



SNS COLLEGE OF TECHNOLOGY
(AN AUTONOMOUS INSTITUTION)

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Department of Biomedical Engineering

Course Name: 19BMT401 – Virtual Reality in Medicine

IV Year : VII Semester

Unit I –INTRODUCTION

**Topic : Input Devices :(Trackers, Navigation, and
Gesture Interfaces)**

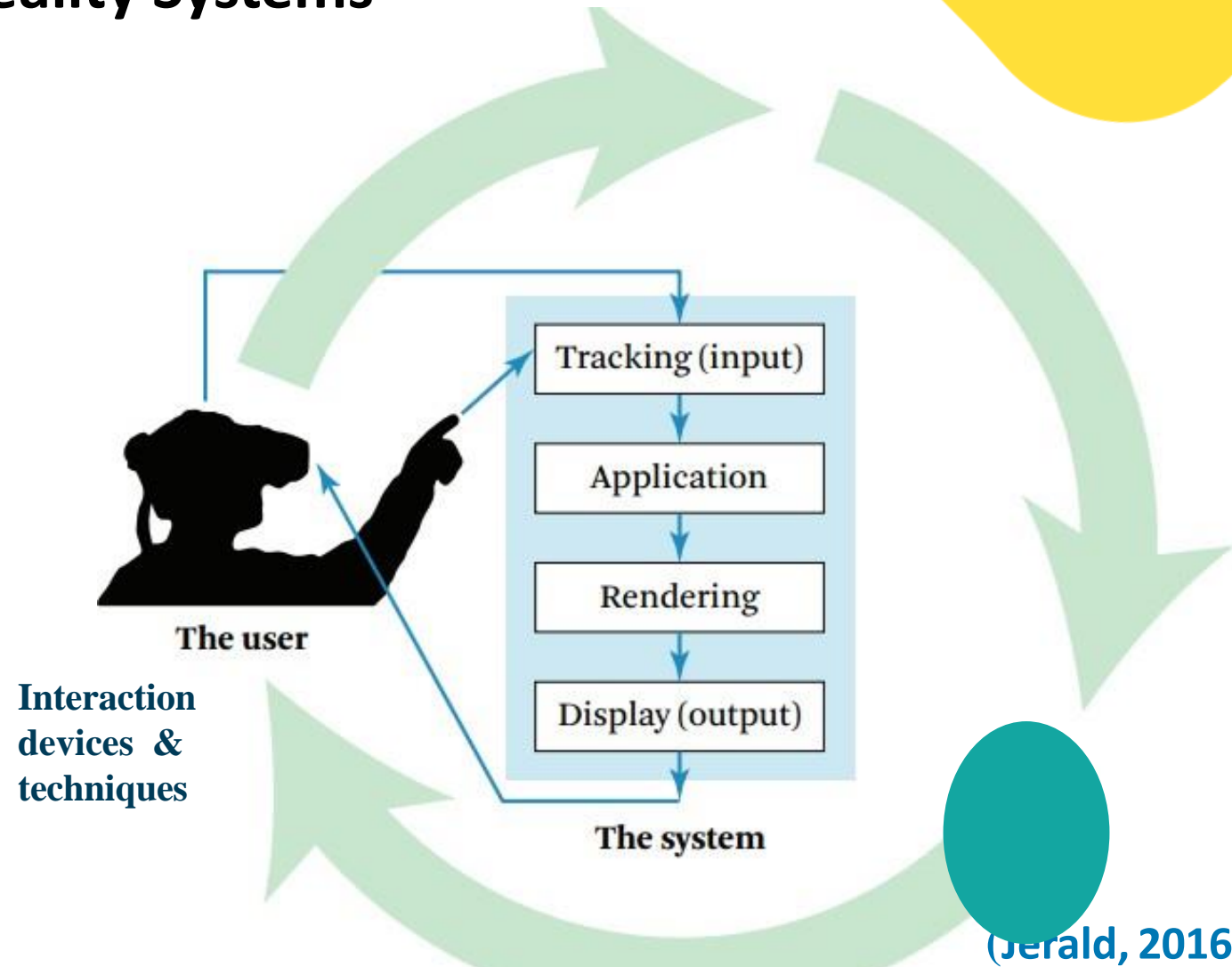


What is Virtual Reality?

“A high-end user interface that involves real-time simulation and **interaction** through multiple sensorial channels.” (vision, sound, touch, smell, taste) ([Burdea and Coiffet., 2003](#))



Virtual Reality Systems





Crucial technologies for VR

- Visual displays
- Graphics rendering system
- Tracking system
- Database system
- **Interaction devices**
- Interaction techniques
- Sound and haptic displays
(if possible...)

