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## DEPARTMENT OF AEROSPACE ENGINEERING

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### UNIT I - FUNDAMENTAL CONCEPTS

#### Initial and Boundary Conditions: Well-posed and Ill-posed Problems

In partial differential equations, it is sometimes easy to attempt a solution using incorrect or insufficient boundary and initial conditions. Whether the solution is being attempted analytically or numerically, such an "ill- posed" problem will usually lead to spurious results at best and no solution at worst. The supersonic blunt body problem discussed above is a classic example. When considering the mixed subsonic-supersonic flow from a steady flow point of view, any attempt to obtain a uniformly valid solution procedure for both regions was ill- posed.

Therefore, we define a well-posed problem as follows: If the solution to a partial differential equation exists and is unique, and if the solution depends continuously upon the initial and boundary conditions, then the problem is well- posed. In CFD, it is important that you establish that your problem is well-posed before you attempt to carry out a numerical solution. When the blunt body problem was set up using the unsteady Euler equations, and a time-marching procedure was employed to go to the steady state at large times starting with essentially arbitrary assumed initial conditions at time  $t = 0$ , the problem suddenly became well-posed.

## Chapter 3: Numerical discretization of the equations of motion

### 3.1 Classification of Partial Differential Equations – Well-Posedness – Initial and boundary conditions

#### Reminder about partial differential equations:

Second order linear partial differential equation (PDE)

$$\alpha \frac{\partial^2 u}{\partial x^2} + 2\beta \frac{\partial^2 u}{\partial x \partial y} + \gamma \frac{\partial^2 u}{\partial y^2} + \delta \frac{\partial u}{\partial x} + \varepsilon \frac{\partial u}{\partial y} + \varphi u = 0$$

Second order linear partial differential equations are classified into 3 types depending on the sign of  $\beta^2 - \alpha\gamma$  :

$$\beta^2 - \alpha\gamma > 0 \quad \text{Hyperbolic}$$

$$\beta^2 - \alpha\gamma = 0 \quad \text{Parabolic}$$

$$\beta^2 - \alpha\gamma < 0 \quad \text{Elliptic}$$

The simplest (**canonical**) examples of these equations are

$$\text{a) } \frac{\partial^2 u}{\partial t^2} = c^2 \frac{\partial^2 u}{\partial x^2} \quad \text{Wave equation (hyperbolic).}$$

Examples: vibrating string, water waves.

$$\text{b) } \frac{\partial u}{\partial t} = \sigma \frac{\partial^2 u}{\partial x^2} \quad \text{Diffusion equation (parabolic).}$$

Examples: heated rod, viscous damping.

$$\text{c) } \frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} = 0 \quad \text{Laplace's equation}$$

(elliptic)

$$\text{or } \frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} = f(x, y) \quad \text{Poisson's equation}$$

Examples: temperature of a plate, streamfunction/vorticity relationship.

The behavior of the solutions, the proper initial and/or boundary conditions, and the numerical methods that can be used to find the solutions *depend essentially on the type of PDE* that we are dealing with.

We need to study these canonical prototypes of the PDEs to develop an understanding of their properties, and then apply similar methods to the more complicated NWP equations.

Another canonical equation very important in atmospheric science is:

$$d) \frac{\partial u}{\partial t} = -c \frac{\partial u}{\partial x} \quad \text{advection equation (also hyperbolic)}$$

The advection equation has the solution  $u(x, t) = u(x - ct, 0)$ .

The advection equation is a first order PDE, but it can also be classified as a hyperbolic, since its solutions satisfy the wave equation

$$a) \frac{\partial^2 u}{\partial t^2} = c^2 \frac{\partial^2 u}{\partial x^2}$$

Conversely, a) can be written as a first order system

$$\frac{\partial \mathbf{u}}{\partial t} = \mathbf{A} \frac{\partial \mathbf{u}}{\partial x} \quad \text{where} \quad \mathbf{u} = \begin{pmatrix} \frac{\partial u}{\partial t} \\ c \frac{\partial u}{\partial x} \end{pmatrix}, \quad \text{and} \quad \mathbf{A} = \begin{bmatrix} 0 & c \\ c & 0 \end{bmatrix}$$

Example: solve the hyperbolic equation a)  $u_{tt} - c^2 u_{xx} = 0$  by transformation of variables.

