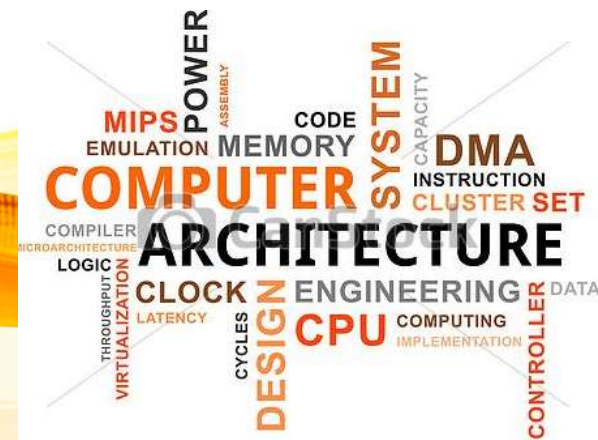


UNIT V

I/O ORGANIZATION AND PARALLELISM

Accessing I/O devices – Interrupts – Direct Memory Access - Buses–
Interface circuits - Standard I/O Interfaces (PCI, SCSI, USB)–Instruction
Level Parallelism : Concepts and Challenges – **Introduction to multicore
processor** - Graphics Processing Unit.



Recap the previous Class





Introduction

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Multi-Core Processor:

- A processing system composed of two or more independent cores or CPUs.
- The cores are typically integrated onto a single integrated circuit die, or they may be integrated on multiple dies in a single chip package

Cores share memory:

- In modern multi-core systems, typically the L1 and L2 cache are private to each core, while the L3 cache is shared among the cores.
- In symmetric multi-core systems, all the cores are identical.
 - Example: multi-core processors used in computer systems.
- In asymmetric multi-core systems, the cores may have different functionalities.

Why multi-core?

- It is difficult to sustain Moore's law and at the same time meet performance demands of various applications.
- Difficult to increase clock frequency, mainly due to power consumption issues.

Possible Solution:

- Replicate hardware and run them at a lower clock rate to reduce power consumption.
- 1 core running at 3 GHz has the same performance as 2 cores running at 1.5 GHz, with lower power consumption.



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Taxonomy of Parallel Architectures^{5/17}

- Single instruction-stream single data-stream
 - Traditional uniprocessor systems.
- Multiple instruction-stream single data-stream
 - No commercial implementation exists.
 - Pipelining can be argued as a type of MISD
- Single instruction-stream multiple data-stream (SIMD)
 - Array and vector processors.
- Multiple instruction-stream multiple data-stream
 - Multiprocessor systems (various architectures

Single-core Computer

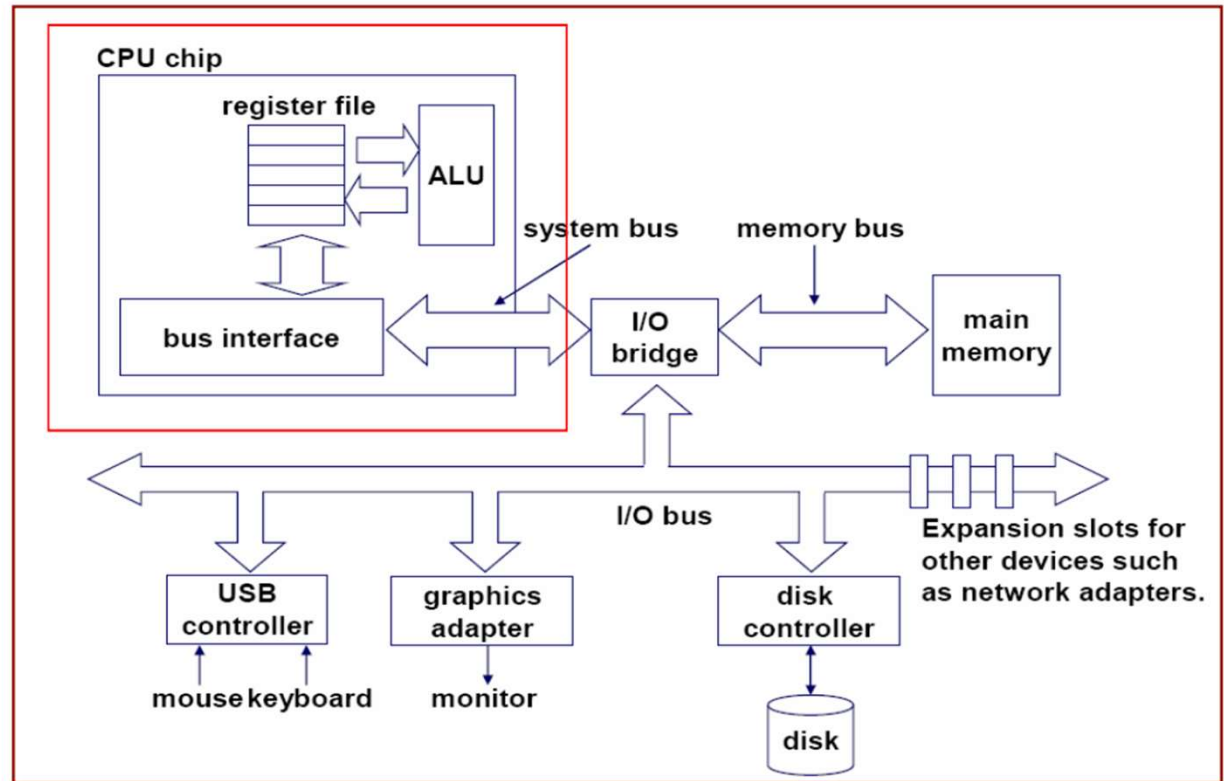
Falls under SISD category.