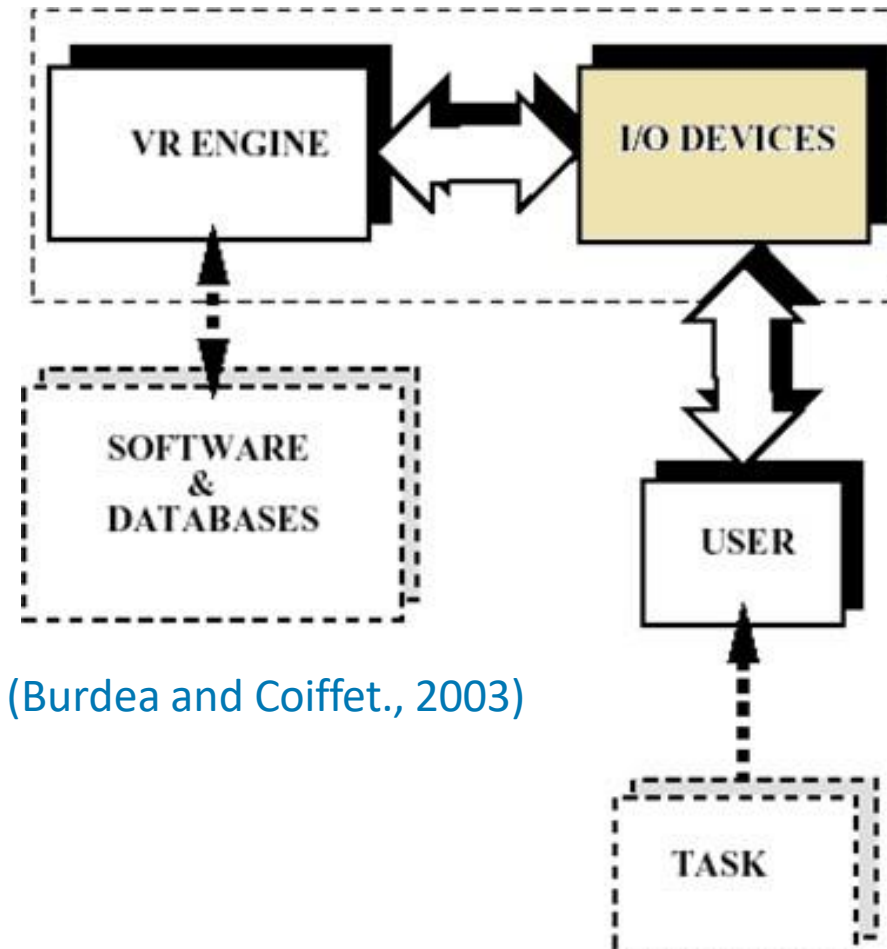


for AR

- + Cameras and registering



Input Devices: Trackers, Navigation and gestures interfaces

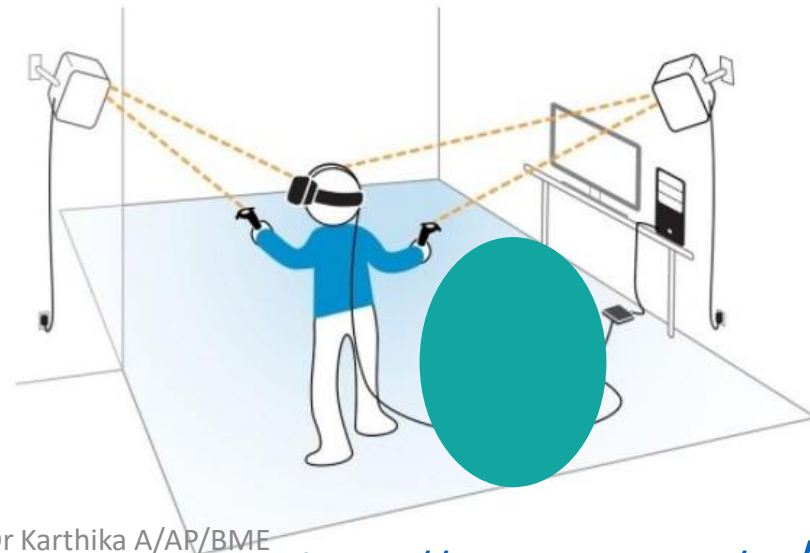
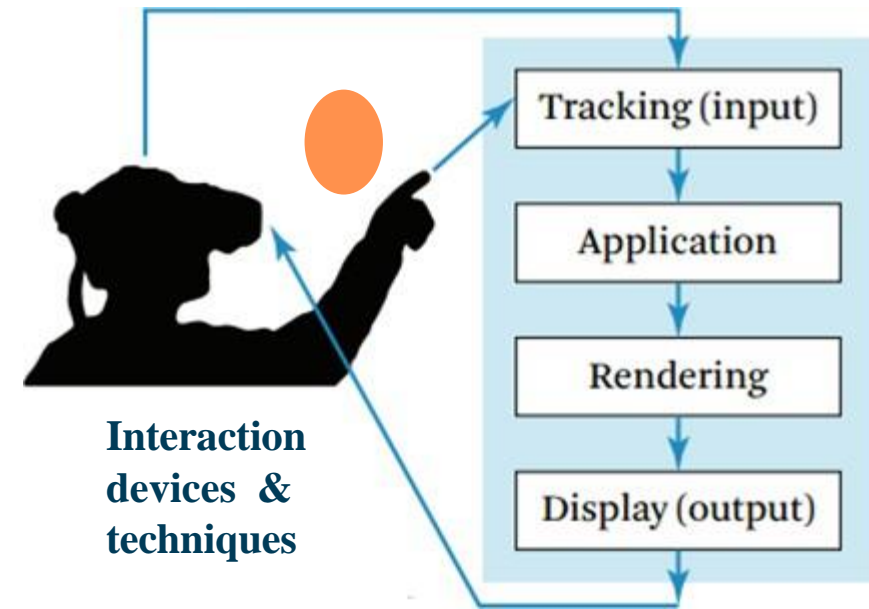


(Burdea and Coiffet., 2003)



Input devices

- Trackers:
 - Magnetic (AC, DC)
 - Optical
 - Ultrasonic
 - Inertial,
 - Mechanical
 - Hybrid ...