Define new variables:

$$\xi = x - ct$$

$$\eta = x + ct$$

These are the **characteristics** of a this hyperbolic equation along which **signals are transmitted**.

$$u_x = u_\xi \xi_x + u_\eta \eta_x = u_\xi + u_\eta$$

$$u_t = u_\xi \xi_t + u_\eta \eta_t = -u_\xi c + u_\eta c$$

so that

$$u_{xx} = \left[ u_{\xi\xi} + 2u_{\xi\eta} + u_{\eta\eta} \right]$$

$$u_{tt} = c^2 \left[ u_{\xi\xi} - 2u_{\xi\eta} + u_{\eta\eta} \right]$$

Therefore

$$u_{tt} - c^2 u_{xx} = -4c^2 u_{\xi\eta} = 0$$

which means  $u_{\xi\eta} = \frac{\partial^2 u}{\partial \xi \partial \eta} = 0$

So, the solution of this equation may be expressed as a sum of a function of  $\xi = x - ct$  and another function of  $\eta = x + ct$  :

$$u = f(x - ct) + g(x + ct)$$

In the atmosphere we have waves (gravity waves, sound waves, even Rossby waves, propagating along characteristics with their own characteristic speed  $c$ ).

Parabolic and elliptic equations don't have characteristics

.

A *well-posed* initial/boundary condition problem has a **unique solution that depends continuously on the initial/boundary conditions**.

The specification of proper initial conditions (IC) and boundary conditions (BC) for a PDE is essential in order to have a well-posed problem.

- If **too many** IC/BC are specified, there will be **no** solution.
- If **too few** IC/BC are specified, the solution will **not be unique**.
- If the number of IC/BC is right, but they are specified at the **wrong place or time**, the solution will be **unique**, but it will not depend **smoothly** on the IC/BC.
- This means that **small errors** in the IC/BC will produce **huge errors** in the solution.
- In any of these cases we have an *ill-posed problem*.

And we can *never* find a numerical solution of a problem that is ill posed: the computer will show its disgust by “blowing up”.

We briefly discuss well posed initial / boundary conditions:

1) Elliptic equations, e.g.: 
$$\frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} = f(x, y)$$

2<sup>nd</sup> order elliptic equations require **one boundary condition on each point of the spatial boundary**.

These are “boundary value”, **time-independent problems**, and the methods used to solve them are introduced in Section 3.4.

The boundary conditions for elliptic equations may be:

- on the value of the function (**Dirichlet** problem), as when we specify the temperature  $u = T$  at the borders of a plate, or
- on its normal derivative (**Neumann** problem), as when we specify the heat flux, e.g., no flux  $\frac{\partial u}{\partial x} = 0$ .
- We could also have a mixed “**Robin**” boundary condition, involving a linear combination of the function and its derivative, as when we specify the flux depending on the temperature  $\frac{\partial u}{\partial x} = C(u - T) \therefore$

2) Linear parabolic equations ( $\frac{\partial u}{\partial t} = \sigma \frac{\partial^2 u}{\partial x^2}$ ) require **one initial condition** at the initial time and **one boundary condition** at each point of the spatial boundaries (if they exist). The spatial BC are similar as for elliptic equations but they depend on time.

