



SNS COLLEGE OF TECHNOLOGY

Kurumbapalayam (Po), Coimbatore - 641 107

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Accredited by NBA - AICTE and Accredited by NAAC - UGC with 'A+' Grade
Approved by AICTE, New Delhi & Affiliated to Anna University, Chennai

DEPARTMENT OF MECHANICAL ENGINEERING

COURSE NAME : 16MEOE2 NEW PRODUCT DEVELOPMENT
III YEAR /V SEMESTER

**Unit 3 – Concept Embodiment And Modeling Of
Product Metrics**

Topic : MECHANICAL EMBODIMENT PRINCIPLES

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Mechanical Embodiment Principles



During the conceptual design phase, the **mechanical** design engineer develops new ideas, new **principles** of solution based on physical **principles** and evaluate their feasibility.

Once an idea (a concept) has been chosen, the product architecture and product part development starts.

- Alignment of forces**
- 3-2-1 Alignment**
- Deflection reduction and Abbe principle**
- Forces in members**
- Vibration reduction.**



Alignment of forces



- ❖ Forces within an assembly are what makes parts move.
- ❖ The **position and orientation** of these forces are design choices that designer makes.
- ❖ To properly design the product, one should consider **three forces** on moving part.

Weight

Frictional force

Applied force





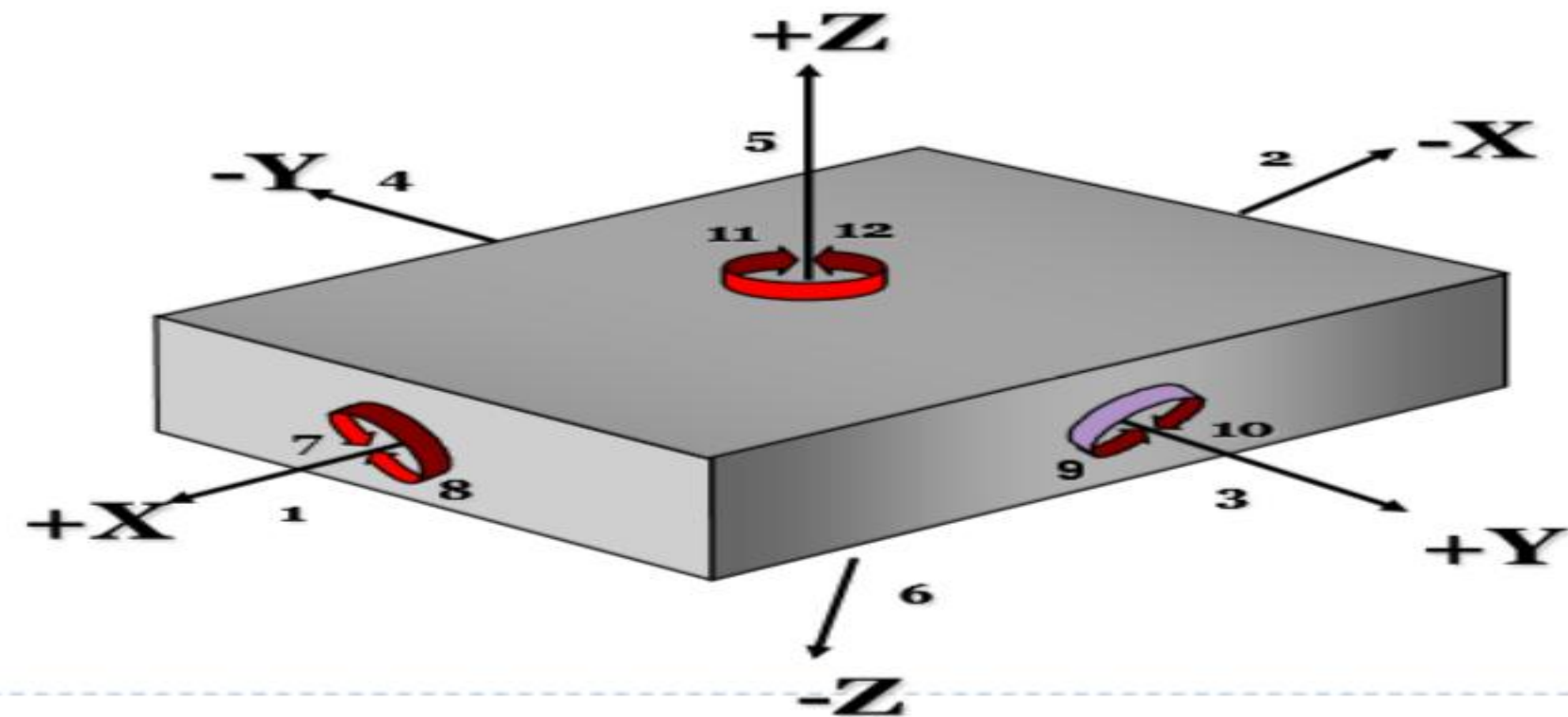
3-2-1 Alignment



Basics of Fixture Design

12 Degrees Of Freedom

- | | |
|------|------|
| (1) | X+ |
| (2) | X- |
| (3) | Y+ |
| (4) | Y- |
| (5) | Z+ |
| (6) | Z- |
| (7) | XCCW |
| (8) | XCW |
| (9) | YCCW |
| (10) | YCW |
| (11) | ZCW |
| (12) | ZCCW |