- Navigation and manipulation interfaces:
 - Tracker-based
 - Controllers
 - 3D mice, ...
- Gesture interfaces:
 - Depth cameras
 - Gloves ...





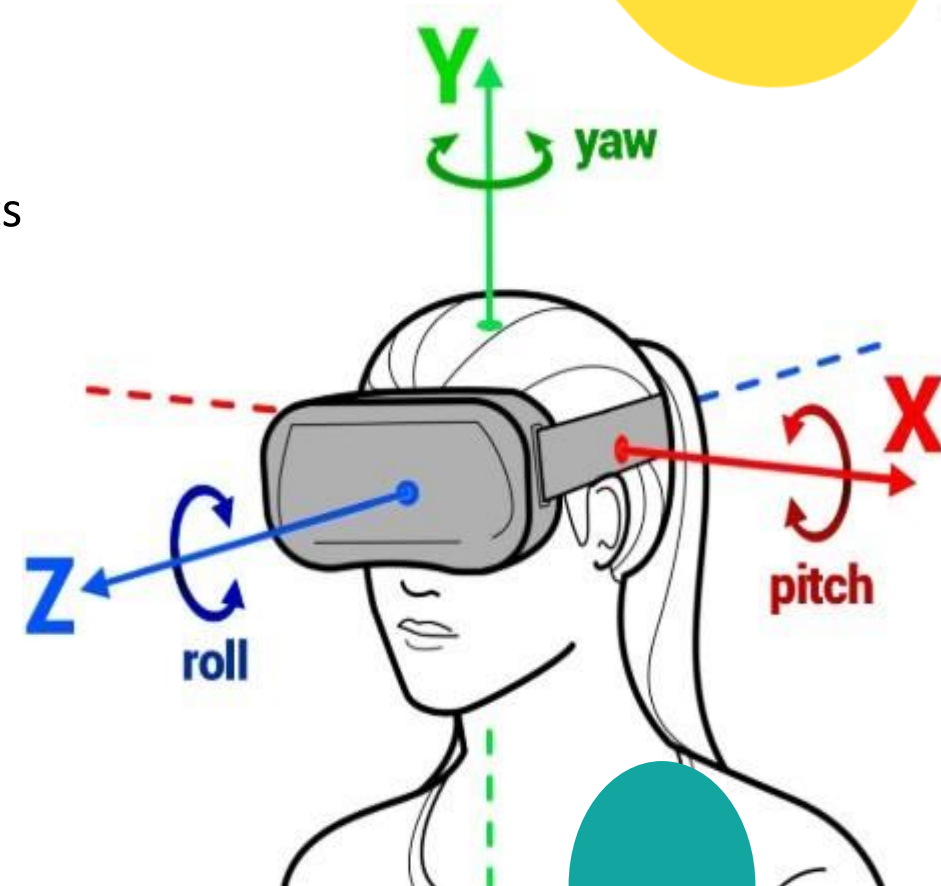
Tracker is a special purpose H/W to measure the real-time change in a 3D object position and orientation

Trackers measure the motion of “objects (e.g. user head) in a fixed system of coordinates.