•Typically two buses:

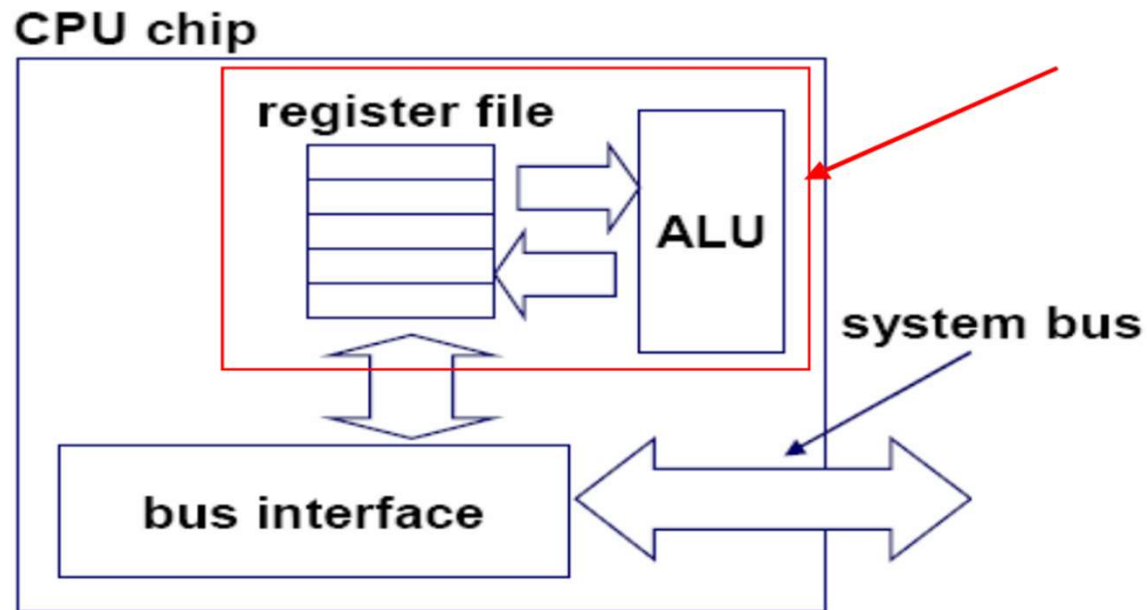
a)A high-speed CPU- memory bus, that also

connects to I/O bridge.

b)A lower-speed I/O bus, connecting various peripherals.



