



BLOCK DIAGRAM REPRESENTATION :-

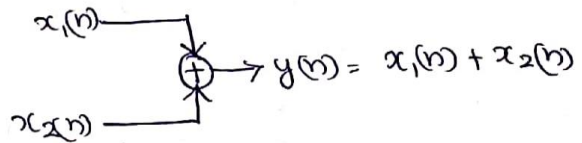
The discrete time systems are represented by block diagram these are also called as DT systems.

Summary of elementary blocks used to represent DT s/ms :-

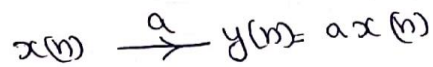
Name of the block

Symbols .

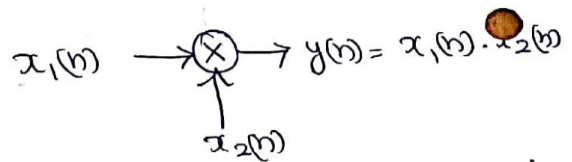
1. Adder



2. constant Multiplier



3. signal Multiplier



4. Delay element



5. Advancing element



1) obtain the DF-I and DF-II realisation of the system described by the differential Equation :-

$$y(n) = \frac{5}{6} y(n-1) + \frac{1}{6} y(n-2) = x(n) + 2x(n-1)$$

Taking z-transform on both sides

$$Y(z) - \frac{5}{6} z^{-1} Y(z) + \frac{1}{6} z^{-2} Y(z) = X(z) + 2z^{-1} X(z)$$

$$Y(z) \left[1 - \frac{5}{6} z^{-1} + \frac{1}{6} z^{-2} \right] = X(z) \left[1 + 2z^{-1} \right]$$

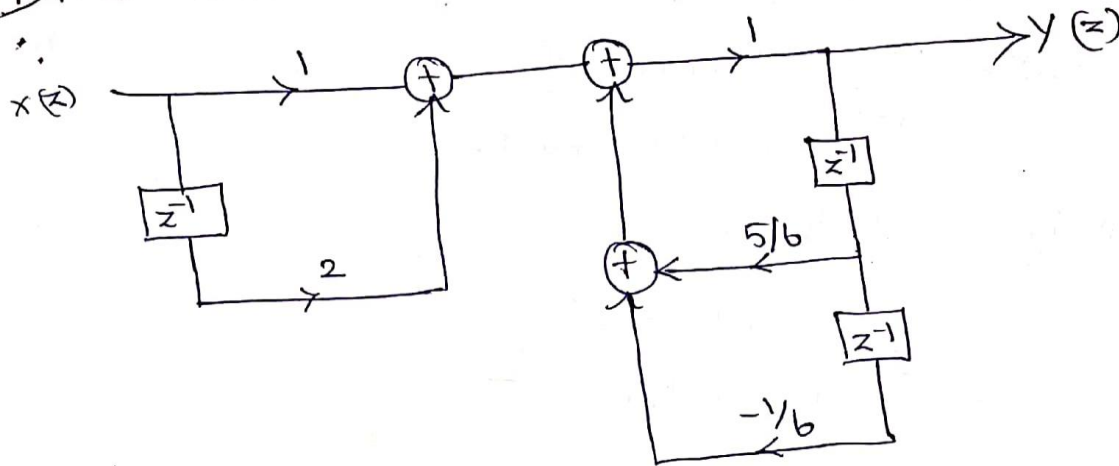
$$X(z) + 2z^{-1} X(z) = W(z) \rightarrow \textcircled{1}$$

$$Y(z) - \frac{5}{6} z^{-1} Y(z) + \frac{1}{6} z^{-2} Y(z) = W(z)$$

$$W(z) - \frac{5}{6} z^{-1} Y(z) - \frac{1}{6} z^{-2} Y(z) = Y(z) \rightarrow \textcircled{2}$$



DF-I Realisation :-



Direct Form-II

$$\frac{Y(z)}{X(z)} = \frac{1 + 2z^{-1}}{1 - \frac{5}{6}z^{-1} + \frac{1}{6}z^{-2}}$$

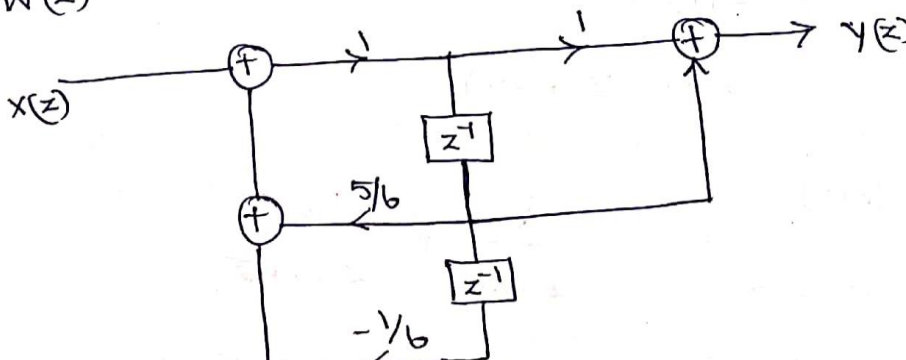
$$\frac{Y(z)}{X(z)} = \frac{Y(z)}{W(z)} \cdot \frac{W(z)}{X(z)}$$

$$\frac{W(z)}{X(z)} = \frac{1}{1 - \frac{5}{6}z^{-1} + \frac{1}{6}z^{-2}}$$

$$X(z) = W(z) - \frac{5}{6}z^{-1}W(z) + \frac{1}{6}z^{-2}W(z)$$

$$W(z) = X(z) + \frac{5}{6}z^{-1}W(z) - \frac{1}{6}z^{-2}W(z) \rightarrow (1)$$

$$\frac{Y(z)}{W(z)} = 1 + 2z^{-1} \quad W(z) + 2z^{-1}W(z) = Y(z) \rightarrow (2)$$





$$(6z+1)(z+1) = A(z-0.25) + B(z-0.5)$$

put $z=0.25$

$$3.875 = B(-0.25)$$

$$B = -15.5$$

put $z=0.5$

$$6 = A(0.25)$$

$$A = \frac{6}{0.25}$$

$$A = 24$$

$$H(z) = \frac{24}{z-0.5} - \frac{15.5}{z-0.25}$$

\downarrow $H_1(z)$ \downarrow $H_2(z)$

complete Realization :-

