



# What is GPS?

**GPS, which stands for Global Positioning System, is the only system today able to show you your exact position on the Earth anytime, in any weather, anywhere.**

**The three parts of GPS are:**

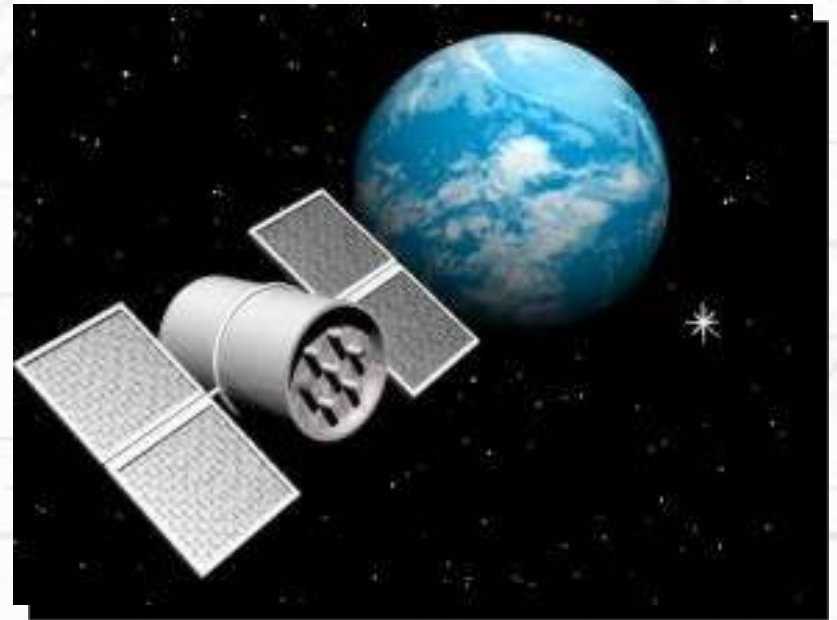
- **Satellites**
- **Receivers**
- **Software**





# Satellites

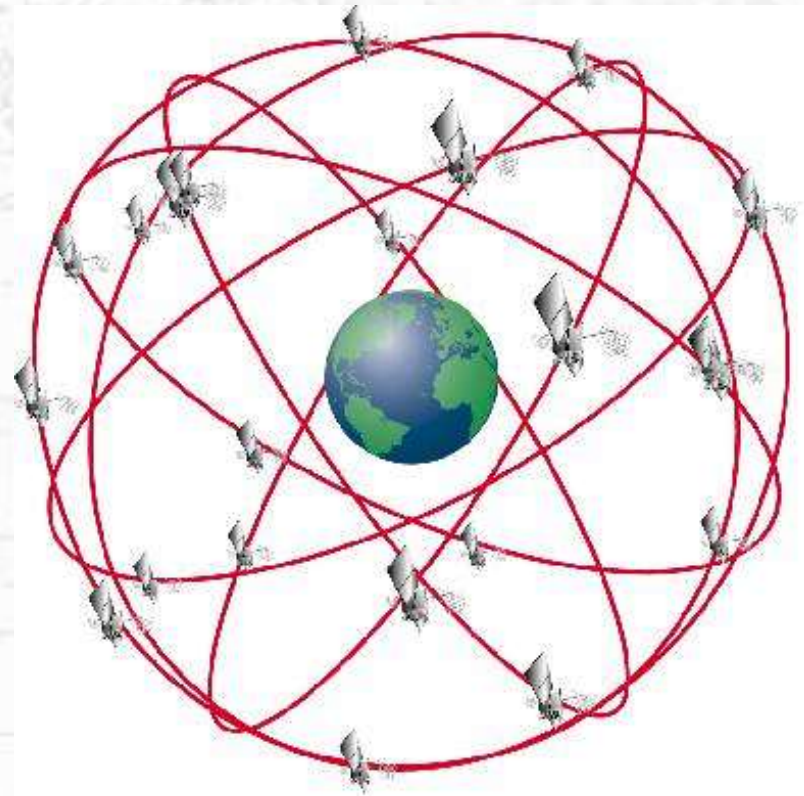
**There are quite a number of satellites out there in space. They are used for a wide range of purposes: satellite TV, cellular phones, military purposes and etc. Satellites can also be used by GPS receivers.**