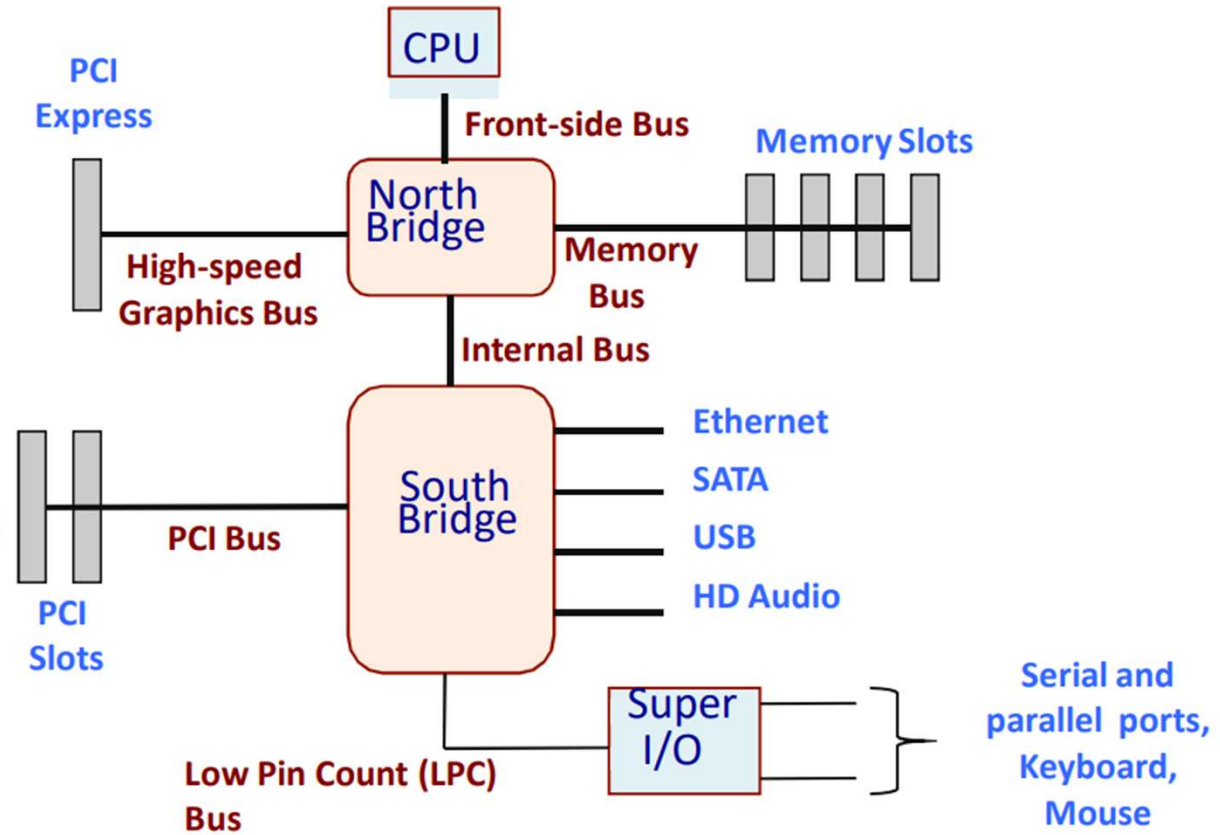
Single-core Computer





Typical mother board architecture:

