

### **SNS COLLEGE OF TECHNOLOGY An Autonomous Institution Coimbatore-35**

Accredited by NBA – AICTE and Accredited by NAAC – UGC with 'A++' Grade Approved by AICTE, New Delhi & Affiliated to Anna University, Chennai

## **DEPARTMENT OF ELECTRONICS & COMMUNICATION ENGINEERING**

# **23ECT202 – SIGNALS AND SYSTEMS**

II YEAR/ III SEMESTER

### **UNIT 3 – LTI CONTINUOUS TIME SYSTEMS**

### **TOPIC – LTI SYSTEMS USING FOURIER TRANSFORM**

LTI SYSTEMS USING FT/23ECT202 – SIGNALS AND SYSTEMS/J.Prabakaran/ECE/SNSCT

07/10/2024





### LTI SYSTEM

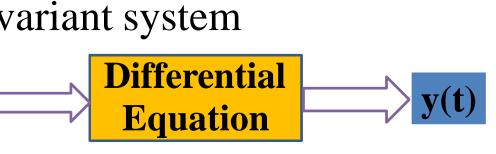
- Linear Time Invariant Systems (LTI) are characterized with the help of
- 1. Differential Equation
- 2. Impulse Response
- 3. Block Diagrams
- 4. State Variable description
- 5. Transfer Functions

#### **Differential Equation :**

- It is used to represent continuous time linear time invariant system
- It relates the input and output of the system









#### LTI SYSTEM

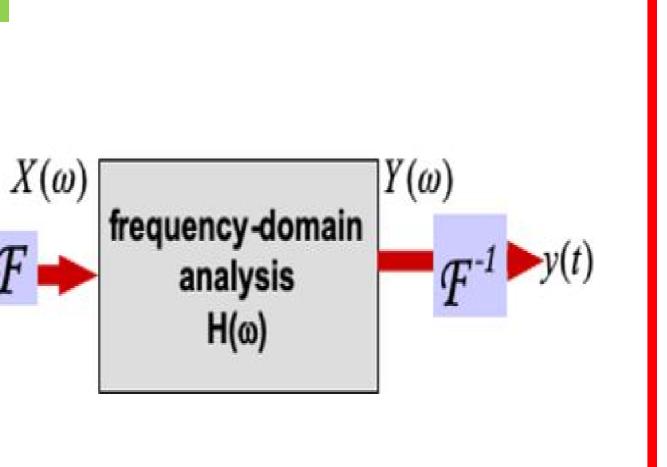
• System Transfer Function: Ratio of the output to the input.

$$\mathbf{H(s)} = \frac{Y(s)}{X(s)}$$

• Frequency Response:

$$\mathbf{H}(\boldsymbol{\omega}) = \frac{Y(\boldsymbol{\omega})}{X(\boldsymbol{\omega})} \qquad x(t) \bullet$$





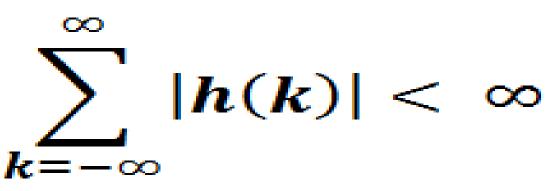


#### LTI SYSTEM

• Condition for an Linear Time Invariant (LTI) system to be causal:

$$h(t) = 0, t < 0$$

• Condition for an Linear Time Invariant (LTI) system to be stable:













• Impulse response is the output generated by the system, when an unit impulse is applied at the input.

 $x(t) = \delta(t) \longrightarrow LTI System \longrightarrow y(t) = h(t)$ 

 $\delta(t)$ •  $H(s) = \frac{Y(s)}{X(s)}$ 0 •  $h(t) = L^{-1} \{H(s)\}$ 

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#### $\delta$ (t) = 1 for t = 0 = 0 for $t \neq 0$