# GPS Satellites

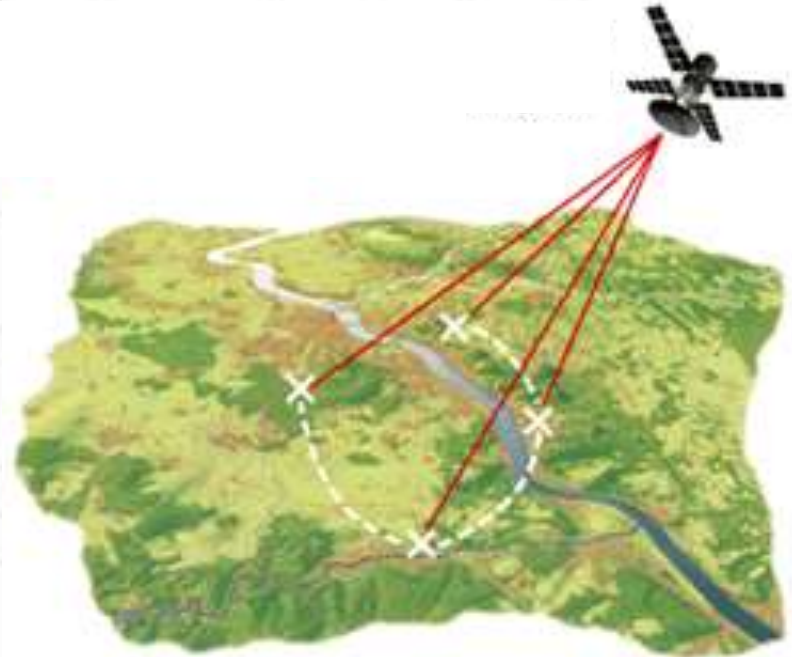
**The GPS Operational Constellation consists of 24 satellites that orbit the Earth in very precise orbits twice a day. GPS satellites emit continuous navigation signals.**





# Receivers and Satellites

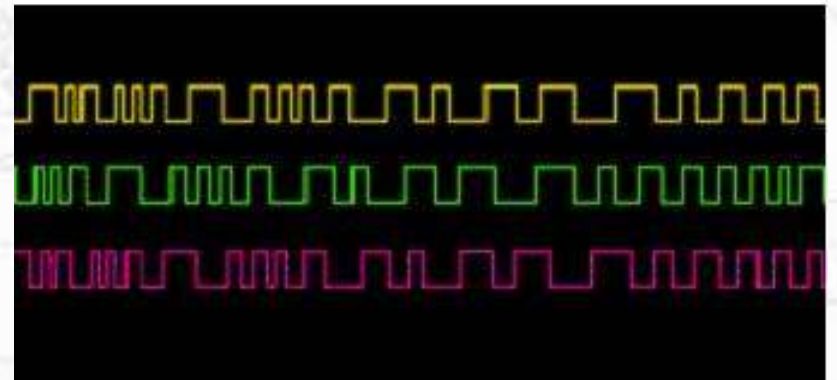
**GPS units are made to communicate with GPS satellites (which have a much better view of the Earth) to find out exactly where they are on the global scale of things.**





# GPS Signals

**Each GPS satellite transmits data that indicates its location and the current time. All GPS satellites synchronize operations so that these repeating signals are transmitted at the same instant.**

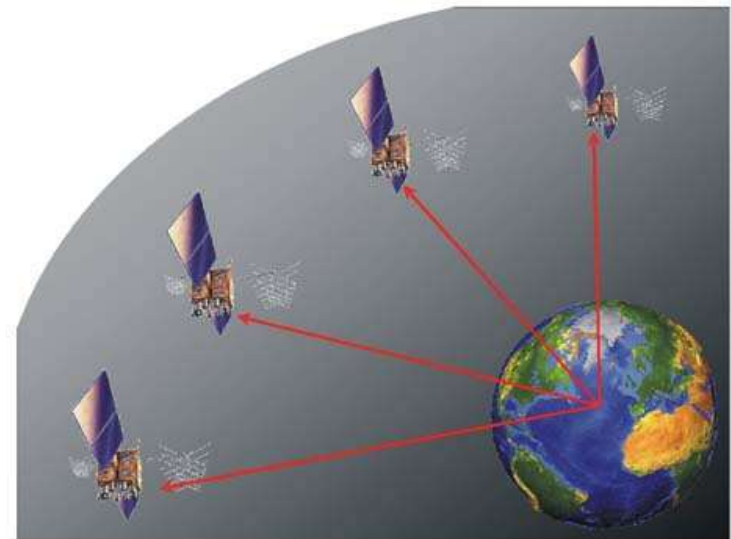


Physically the signal is just a complicated digital code, or in other words, a complicated sequence of “on” and “off” pulses.