Major functions required for proper design

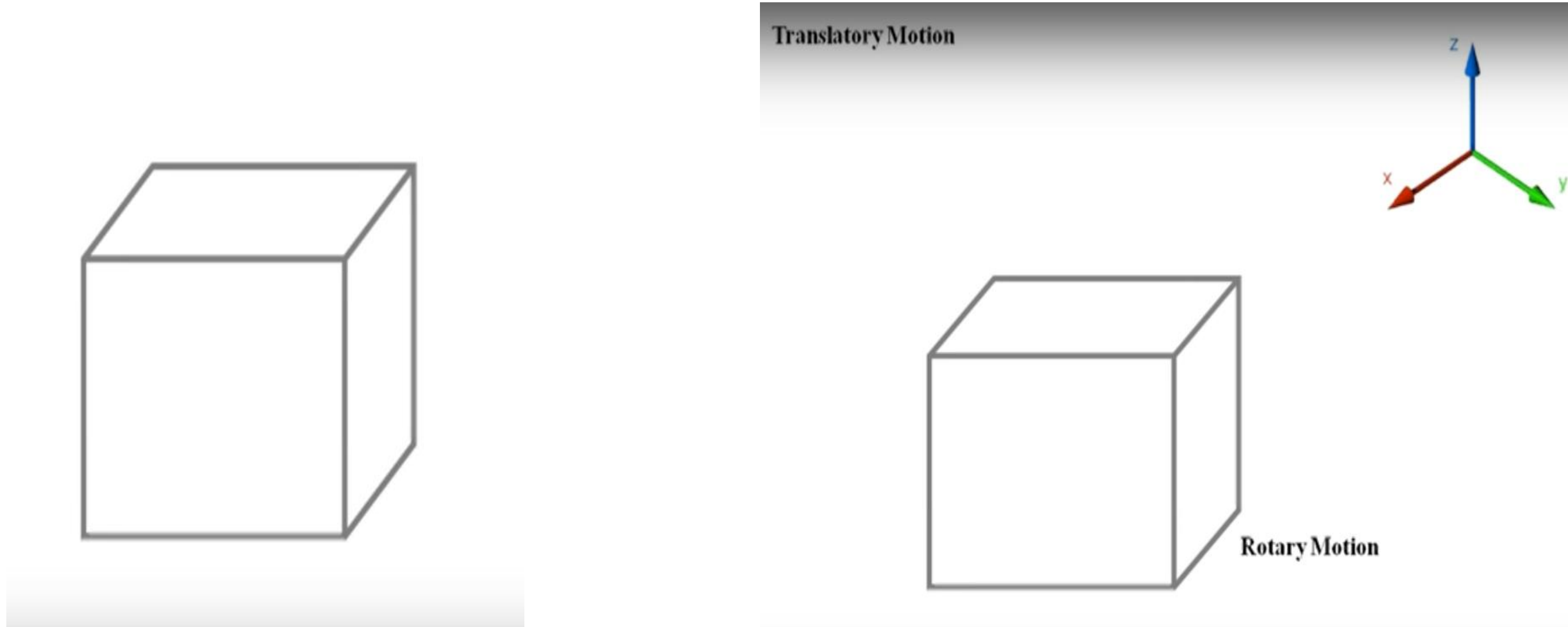


- Location**
- Supporting**
- Clamping of blank**



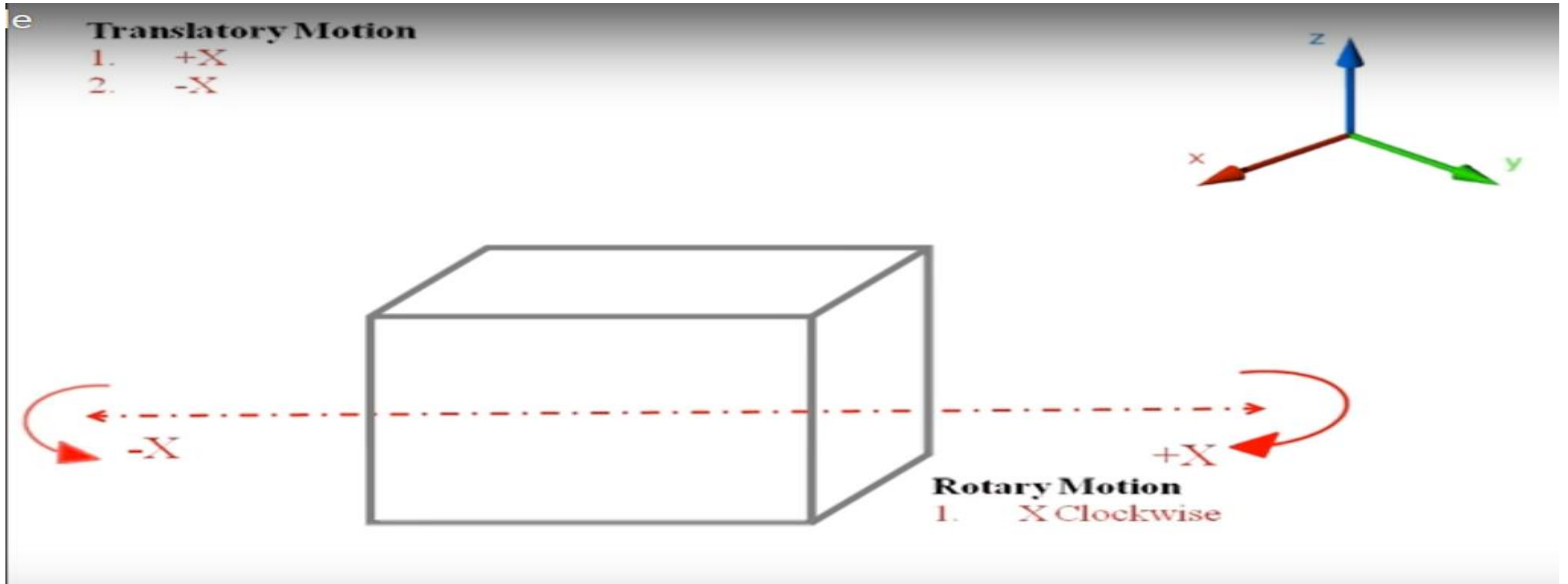


3-2-1 Alignment