### FOURIER TRANSFORM

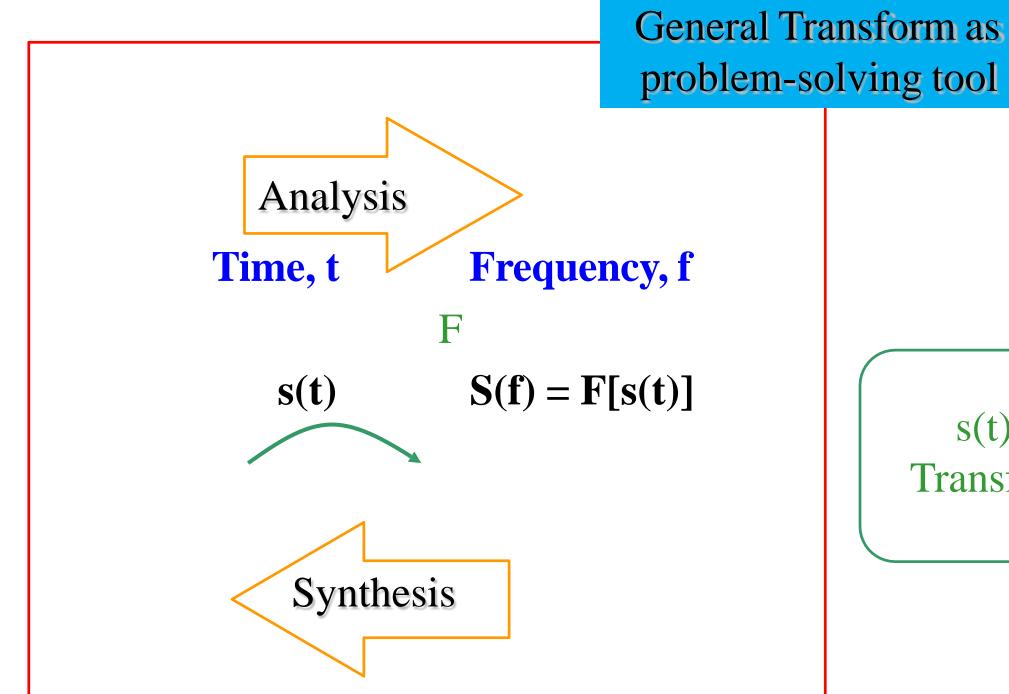
- Fourier transform can be applied for both periodic and non periodic signals
- It can be represented in frequency domain
- It provides effective reversible transformation link between frequency domain and time domain representation of the signal
- The spacing between spectral components becomes infinitesimal and hence the frequency spectrum appears to be continuous
- Periodic signals has fixed period To