# Time Difference

**The GPS receiver compares the time a signal was transmitted by a satellite with the time it was received. The time difference tells the GPS receiver how far away the satellite is.**





# Calculating Distance

**Velocity x Time = Distance**

**Radio waves travel at the speed of light, roughly 186,000 miles per second (mps)**

If it took 0.06 seconds to receive a signal transmitted by a satellite floating directly overhead, use this formula to find your distance from the satellite.

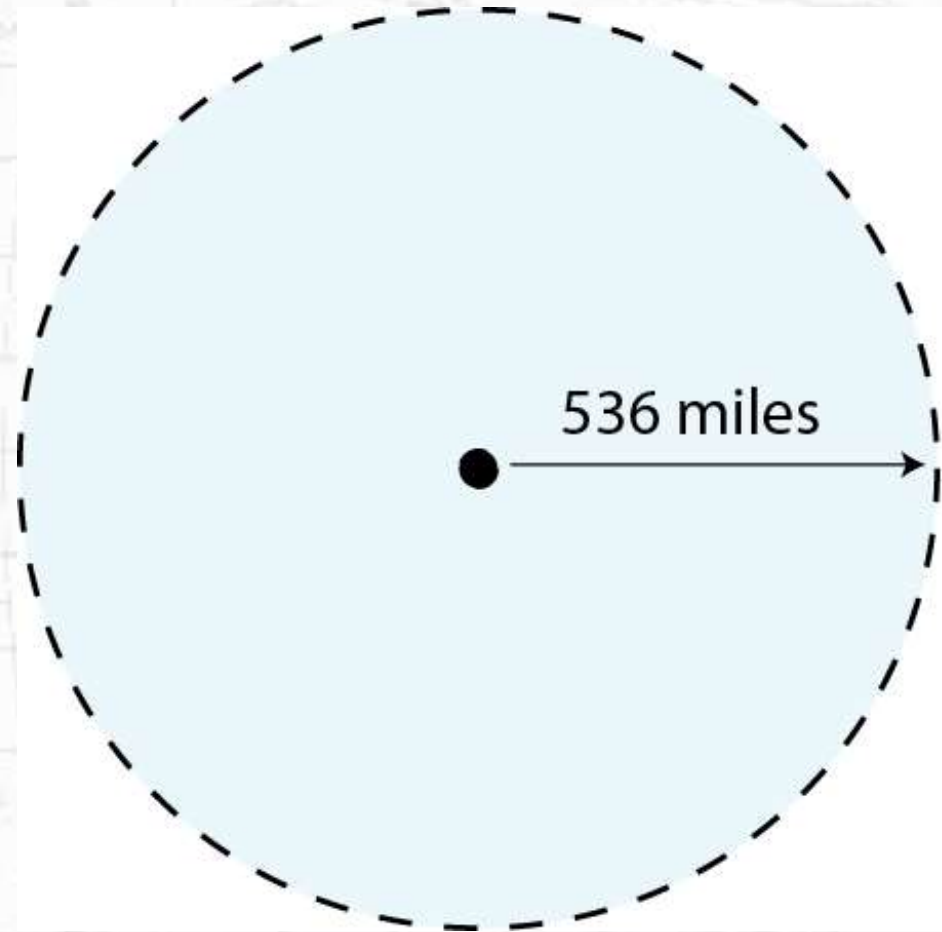
**186,000 mps x 0.06 seconds = 11,160 miles**