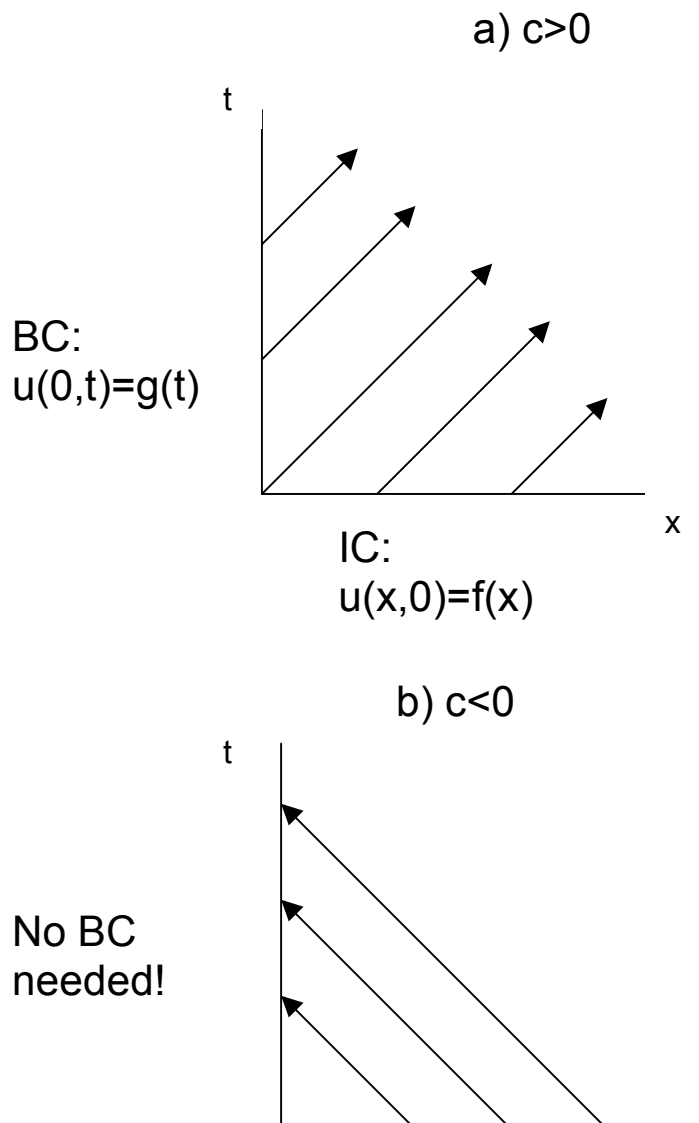
For example, for a heated rod, we need the initial temperature  $T(x,0)$  and the temperature at each end  $T(0,t)$ ,  $T(L,t)$  as a function of time.

3) Linear hyperbolic equations ( $\frac{\partial^2 u}{\partial t^2} = c^2 \frac{\partial^2 u}{\partial x^2}$ ) require as many initial conditions as the number of characteristics that

come out of every point in the surface  $t=0$ , and as many boundary conditions as the number of characteristics that cross a point in the (space) boundary pointing *inwards* (into the spatial domain).

Example: to solve  $\frac{\partial u}{\partial t} = -c \frac{\partial u}{\partial x}$  for  $x > 0, t > 0$ .

Fig. 3.1: Schematic of the characteristics of the advection equation  $\partial u / \partial t = -c \partial u / \partial x$  for positive and negative velocity  $c$  and the corresponding well posed IC/BC.





Characteristics: solutions of  $dx/dt=c$ . Space boundary:  $x=0$ . (see schematic Fig. 3.1a,b). If  $c>0$ , we need IC:  $u(x,0)=f(x)$ ; BC:  $u(0,t)=g(t)$ . If  $c<0$ , we need IC:  $u(x,0)=f(x)$  but *no BC!*

For nonlinear equations, no general statements can be made, but physical insight and local linearization can help to determine proper IC/BC.

For example, in the nonlinear advection equation

$\frac{\partial u}{\partial t} = -u \frac{\partial u}{\partial x}$ , the characteristics are  $dx/dt=u$ , and since we don't know a priori the sign of  $u$  at the boundary, and whether the characteristics will point inwards or outwards, we have to estimate the value of  $u$  from the nearby solution, and define the BC accordingly.

One method to solve simple PDE's is the method of separation of variables, but unfortunately in most cases it is not possible to use it (hence the need for numerical models!). Nevertheless, it is useful to try to solve some simple PDE's analytically.