#### FOURIER TRANSFORM



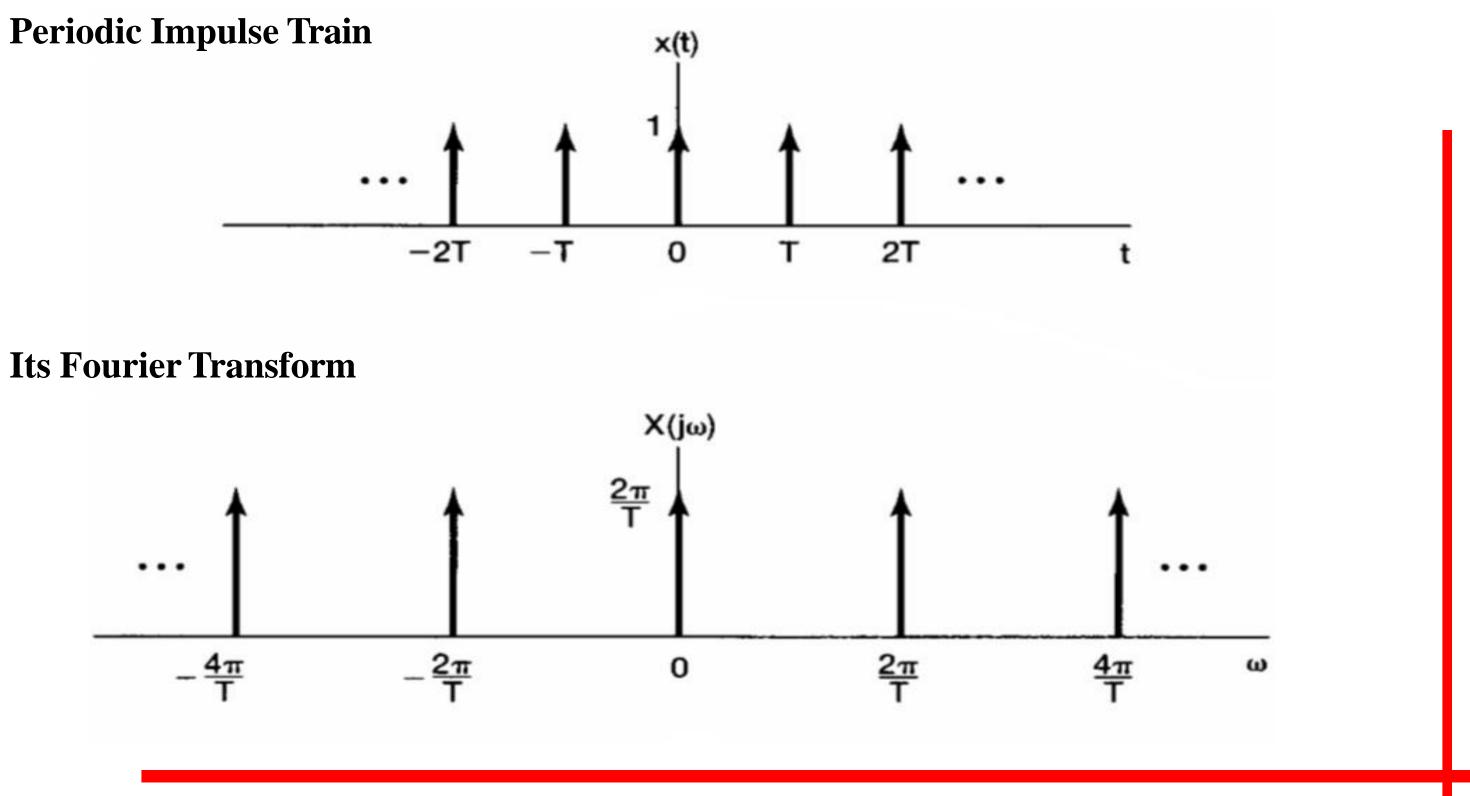




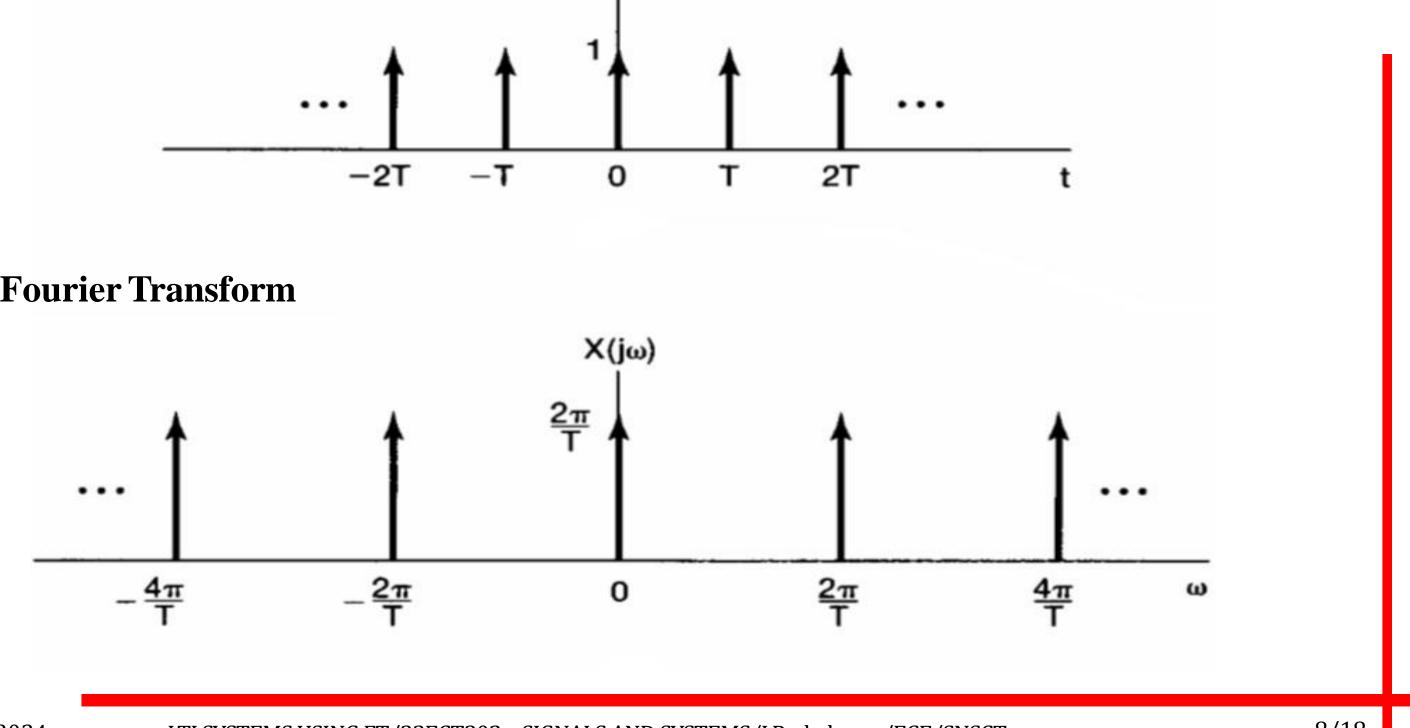
#### s(t), S(f):**Transform Pair**



#### **REPRESENTATION OF FT**



**Its Fourier