



SNS COLLEGE OF TECHNOLOGY

(An Autonomous Institution)



COIMBATORE-35

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DEPARTMENT OF ELECTRICAL AND ELECTRONICS ENGINEERING

COURSE NAME: 19EEB301/ CONTROL SYSTEMS

III YEAR / V SEMESTER

Unit II – TIME RESPONSE

Topic : Steady State Error



Steady State error

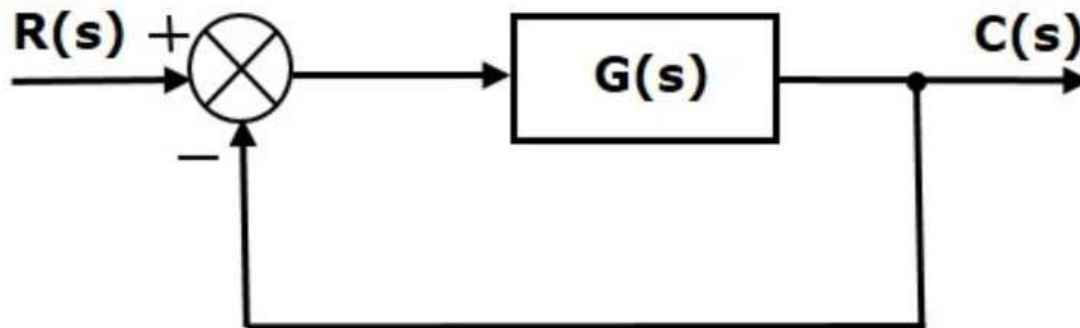
- The deviation of the output of control system from desired response during steady state is known as steady state error.
- It is represented as e_{ss}
- steady state error can find using the final value theorem as follows.

$$e_{ss} = \lim_{t \rightarrow \infty} e(t) = \lim_{s \rightarrow 0} sE(s)$$

where,

- $E(s)$ is the Laplace transform of the error signal, $e(t)$

Steady State Errors for Unity Feedback Systems





Steady State error

- The transfer function of the unity negative feedback closed loop control system as

$$E(s) = \frac{R(s)}{1 + G(s)}$$

Input signal	Steady state error e_{ss}	Error constant
unit step signal	$\frac{1}{1+k_p}$	$K_p = \lim_{s \rightarrow 0} G(s)$
unit ramp signal	$\frac{1}{K_v}$	$K_v = \lim_{s \rightarrow 0} sG(s)$
unit parabolic signal	$\frac{1}{K_a}$	$K_a = \lim_{s \rightarrow 0} s^2 G(s)$

- where, K_p , K_v and K_a are position error constant, velocity error constant and acceleration error constant respectively.



Steady State error

<u>Type 0 system</u>	<i>Step Input</i>	<i>Ramp Input</i>	<i>Parabolic Input</i>
<i>Steady-State Error Formula</i>	$1/(1+K_p)$	$1/K_v$	$1/K_a$
<i>Static Error Constant</i>	$K_p = \text{constant}$	$K_v = 0$	$K_a = 0$
<i>Error</i>	$1/(1+K_p)$	Infinity	infinity

<u>Type 1 system</u>	<i>Step Input</i>	<i>Ramp Input</i>	<i>Parabolic Input</i>
<i>Steady-State Error Formula</i>	$1/(1+K_p)$	$1/K_v$	$1/K_a$
<i>Static Error Constant</i>	$K_p = \text{infinity}$	$K_v = \text{constant}$	$K_a = 0$
<i>Error</i>	0	$1/K_v$	infinity

<u>Type 2 system</u>	<i>Step Input</i>	<i>Ramp Input</i>	<i>Parabolic Input</i>
<i>Steady-State Error Formula</i>	$1/(1+K_p)$	$1/K_v$	$1/K_a$
<i>Static Error Constant</i>	$K_p = \text{infinity}$	$K_v = \text{infinity}$	$K_a = \text{constant}$
<i>Error</i>	0	0	$1/K_a$



Thank You