



## DEPARTMENT OF MATHEMATICS

14) Find the values of  $a$  and  $b$  so that the surface  $ax^3 - by^2z = (a+3)x^2$  and  $4x^2y - z^3 = 11$  may cut orthogonally at  $(2, -1, -3)$ .

Soln:

$$a = -7/3 \quad \& \quad b = 64/9$$

### DIVERGENCE OF A VECTOR POINT FUNCTION:

Let  $\vec{F}$  be any given continuously differentiable vector point function then the divergence of  $\vec{F}$  is defined as,

$$\begin{aligned} \operatorname{div} \vec{F} &= \nabla \cdot \vec{F} = \left( \vec{i} \frac{\partial}{\partial x} + \vec{j} \frac{\partial}{\partial y} + \vec{k} \frac{\partial}{\partial z} \right) \cdot \vec{F} \\ &= \vec{i} \cdot \frac{\partial \vec{F}}{\partial x} + \vec{j} \cdot \frac{\partial \vec{F}}{\partial y} + \vec{k} \cdot \frac{\partial \vec{F}}{\partial z} \end{aligned}$$

Note :

- $\nabla \cdot \vec{F}$  is a scalar point function.
- If  $\vec{F} = F_1 \vec{i} + F_2 \vec{j} + F_3 \vec{k}$  be a continuously differentiable vector point function then,

$$\operatorname{div} \vec{F} = \frac{\partial F_1}{\partial x} + \frac{\partial F_2}{\partial y} + \frac{\partial F_3}{\partial z}$$

### Solenoidal vector:

A vector  $\vec{F}$  is said to be solenoidal vector if  $\operatorname{div} \vec{F} = 0$ .

### CURL OF A VECTOR POINT FUNCTION:

Let  $\vec{F} = F_1 \vec{i} + F_2 \vec{j} + F_3 \vec{k}$  be any given continuously differentiable vector point function, the curl or rotation of  $\vec{F}$  is defined as,



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$$\begin{aligned}\text{curl } \vec{F} &= \nabla \times \vec{F} \\ &= \left( \vec{i} \frac{\partial}{\partial x} + \vec{j} \frac{\partial}{\partial y} + \vec{k} \frac{\partial}{\partial z} \right) \times \vec{F} \\ &= \vec{i} \times \frac{\partial \vec{F}}{\partial x} + \vec{j} \times \frac{\partial \vec{F}}{\partial y} + \vec{k} \times \frac{\partial \vec{F}}{\partial z} \\ &= \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ F_1 & F_2 & F_3 \end{vmatrix}\end{aligned}$$

Note:  $\nabla \times \vec{F}$  is a vector point function.

### IRROTATIONAL VECTOR:

A vector  $\vec{F}$  is said to be irrotational if

$$\nabla \times \vec{F} = 0$$

i.e.,  $\text{curl } \vec{F} = \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ F_1 & F_2 & F_3 \end{vmatrix} = 0$

### CONSERVATIVE VECTOR FIELD:

If a vector point function  $\vec{F}$  is expressible as the gradient of a scalar point function  $\phi$ , then

$\vec{F}$  is conservative i.e.,  $\vec{F}$  is conservative if  $\vec{F} = \nabla \phi$ .

Here  $\phi$  is called scalar potential.

$\vec{F}$  is conservative force if  $\text{curl } \vec{F} = 0$ .



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### PROBLEMS :

① Prove that  $\text{curl}(\nabla\phi) = 0$  (or)  $\nabla \times \nabla\phi = 0$ .