Transform** 



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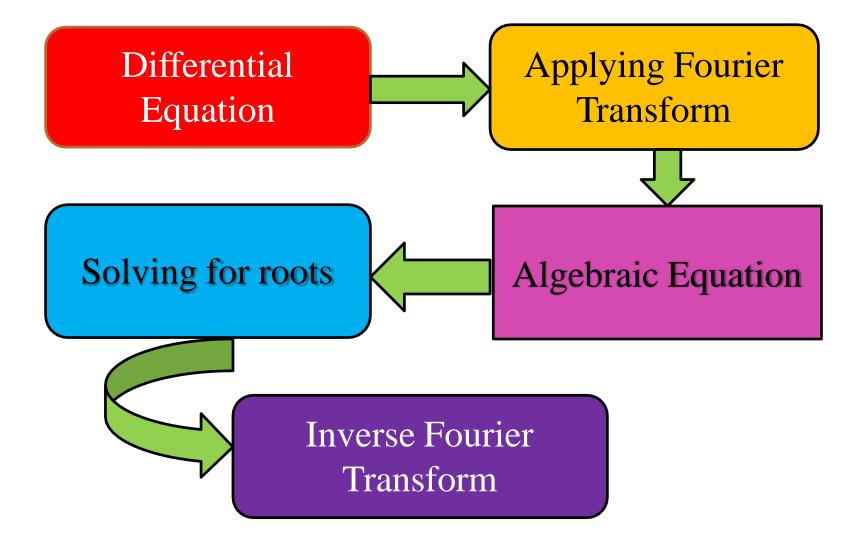
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#### **TO FIND IMPULSE RESPONSE**