Example 1: Solve by the method of **separation of variables** these prototype PDEs:

$$\nabla^2 u = \frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} = 0 \quad 0 \leq x \leq 1, \quad 0 \leq y \leq 1,$$

subject to the BCs (data on the northern boundary)

$$u(x,0) = 0; \quad u(x,1) = A \sin m\pi x; \quad u(0,y) = u(1,y) = 0$$

Separate variables: assume the solution is a **product of a function of x and a function of y**:

$$u(x, y) = X(x) \cdot Y(y)$$

The equation becomes

$$Y \frac{d^2 X}{dx^2} + X \frac{d^2 Y}{dy^2} = 0 \quad \text{or} \quad \frac{1}{X} \frac{d^2 X}{dx^2} = -\frac{1}{Y} \frac{d^2 Y}{dy^2}$$

Since a function of x can be equal to a function of y, if and only if they are **both equal to the same constant**  $-K^2$  :

$$\frac{d^2 X}{dx^2} + K^2 X = 0 \quad \frac{d^2 Y}{dy^2} - K^2 Y = 0$$

with solutions

$$X = C_1 \sin Kx + C_2 \cos Kx \quad Y = C_3 \sinh Ky + C_4 \cosh Ky$$

The BC  $u(0, y) = 0$  forces  $C_2=0$  so that  $X = C_1 \sin Kx$  ;

the BC  $u(1, y) = 0$  forces  $\sin K = 0$  or  $K = n\pi$  ; so that  
 $X = C_1 \sin n\pi x$

The BC  $u(x, 0) = 0$  forces  $C_4=0$  so that  $Y = C_3 \sinh Kx$

The BC  $u(x, 1) = A \sin m\pi x$  forces  $n=m$  and  
 $C_1 C_3 \sinh m\pi = A$

Thus the solution is

$$u(x, y) = \frac{A}{\sinh m\pi} \sin m\pi x \sinh m\pi y$$

**More general BCs** for the elliptic equation:

Suppose that the northern boundary is now

$$u(x, 1) = f(x)$$

Find the solution. Assume we can Fourier analyze the function

$$u(x, 1) = f(x) = \sum_{k=1}^{\infty} a_k \sin k\pi x \quad \text{with} \quad \sum_{k=1}^{\infty} k^2 a_k < \infty$$

$$u(x, y) = \sum_{k=1}^{\infty} \frac{a_k}{\sinh k\pi} \sin k\pi x \sinh k\pi y$$

In the same way we can find solutions for non-vanishing boundary values on the other three edges. Thus the more general problem on a rectangular domain

$\nabla^2 u(x, y) = 0$   $u(x, y) = F(x, y)$  on the boundary, may be solved.

Another example: a **Parabolic Equation**:

$$\frac{\partial u}{\partial t} = \sigma \frac{\partial^2 u}{\partial x^2}, \quad 0 \leq x \leq 1, t \geq 0,$$

Boundary Conditions:  $u(0,t)=u(1,t)=0$ ;

Initial Conditions:  $u(x,0) = f(x) = \sum_{k=1}^{\infty} a_k \sin k\pi x$

Find the solution

$$u(x,t) = \sum_{k=1}^{\infty} a_k e^{-\sigma k^2 \pi^2 t} \sin k\pi x$$

Note that **the higher the wavenumber, the faster it goes to zero**, i.e., the solution is smoothed as time goes on.

Another example: A **Hyperbolic Equation**

$$\frac{\partial^2 u}{\partial t^2} = c^2 \frac{\partial^2 u}{\partial x^2} \quad 0 \leq x \leq 1, 0 \leq t \leq 1$$

**Boundary Conditions at the two borders:**  $u(0,t)=u(1,t)=0$

**Two Initial Conditions:**  $u(x,0) = f(x) = \sum_{k=1}^{\infty} a_k \sin k\pi x$  ;

$$\frac{\partial u}{\partial t}(x,0) = g(x) = \sum_{k=1}^{\infty} b_k \sin k\pi x$$

Find the solution by the method of separation of variables

**Another example of a hyperbolic equation:** Same as above, but now, instead of 2 initial conditions, we give an **initial** and a **“final”** condition:

$$\text{BC: } u(0,t)=u(1,t)=0$$

$$\text{IC: } u(x,0)=f(x); \text{ “final condition” } u(x,1)=g(x).$$

In other words, we try to solve a hyperbolic (wave) equation as if it were a boundary value problem.

Show that the solution is **unique** but it does not depend **smoothly** on the IC/BCs, and therefore it is **not a well-posed** problem.

**Conclusion:** Before trying to solve a problem numerically, make sure that it is well posed: it has a unique solution that depends continuously on the data that define the problem.