• Chipset consisting of north bridge and south bridge

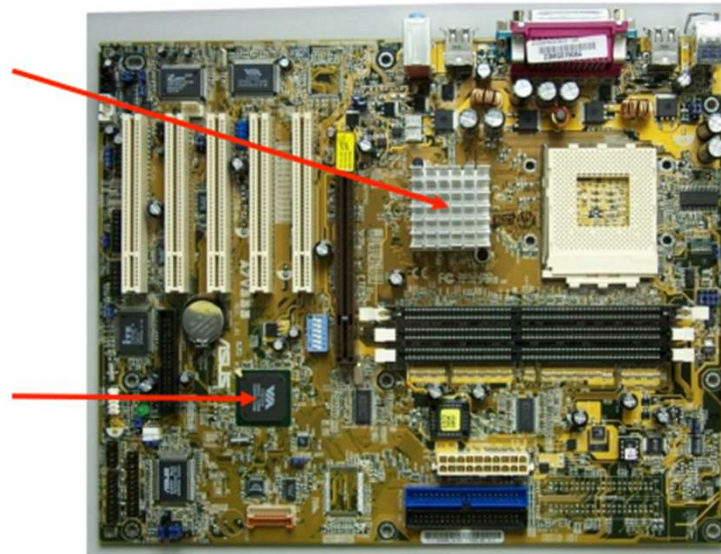


Locating North Bridge and South Bridge Chipset on Motherboard

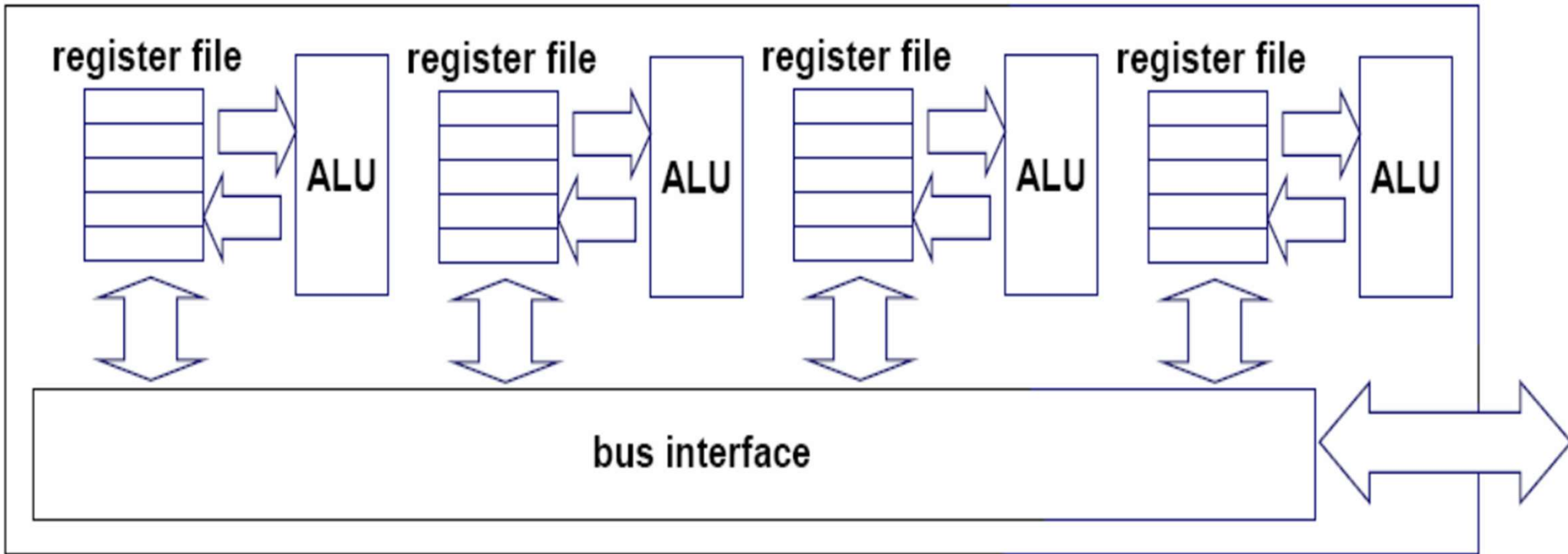
- Bus speeds and other capabilities depend upon the chipset.

**North
Bridge**

**South
Bridge**



Multi-core Architecture





Can be broadly classified into two types:

Tightly coupled multiprocessors

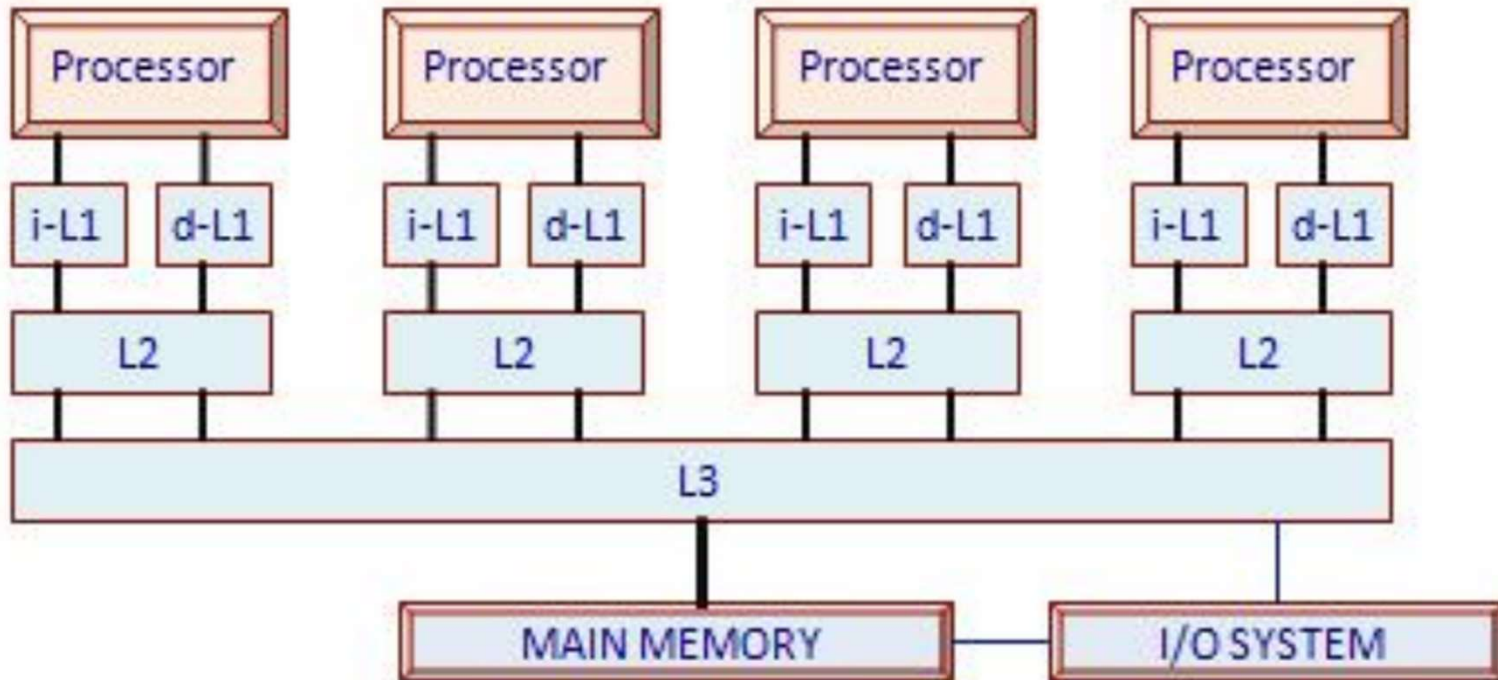
- The processors access common shared memory.
- Inter-processor communication takes place through shared memory.
- Multi-core architectures fall under this category.