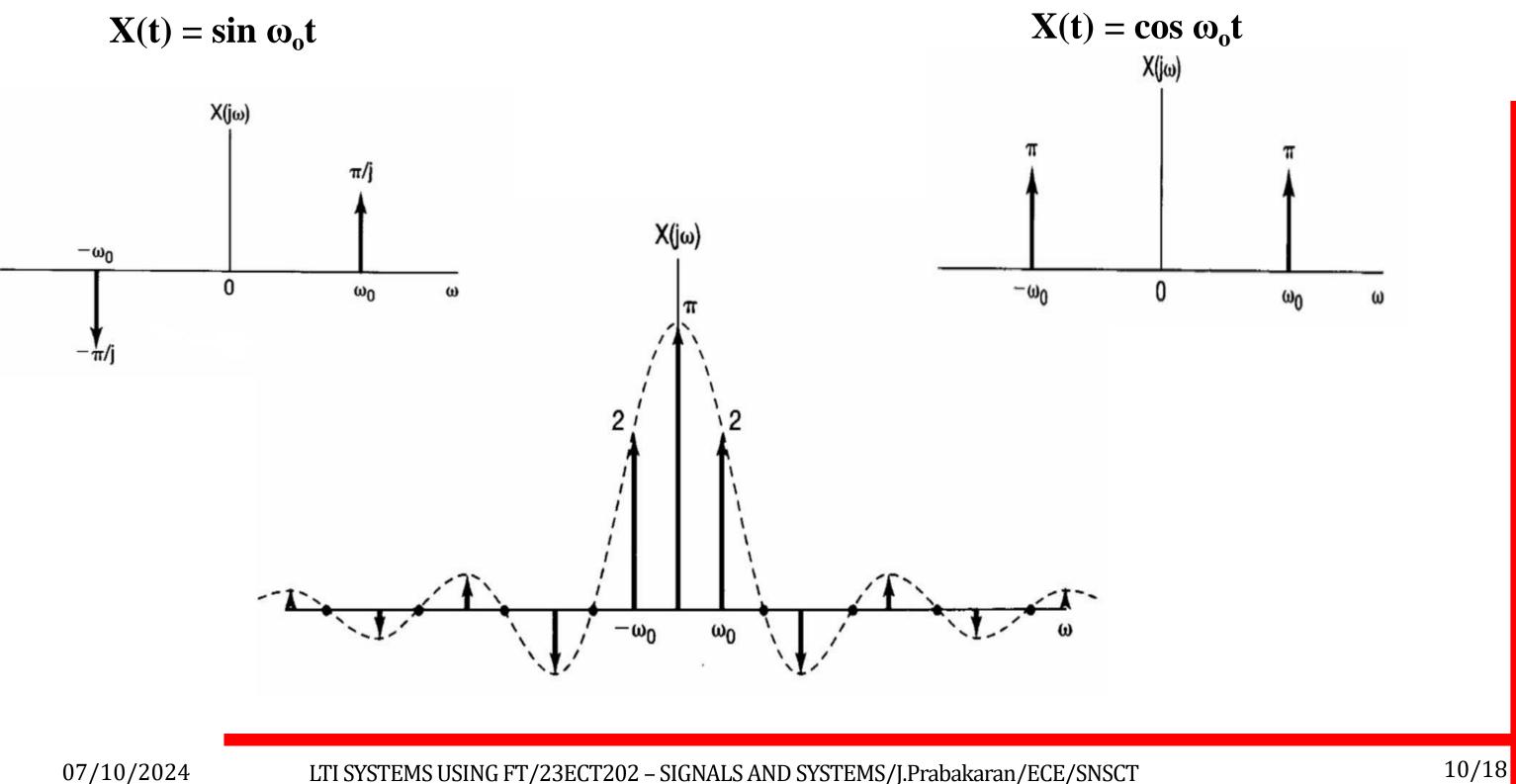








### PERIODIC SYMMETRIC SQUARE WAVE







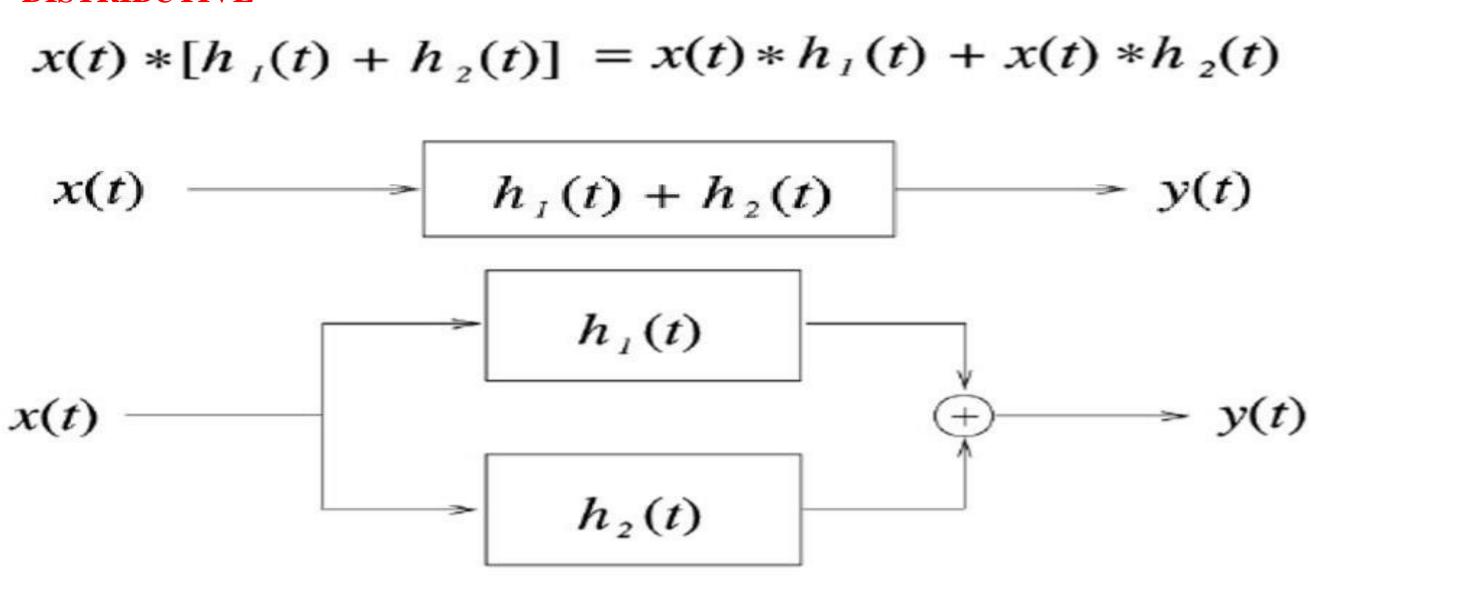


#### **PROPERTIES OF CONVOLUTION INTEGRAL**

COMMUTATIVE

$$x(t) * h(t) = h(t) * :$$

**DISTRIBUTIVE** 



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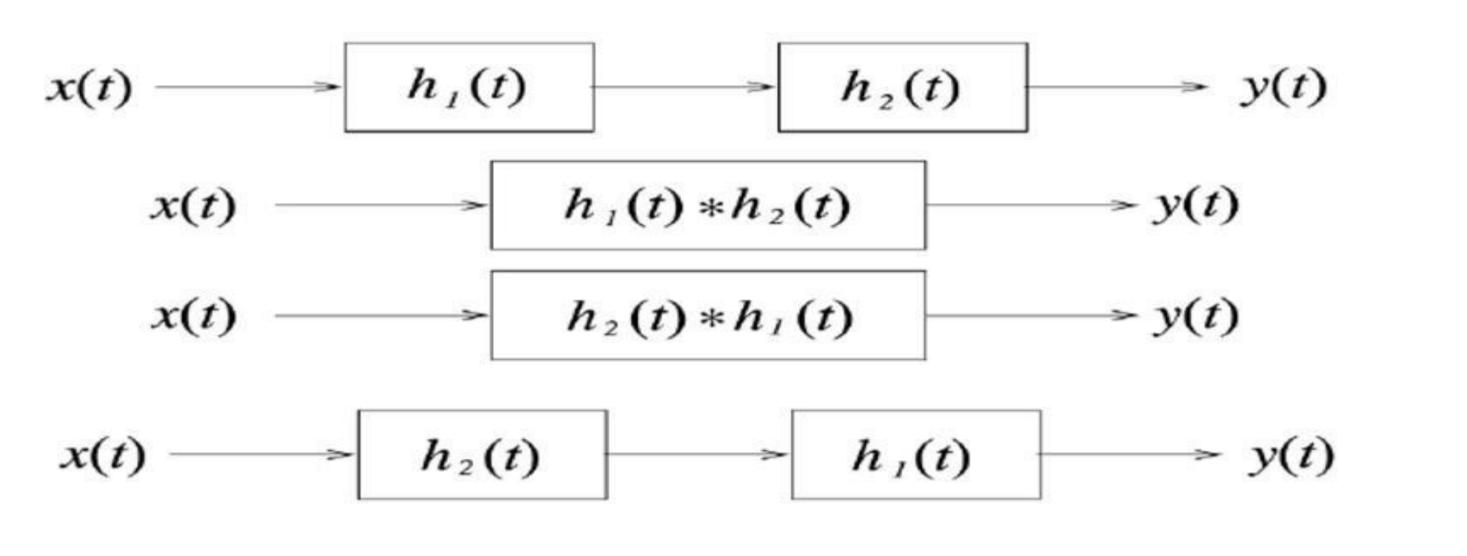


x(t)



#### **ASSOCIATIVE PROPERTY**

$$[x(t) * h_{1}(t)] * h_{2}(t) = x(t) * |$$
  
[x(t) \* h\_{2}(t)] \* h\_{1}(t) = x(t) \* [



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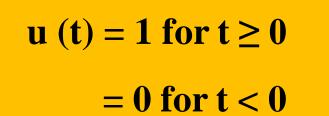


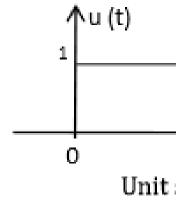


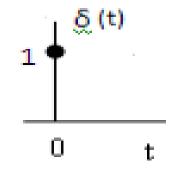
### $[h_1(t) * h_2(t)]$ $[h_2(t) * h_1(t)]$