3-2-1 Alignment





3-2-1 Alignment



e

Translatory Motion

1. $+X$
2. $-X$
3. $+Y$
4. $-Y$

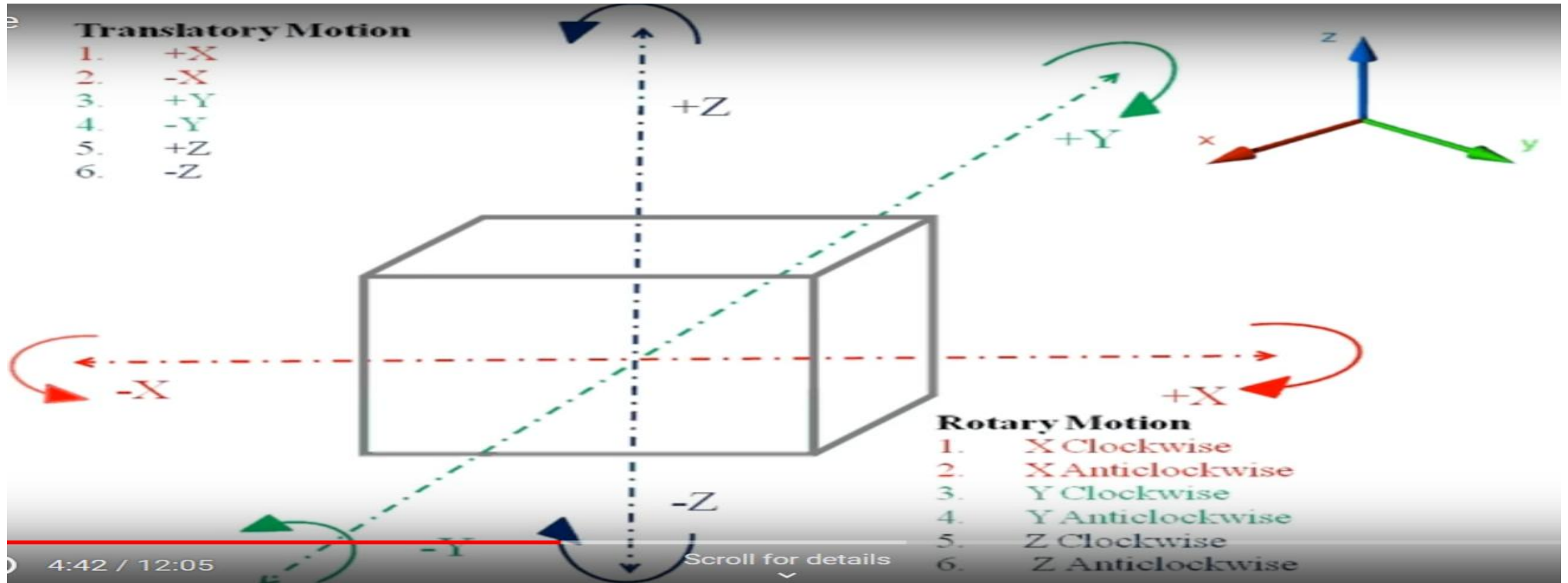
Rotary Motion

1. X Clockwise
2. X Anticlockwise
3. Y Clockwise