Soln:

$$\nabla = \vec{i} \frac{\partial}{\partial x} + \vec{j} \frac{\partial}{\partial y} + \vec{k} \frac{\partial}{\partial z}$$

$$\nabla\phi = \vec{i} \frac{\partial\phi}{\partial x} + \vec{j} \frac{\partial\phi}{\partial y} + \vec{k} \frac{\partial\phi}{\partial z}$$

$$\text{Curl}(\nabla\phi) = \nabla \times \nabla\phi = \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ \frac{\partial\phi}{\partial x} & \frac{\partial\phi}{\partial y} & \frac{\partial\phi}{\partial z} \end{vmatrix}$$

$$= \vec{i} \left( \frac{\partial^2\phi}{\partial y \partial z} - \frac{\partial^2\phi}{\partial y \partial z} \right) - \vec{j} \left( \frac{\partial^2\phi}{\partial x \partial z} - \frac{\partial^2\phi}{\partial x \partial z} \right) +$$

$$= 0 \quad \vec{k} \left( \frac{\partial^2\phi}{\partial x \partial y} - \frac{\partial^2\phi}{\partial x \partial y} \right)$$

② Prove that  $\text{div}(\text{curl } \vec{F}) = 0$  (or)  $\nabla \cdot (\nabla \times \vec{F}) = 0$

Soln:

$$\text{Curl } \vec{F} = \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ F_1 & F_2 & F_3 \end{vmatrix} \quad \text{if } \vec{F} = F_1\vec{i} + F_2\vec{j} + F_3\vec{k}$$

$$\nabla \times \vec{F} = \vec{i} \left( \frac{\partial F_3}{\partial y} - \frac{\partial F_2}{\partial z} \right) - \vec{j} \left( \frac{\partial F_3}{\partial x} - \frac{\partial F_1}{\partial z} \right) +$$

$$\vec{k} \left( \frac{\partial F_2}{\partial x} - \frac{\partial F_1}{\partial y} \right)$$

$$\nabla \cdot \nabla \times \vec{F} = \left( \vec{i} \frac{\partial}{\partial x} + \vec{j} \frac{\partial}{\partial y} + \vec{k} \frac{\partial}{\partial z} \right) \cdot \left[ \vec{i} \left( \frac{\partial F_3}{\partial y} - \frac{\partial F_2}{\partial z} \right) - \vec{j} \left( \frac{\partial F_3}{\partial x} - \frac{\partial F_1}{\partial z} \right) + \vec{k} \left( \frac{\partial F_2}{\partial x} - \frac{\partial F_1}{\partial y} \right) \right]$$

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- ⑦ Find the constants  $a, b, c$  so that the vector  
 $\vec{F} = (x + 2y + az)\vec{i} + (bx - 3y - z)\vec{j} + (4x + cy + 2z)\vec{k}$   
 is irrotational.

Soln:

$$\nabla \times \vec{F} = \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ x+2y+az & bx-3y-z & 4x+cy+2z \end{vmatrix}$$

$$= \vec{i} \left[ \frac{\partial}{\partial y} (4x + cy + 2z) - \frac{\partial}{\partial z} (bx - 3y - z) \right]$$

$$- \vec{j} \left[ \frac{\partial}{\partial x} (4x + cy + 2z) - \frac{\partial}{\partial z} (x + 2y + az) \right]$$

$$+ \vec{k} \left[ \frac{\partial}{\partial x} (bx - 3y - z) - \frac{\partial}{\partial y} (x + 2y + az) \right]$$

$$= \vec{i} (c+1) - \vec{j} (4-a) + \vec{k} (b-2)$$

Given:  $\vec{F}$  is irrotational.

i.e.,  $\nabla \times \vec{F} = 0$ .

$$\vec{i} (c+1) - \vec{j} (4-a) + \vec{k} (b-2) = 0$$

$$c+1 = 0 \Rightarrow c = -1$$

$$4-a = 0 \Rightarrow a = 4$$

$$b-2 = 0 \Rightarrow b = 2$$

- ⑧ Find 'a' so that the vector

$$\vec{A} = (ax^2 - y^2 + x)\vec{i} - (2xy + y)\vec{j}$$
 is irrotational.

Soln:

Given:  $\vec{A}$  is irrotational.

$$\nabla \times \vec{A} = 0$$



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$$\nabla \times \vec{A} = \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ \partial/\partial x & \partial/\partial y & \partial/\partial z \\ ax^2 - y^2 + x & -(2xy + y) & 0 \end{vmatrix}$$

$$= \vec{i}(0) - \vec{j}(0) + \vec{k}(-2y + 2y) = 0.$$

$\therefore 'a'$  is arbitrary.