# Triangulation

**Geometric  
Principle:**

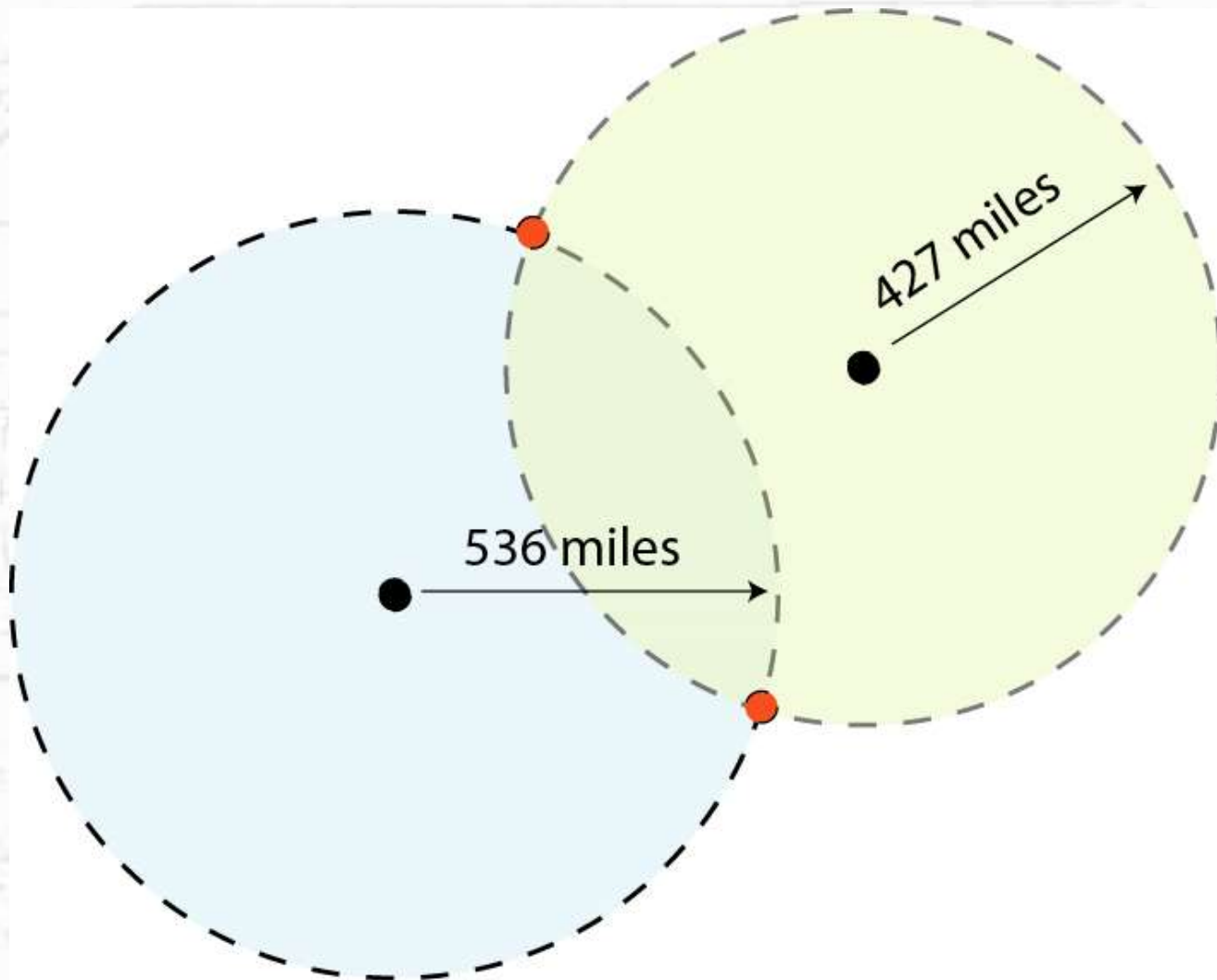
**You can find one  
location if you  
know its distance  
from other,  
already-known  
locations.**