4. Y Anticlockwise

4:17 / 12:05 Scroll for details



3-2-1 Alignment





3-2-1 Alignment



Work-piece



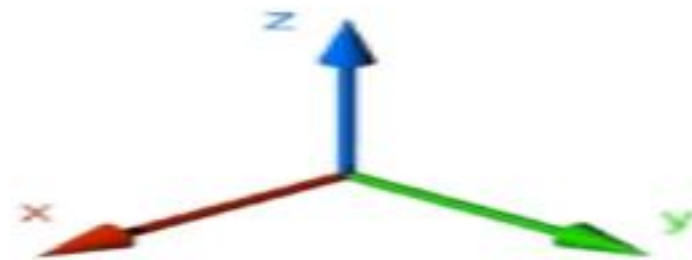


3-2-1 Alignment



Transverse Motion

Rotary Motion



Work-piece





3-2-1 Alignment



Transverse Motion

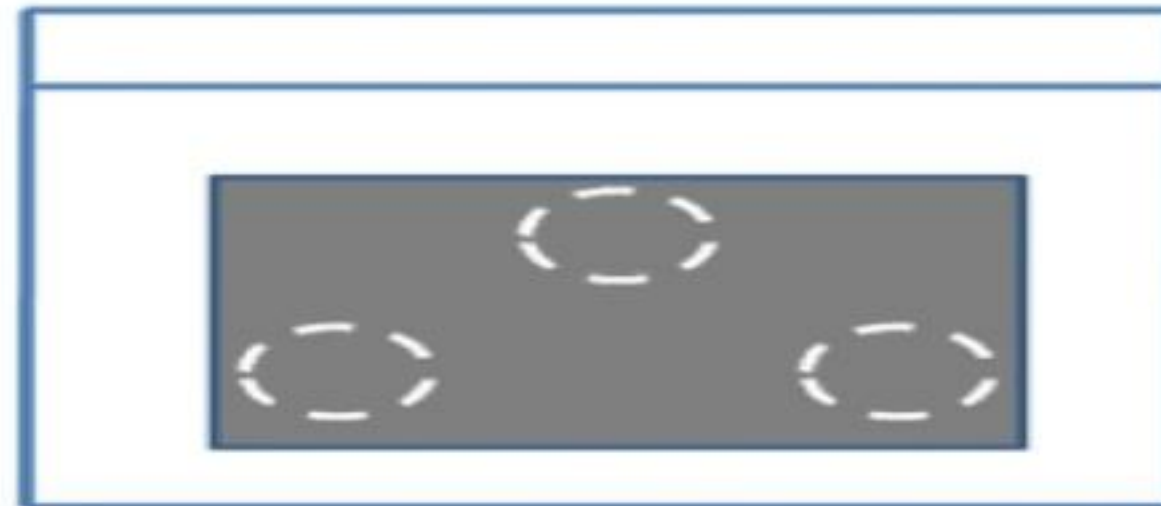
6. -Z

Rotary Motion

Locating and Supporting pins

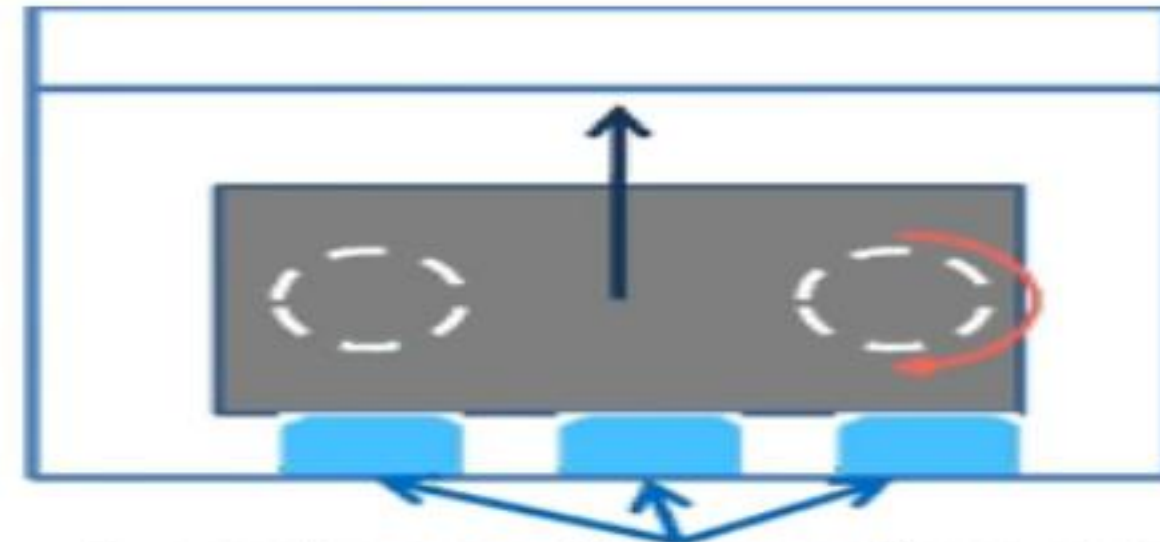