Virtual objects have **6 degrees of freedom** (D.O.Fs):

- three translations;
- three rotations.

Roll – rotation around the zz axis



(Burdea and Coen 2003)

you may find other definitions...



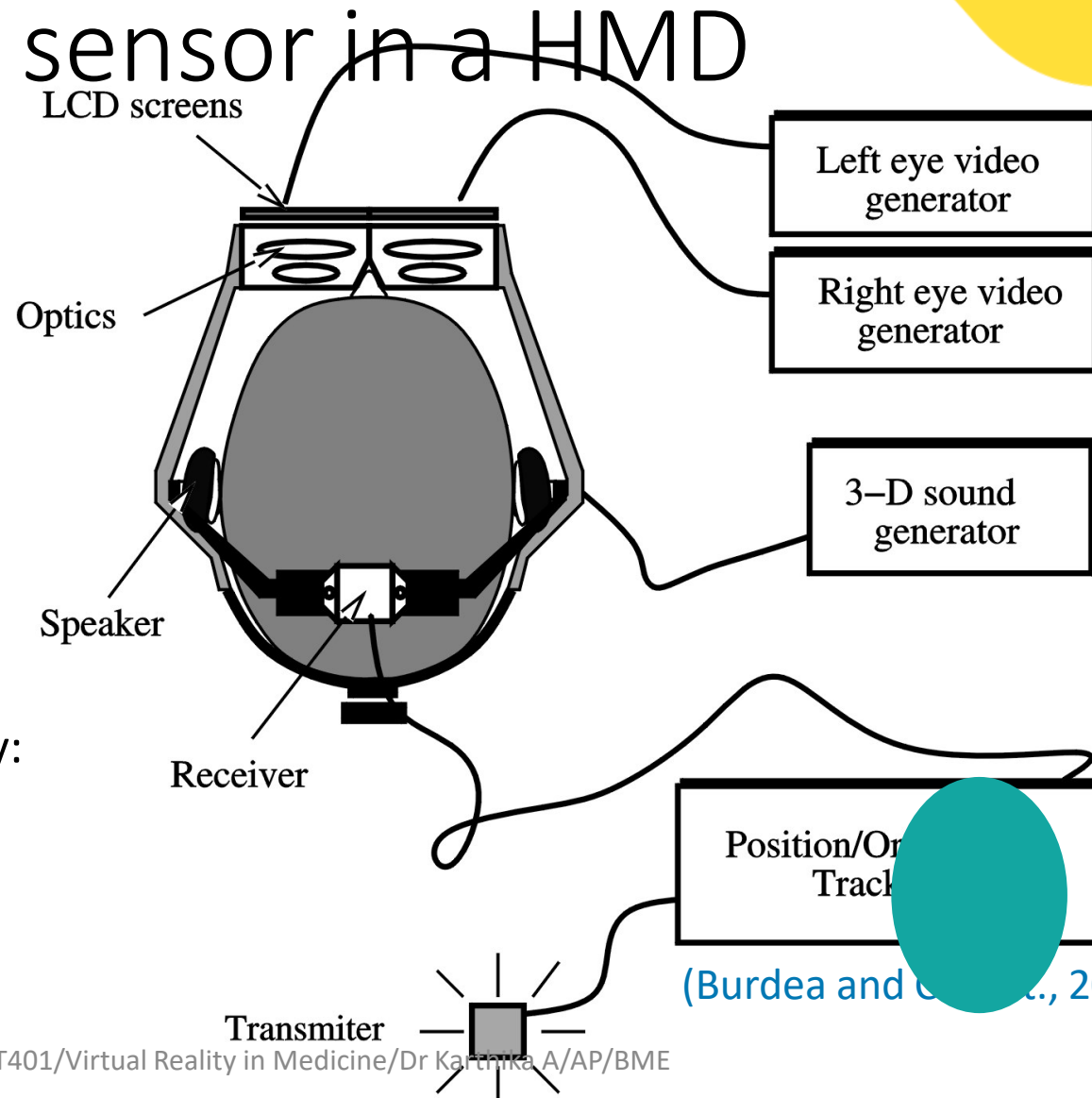
Example:

3D magnetic sensor in a HMD

Without the head tracker

- the image
- the sound

cannot change to match the head posture



Required tracking accuracy:
Image > sound

(Burdea and C. et al., 2003)



Tracker characteristics:

- Measurement rate – Readings/sec
- Sensing latency
- Sensor noise and drift
- Measurement accuracy
- Measurement repeatability
- Resolution
- Tethered or wireless
- Work envelope
- Sensing degradation
- ...