#### **BASIC SIGNALS**

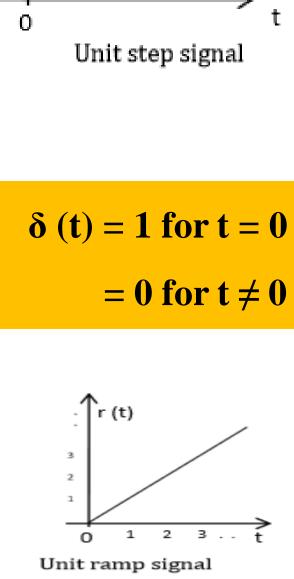


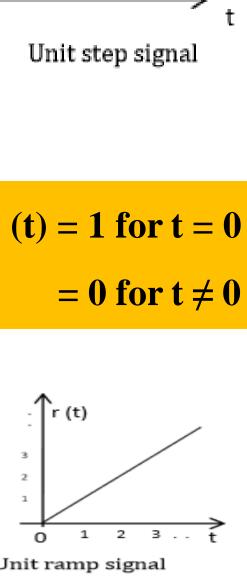




Unit Impulse signal

$$\mathbf{r}\left(t\right) = t \text{ for } t \ge 0$$





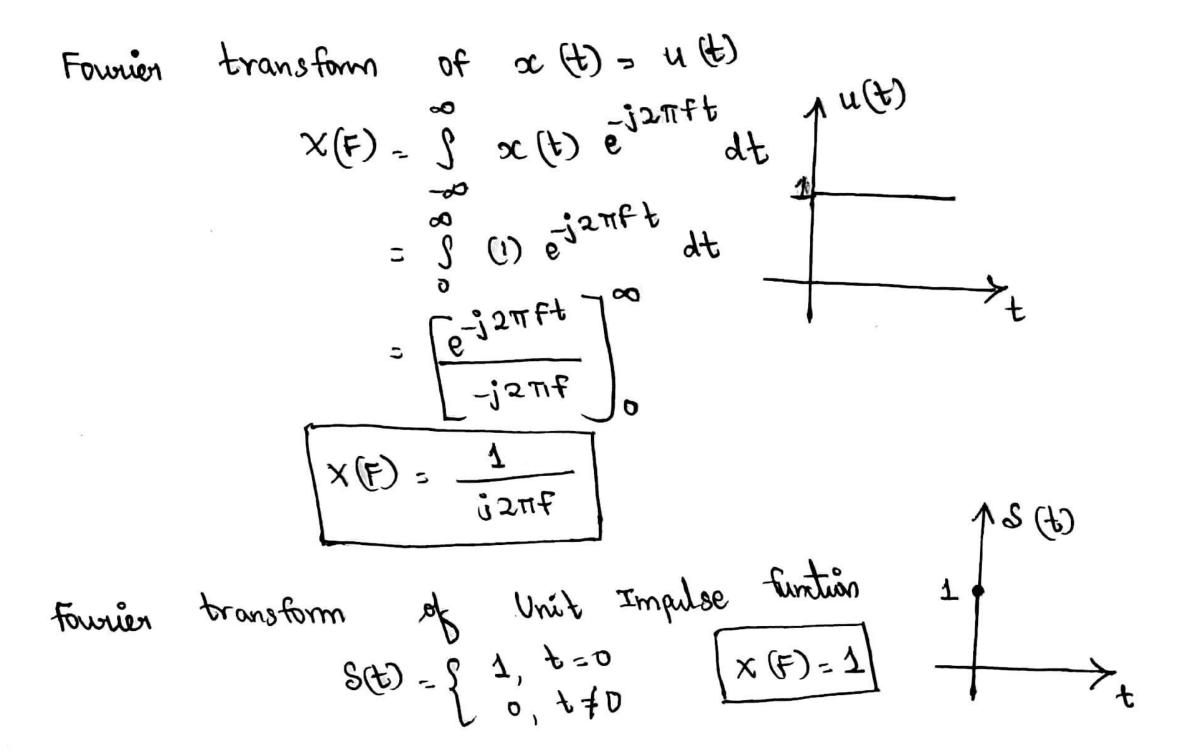
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### FOURIER TRANSFORM RESULTS