Work-piece





3-2-1 Alignment



Transverse Motion

3. +Y

6. -Z

Rotary Motion

1. X Clockwise

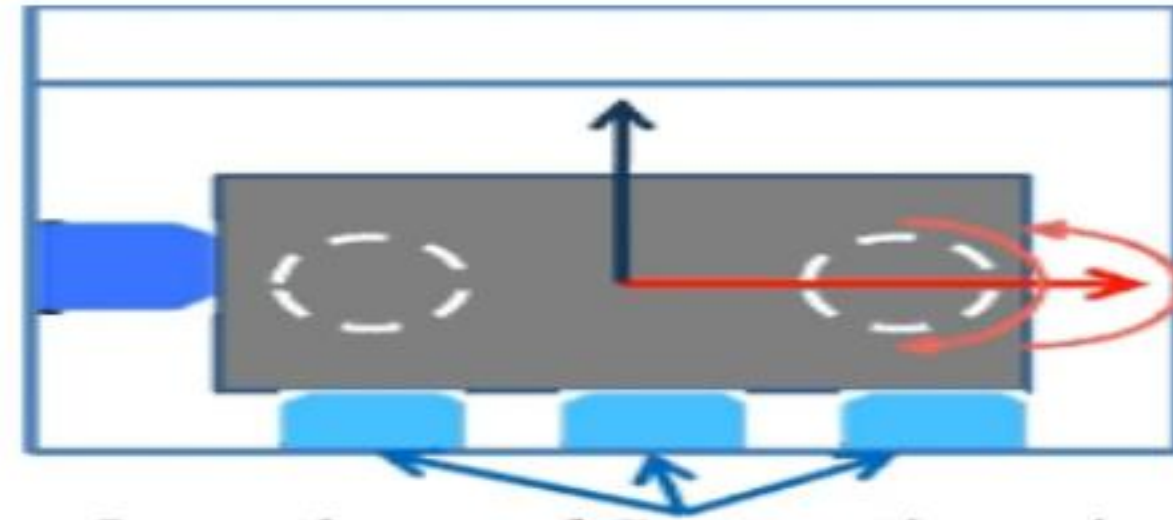
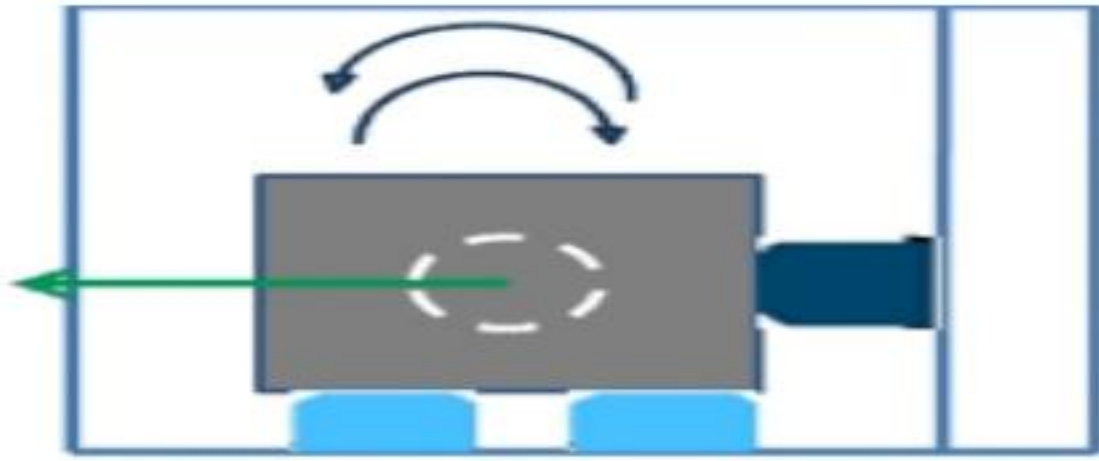
2. X Anticlockwise