Magnetic Trackers

- A magnetic tracker is a non-contact position measurement device that uses a magnetic field produced by a stationary **TRANSMITTER** to determine the real-time position of a moving **RECEIVER** element
 - may be AC
 - DC



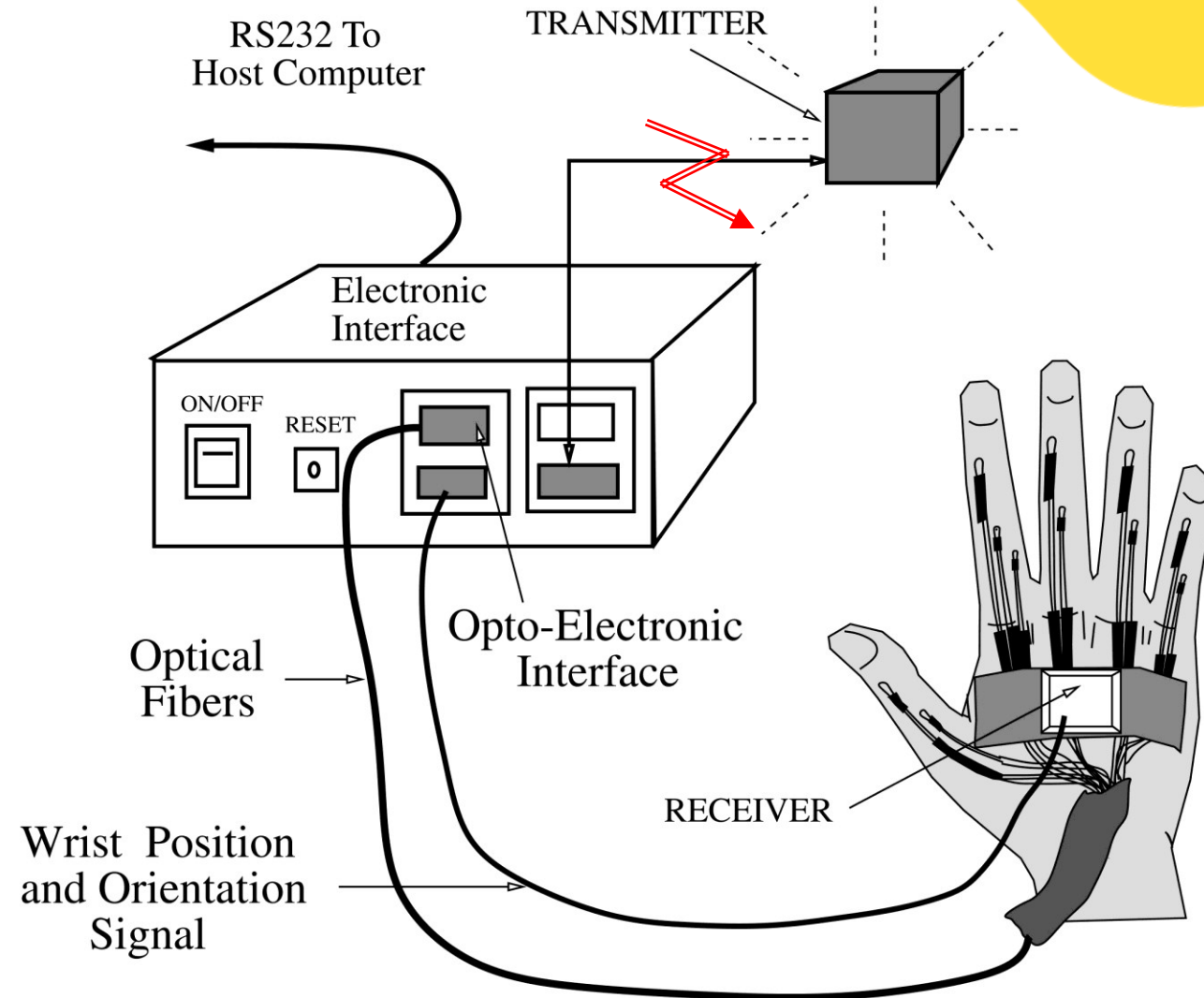
Magnetic Trackers

- Use low-frequency **magnetic fields to measure position**
- Fields are produced by a fixed source
- Size of source grows with the tracker work envelope
- The **receiver is attached to the tracked object** and has three perpendicular antennas
- Distance is inferred from the voltages induced in the antennas – **needs calibration...**