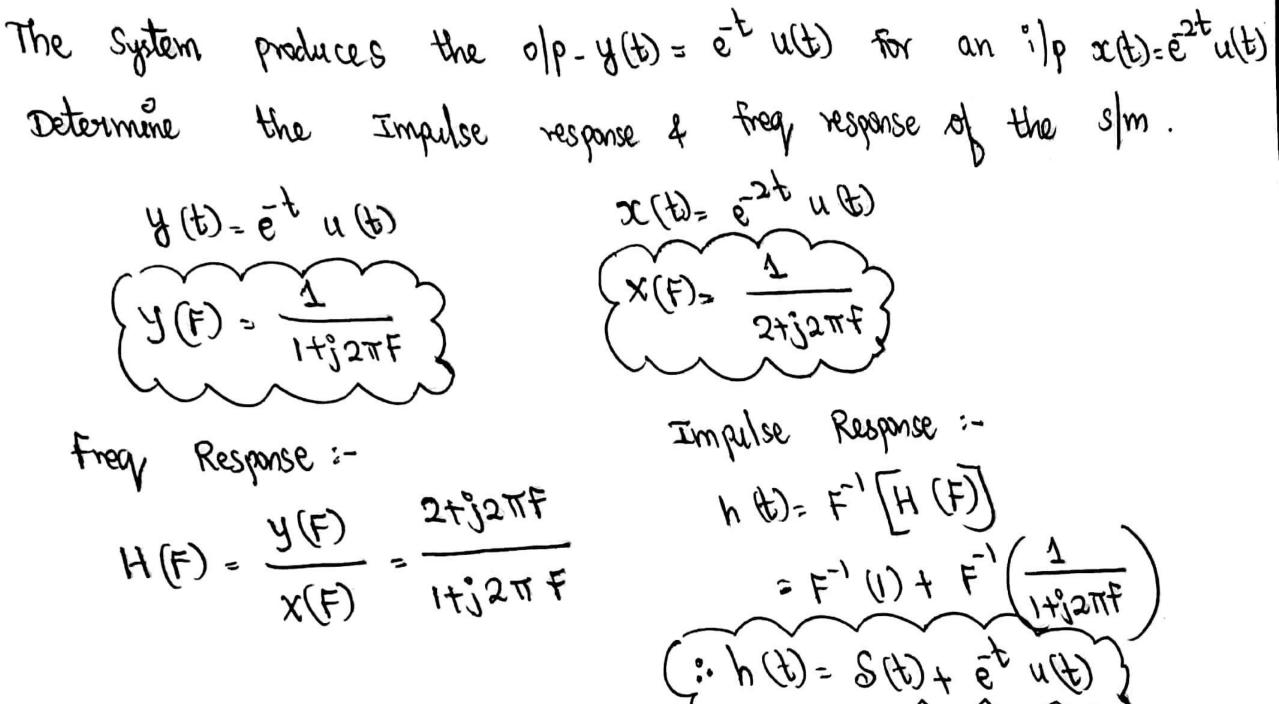


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#### FOURIER TRANSFORM RESULTS



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NSMIUTIONS freq response of the sm. h t)= F' [H (F)] = F-) (1) + F 1+12777  $h(t) = S(t) + \tilde{e}^{t}$ 



#### FOURIER TRANSFORM RESULTS

Diff Equation of the system is given as The  $\frac{d^2}{dt^2} \mathcal{Y}(t) + 5 \frac{d}{dt} \mathcal{Y}(t) + 6 \mathcal{Y}(t) = -\frac{d}{dt} \mathbf{x}(t)$ senoquere porte inmine By taking Jourier transform  $(j\omega)^2 \quad \gamma(\omega) + 5 j\omega \gamma(\omega) + 6 \gamma(\omega) = (-j\omega) \times (\omega)$  $\gamma(\omega) \int (j\omega)^2 + 5j\omega + b \int = -j\omega x(\omega)$  $: H(w) = \frac{\gamma(w)}{\chi(w)} = \frac{-jw}{(jw)^2 + jw} + b$ 

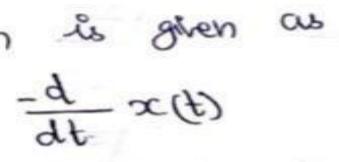
$$H(w) = \frac{-jw}{(jw+2)(jw+3)}$$

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### ASSESSMENT

- 1. The system transfer function is given by ------
- 2. ----- relates the input and output of the system.
- 3. What is meant by impulse response?
- 4. Define Unit step and Unit Impulse Signal.
- 5. The condition of an LTI system to be causal is given by ------
- 6. Fourier transform of Unit step function is given by ------
- The condition of stability of an LTI system is ------7.
- 8. LTI Systems are characterized with the help of ------







## THANK YOU

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