Work-piece



3-2-1 Alignment



Locating and Supporting pins



Work-piece

Locating Pin



Transverse Motion

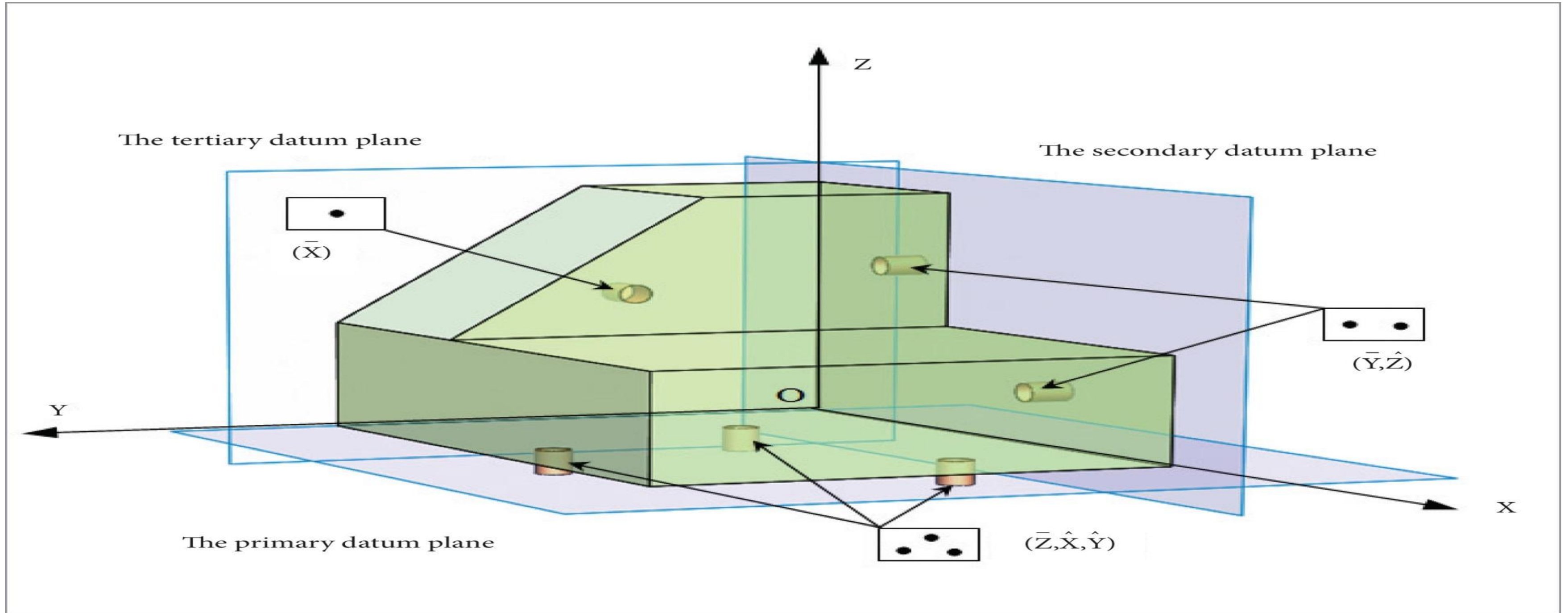
- 2. -X
- 3. +Y
- 6. -Z

Rotary Motion

- 1. X Clockwise
- 2. X Anticlockwise
- 3. Y Clockwise
- 4. Y Anticlockwise
- 5. Z Clockwise
- 6. Z Anticlockwise



3-2-1 Alignment





Practise quiz



1. Principle of _____ states that “In order to achieve the maximum accuracy in location the locating points should, therefore, be placed as far apart from one another as it is possible”.

- (A) Six point location
- (B) Least points
- (C) Extreme positions
- (D) Mutually perpendicular planes



2. When 3-2-1 principle is used to support and locate a three dimensional work-piece during machining, the number of degrees of freedom that are restricted is

- A. 7
- B. 8
- C. 9
- D. 10

Ans: 1-C, 2.C



Vibration reduction



Three approaches to vibrate less

- First approach : **Reduce the source**
- Second approach: **Change the natural frequency of source or transmitting parts**
- Third approach : **Insertion of dampeners**

Thank You