Magnetic tracker with the old Data Glove

(Burdea and Coiffet., 2003)





Ultrasonic Trackers

A non-contact position measurement device that uses an ultrasonic signal produced by a stationary transmitter to determine the real-time position/orientation of a moving receiver. ([Burdea and Coiffet., 2003](#))



Ultrasonic Trackers

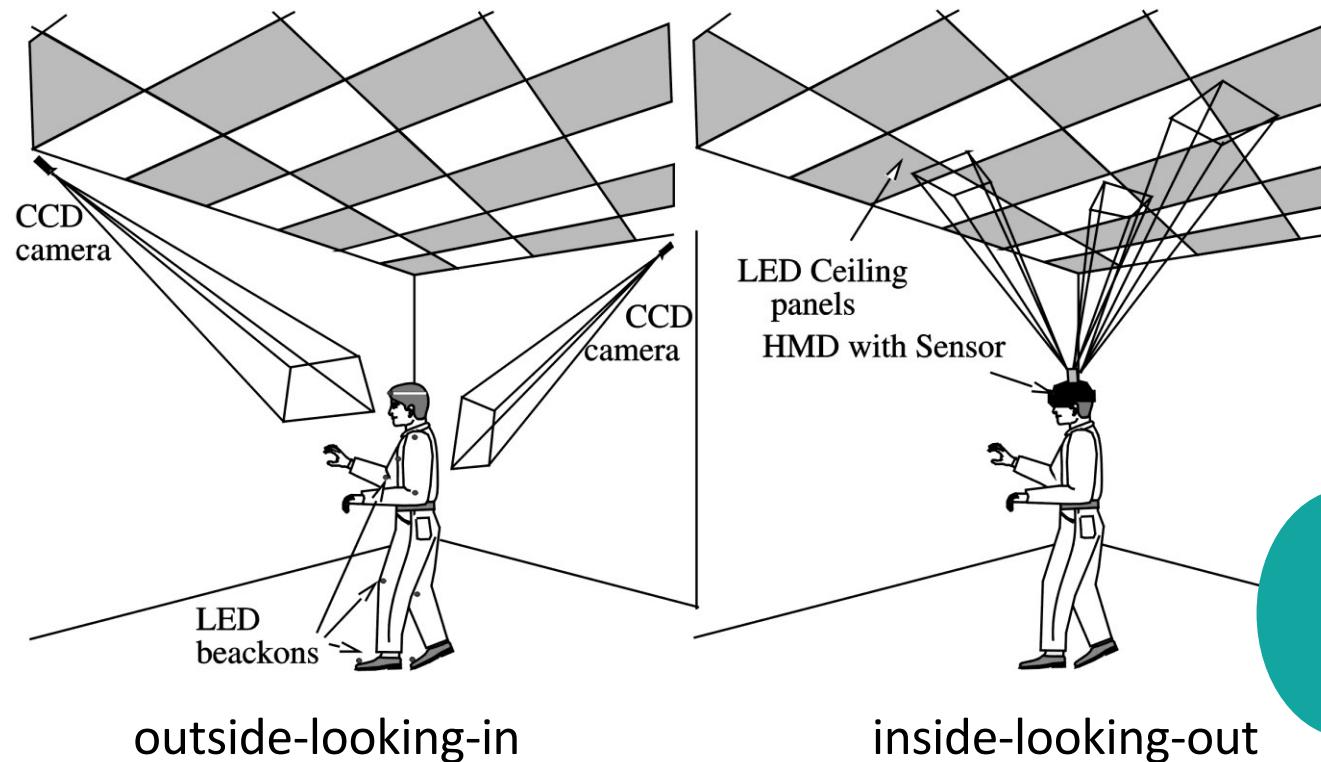
- Use low-frequency ultrasound to measure position
- Number of sources grows with the tracker work envelope
- Distance is inferred from the sound time of flight
- **Sensitive to air temperature and other noise sources**
- **Requires “direct line of sight”**
- Slower than magnetic trackers (max 50 updates/sec)
- More adequate to track hands than head





