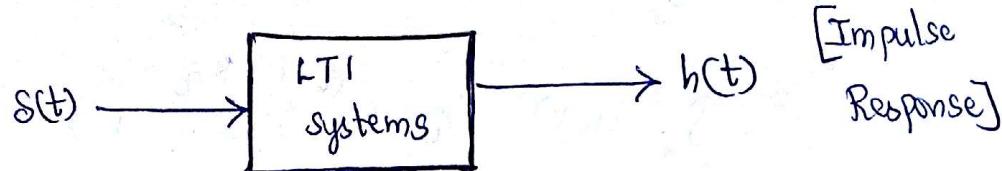


# UNIT - III

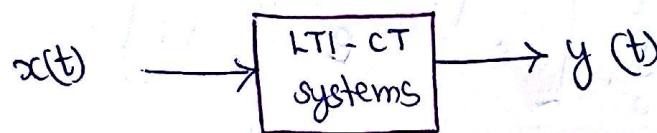
## LTI - CONTINUOUS TIME SYSTEMS

Impulse Response :-



Impulse response is the o/p generated by the system when unit impulse is applied at the Input.

convolution integral :- Output of an LTI CT system :-



$$y(t) = T[x(t)]$$

$x(t)$  can be represented in terms of impulses as

$$x(t) = \int_{-\infty}^{\infty} x(\tau) \delta(t-\tau) d\tau$$

$$y(t) = T \left[ \int_{-\infty}^{\infty} x(\tau) \delta(t-\tau) d\tau \right]$$

$$= \int_{-\infty}^{\infty} x(\tau) T[\delta(t-\tau)] d\tau$$

Relation between

$$\therefore y(t) = \int_{-\infty}^{\infty} x(\tau) h(t-\tau) d\tau$$

I/p and o/p

$$y(t) = x(t) * h(t)$$

of the  
system

By using convolution Integral obtain the response of the system two unit step input signals :-

$$h(t) = \frac{R}{L} e^{-t R/L} u(t), \quad x(t) = u(t)$$

$$y(t) = \int_{-\infty}^{\infty} x(\tau) h(t-\tau) d\tau$$

$$= \int_{-\infty}^{\infty} u(\tau) \frac{R}{L} e^{-(t-\tau) R/L} u(t-\tau) d\tau$$

$$= \int_0^t \frac{R}{L} e^{-(t-\tau) R/L} d\tau$$

$$= \int_0^t \frac{R}{L} e^{-(t-\tau) R/L} d\tau$$

$$= \frac{R}{L} \int_0^t \left[ e^{-t R/L} e^{\tau R/L} d\tau \right]$$

$$= \frac{R}{L} e^{-t R/L} \int_0^t e^{\tau R/L} d\tau$$

$$= \frac{R}{L} e^{-t R/L} \left[ \frac{e^{\tau R/L}}{R/L} \right]_0^t$$

$$= \frac{R}{L} e^{-t R/L} \left[ \frac{e^{t R/L}}{R/L} - \frac{1}{R/L} \right]$$

$$y(t) = 1 - e^{-t R/L}$$

Properties of convolution Integral :-

i) commutative property :-

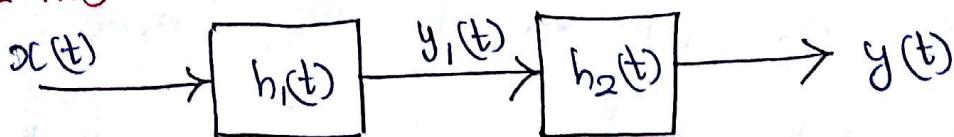
$$y(t) = x(t) * h(t) = h(t) * x(t)$$

$$= \int_{-\infty}^{\infty} x(\tau) h(t-\tau) d\tau = \int_{-\infty}^{\infty} h(\tau) x(t-\tau) d\tau$$

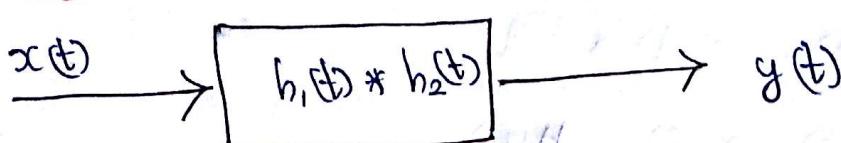
2) Associative Property :-

$$[x(t) * h_1(t)] * h_2(t) = x(t) * [h_1(t) * h_2(t)]$$

L.H.S



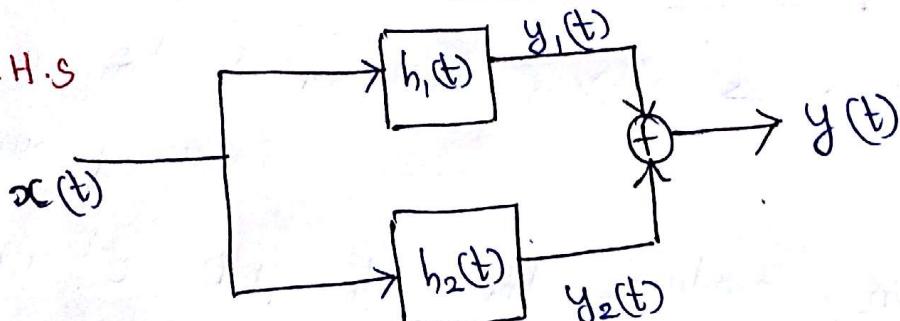
R.H.S



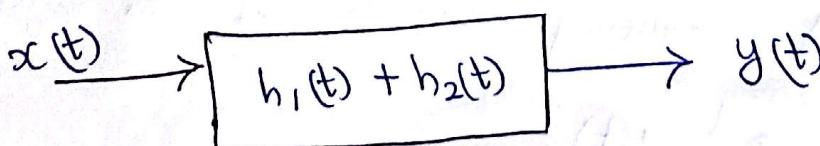
3) Distributive property :-

$$x(t) * h_1(t) + x(t) * h_2(t) = x(t) * [h_1(t) + h_2(t)]$$

L.H.S



R.H.S



Condition for an LTI system to be causal :-

$$h(t) = 0, \text{ for } t < 0$$

Condition for an LTI system to be stable :-

$$\int_{-\infty}^{\infty} |h(t)| dt < \infty$$