future for online computing and e-commerce, it will enhance the shopper experience and help online shopper to feel the merchandise without leave their home

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Thank You