Optical Trackers

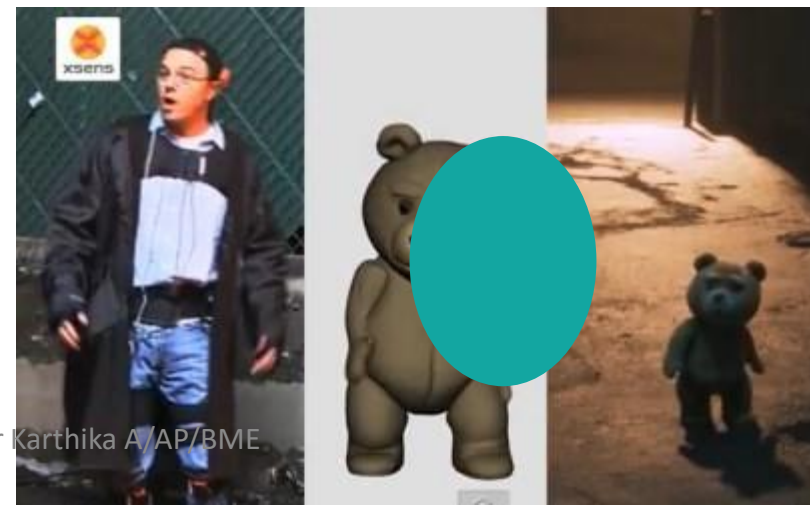
A non-contact position measurement device that uses optical sensing to determine the real-time position/ orientation of an object (Burdea and Coiffet., 2003)





Inertial Trackers

- No interference from metallic objects
- No interference from magnetic fields
- Large-volume tracking
- “Source-less” orientation tracking
- Full-room tracking
- Errors grow geometrically in time!