Loosely coupled multiprocessors

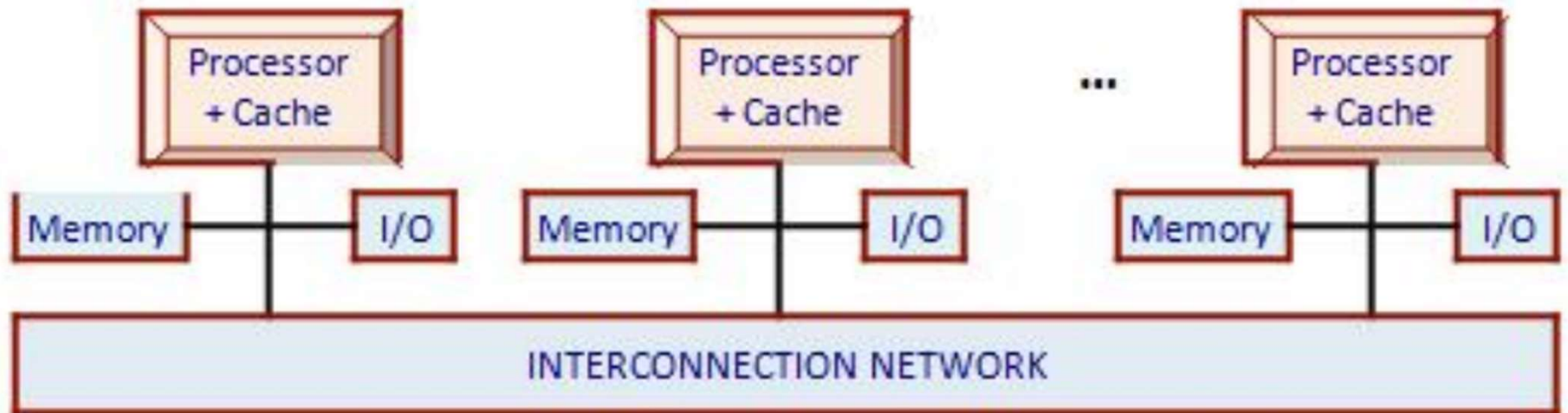
- Memory is distributed among the processors.
- Processors typically communicate through a high network.



(a) Tightly Coupled Multiprocessors



(b) Loosely Coupled Multiprocessors



Some features:

- Cost-effective way to scale memory bandwidth.
- Communicating data between processors is complex and has higher latency.
- Memory access time depends on the location of data.
 - Called Non Uniform Memory Access – NUMA.



Cache Coherency Problem in Multiprocessors

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Maintaining coherence between data loaded in processor caches is an issue in multiprocessor systems.

- Same memory block is loaded into two processor caches.
- One of the processors updates the data in its local cache.
- Data in the other processor cache and also memory becomes inconsistent.

Broadly two classes of techniques are used to solve this problem:

- Snoopy protocols
- Directory-based protocols

Some features:

- Difficult to extend it to large number of processors
- Memory bandwidth requirements increase with the number of processors.
- Memory access time for all processors is uniform.
- Called Uniform Memory Access – UMA

TEXT BOOK

Carl Hamacher, Zvonko Vranesic and Safwat Zaky, “Computer Organization”, McGraw-Hill, 6th Edition 2012.

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3. John P.Hayes, “Computer Architecture and Organization”, McGraw Hill, 3rd Edition, 2002
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THANK YOU