- ⑨ Prove  $\vec{F} = (y^2 \cos x + z^3) \vec{i} + (2y \sin x - 4) \vec{j} + 3xz^2 \vec{k}$  is irrotational and find its scalar potential  $\phi$  such that  $\vec{F} = \nabla \phi$ .

Soln:

$$\nabla \times \vec{F} = \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ \partial/\partial x & \partial/\partial y & \partial/\partial z \\ y^2 \cos x + z^3 & 2y \sin x - 4 & 3xz^2 \end{vmatrix}$$

$$= \vec{i} \left[ \frac{\partial}{\partial y} (3xz^2) - \frac{\partial}{\partial z} (2y \sin x - 4) \right]$$

$$- \vec{j} \left[ \frac{\partial}{\partial x} (3xz^2) - \frac{\partial}{\partial z} (y^2 \cos x + z^3) \right]$$

$$+ \vec{k} \left[ \frac{\partial}{\partial x} (2y \sin x - 4) - \frac{\partial}{\partial y} (y^2 \cos x + z^3) \right]$$

$$= 0\vec{i} + 0\vec{j} + 0\vec{k}$$

$$= 0$$

$\therefore \vec{F}$  is irrotational.

To find  $\phi$ :

$$\nabla \phi = (y^2 \cos x + z^3) \vec{i} + (2y \sin x - 4) \vec{j} + 3xz^2 \vec{k}$$

$$\text{We know that } \nabla \phi = \vec{i} \frac{\partial \phi}{\partial x} + \vec{j} \frac{\partial \phi}{\partial y} + \vec{k} \frac{\partial \phi}{\partial z}$$

$$\frac{\partial \phi}{\partial x} = y^2 \cos x + z^3 \Rightarrow \phi = y^2 \sin x + z^3 x + f(y, z)$$

$$\frac{\partial \phi}{\partial y} = 2y \sin x - 4 \Rightarrow \phi = y^2 \sin x - 4y + f(x, z)$$

$$\frac{\partial \phi}{\partial z} = 3xz^2 \Rightarrow \phi = y^2 x z^3 + f(x, y)$$

- (10) Show that  $\vec{F} = (6xy + z^3) \vec{i} + (3x^2 - z) \vec{j} + (3xz^2 - y) \vec{k}$  is irrotational. Find  $\phi$  such that  $\vec{F} = \nabla \phi$ .

Soln:  $\phi = 3x^2y + xz^3 - yz + c$

- (11) If  $\nabla \phi = yz \vec{i} + xz \vec{j} + xy \vec{k}$  then find  $\phi$ .

Soln:  $\phi = xyz + c$

- (12) Prove that  $\text{div } \hat{r} = 2/r$ .

Soln:

$$\text{div } \hat{r} = \nabla \cdot \left( \frac{\vec{r}}{r} \right)$$

$$= \left( \frac{\partial}{\partial x} \vec{i} + \frac{\partial}{\partial y} \vec{j} + \frac{\partial}{\partial z} \vec{k} \right) \cdot \left( \frac{x\vec{i} + y\vec{j} + z\vec{k}}{r} \right)$$

$$= \frac{\partial}{\partial x} \left( \frac{x}{r} \right) + \frac{\partial}{\partial y} \left( \frac{y}{r} \right) + \frac{\partial}{\partial z} \left( \frac{z}{r} \right)$$

$$= \frac{1}{r} - \frac{1}{r^2} \cdot x \frac{\partial r}{\partial x} + \frac{1}{r} - \frac{1}{r^2} y \frac{\partial r}{\partial y} +$$

$$\frac{1}{r} - \frac{1}{r^2} z \frac{\partial r}{\partial z}$$

$$= \frac{3}{r} - \frac{1}{r^2} \left[ x \frac{\partial r}{\partial x} + y \frac{\partial r}{\partial y} + z \frac{\partial r}{\partial z} \right]$$

Now  $r^2 = x^2 + y^2 + z^2$

$$2r \frac{\partial r}{\partial x} = 2x \Rightarrow \frac{\partial r}{\partial x} = \frac{x}{r}$$