Hybrid Ultrasonic/Inertial Tracker



6 DOFs

Ultrasonic – position

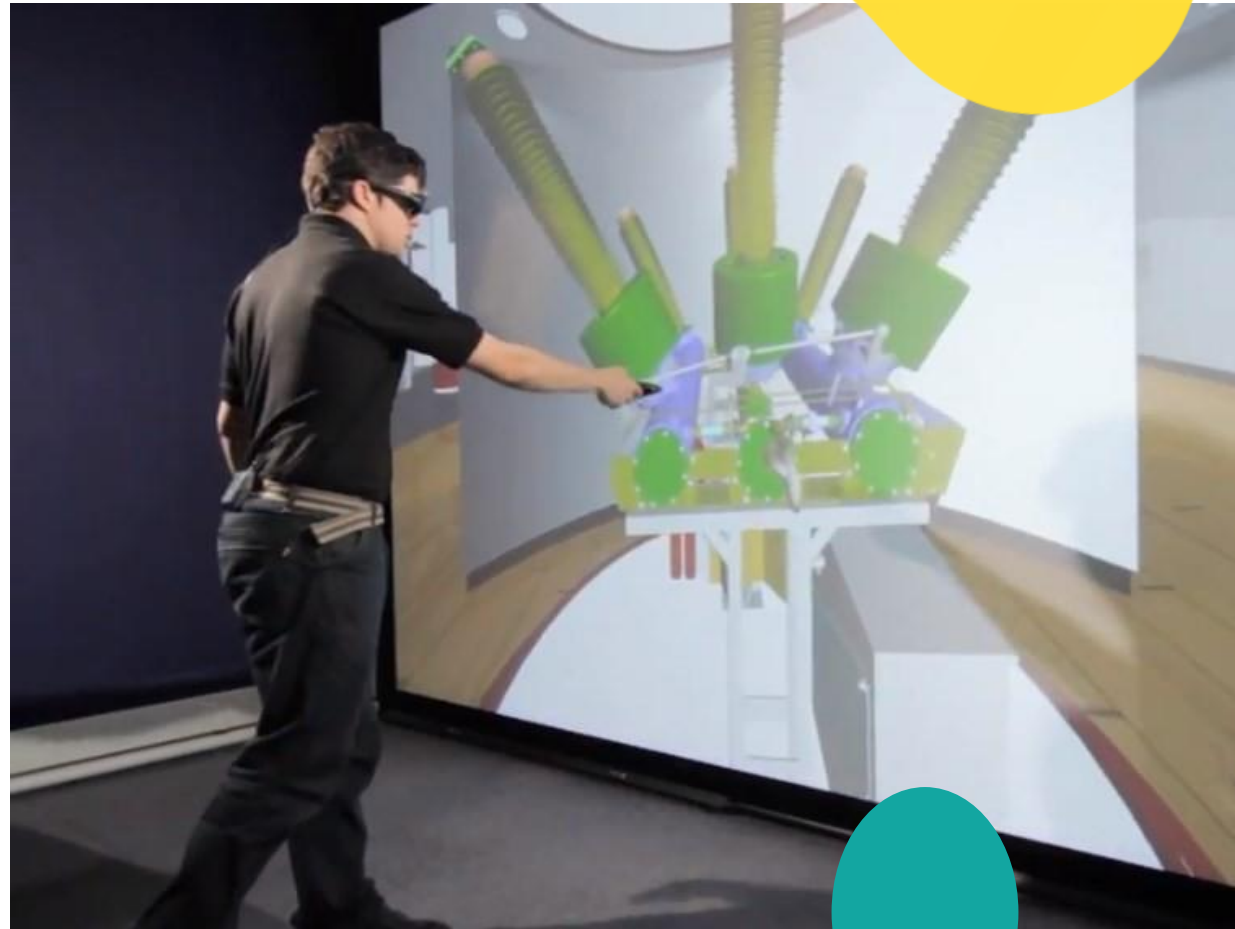
Inertial - orientation

Sub-millimeter accuracy

Head + hand units

Used for:

- Training
- Assembly/ disassembly
and design review
- ...



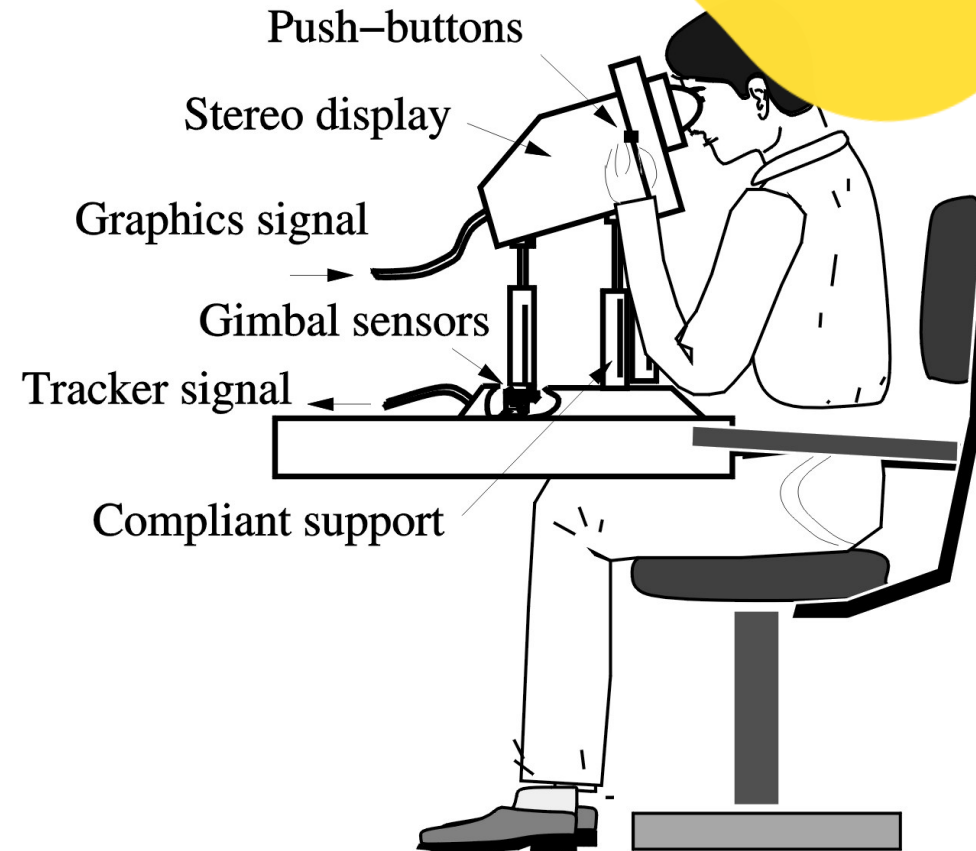


Mechanical Trackers

A mechanical tracker consists of a serial or parallel kinematic structure composed of links interconnected by sensorized joints.

(Burdea and Coiffet., 2003)

Were among the first tracking systems ever used



Mechanical tracker - Push 1280 x 1024 stereo display
(Fakespace Inc)



Mechanical Trackers

Pros

- Use sensors imbedded in exoskeletons to measure position
- Have extremely low latencies
- Are immune to interference from magnetic fields and large metal objects

Cons

- Limit the user's freedom of motion
- Can be heavy if worn on the body
- Expensive



Thank You