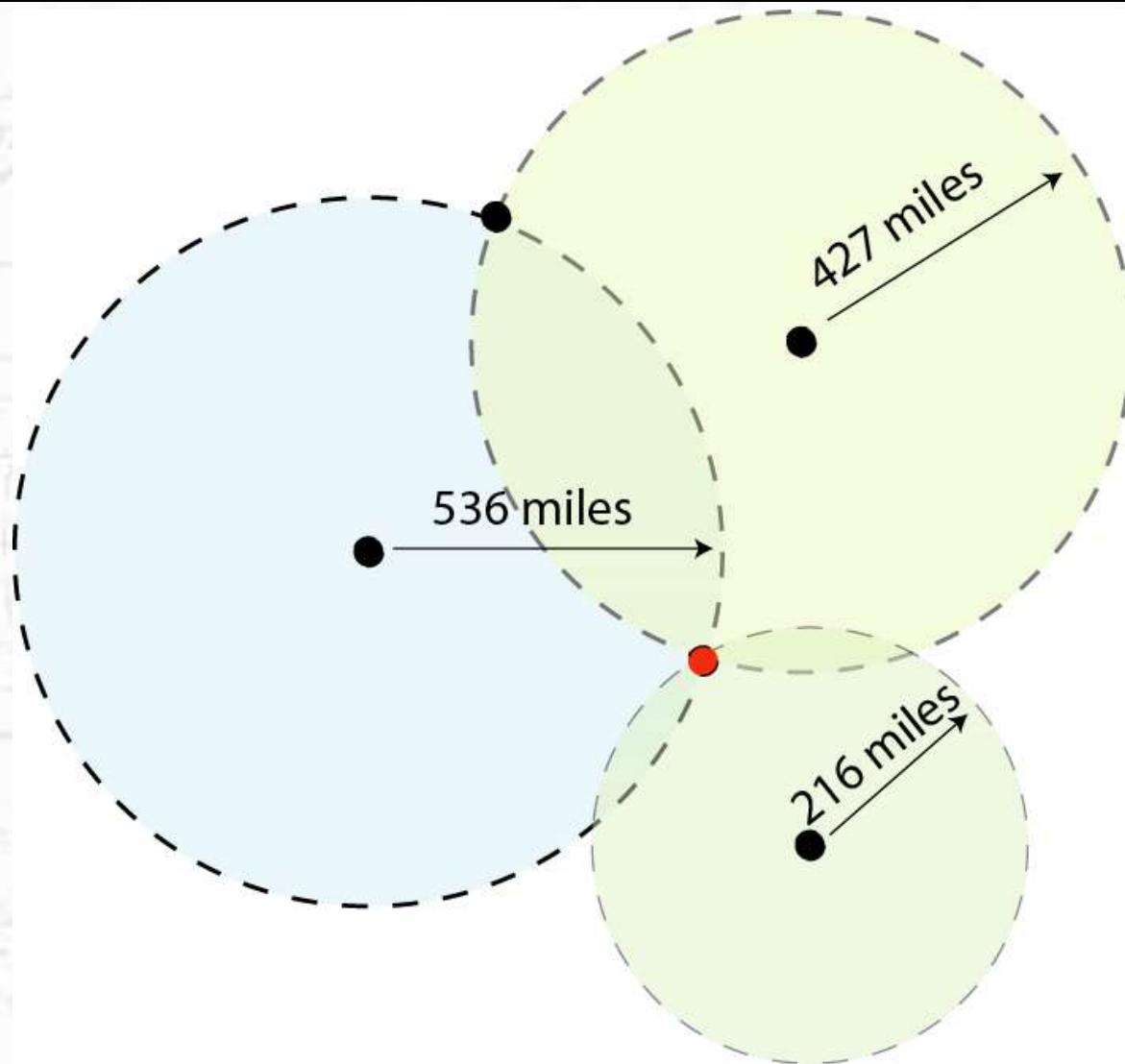


# Triangulation





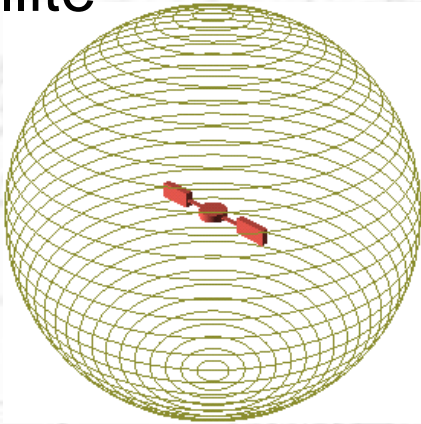
# Triangulation



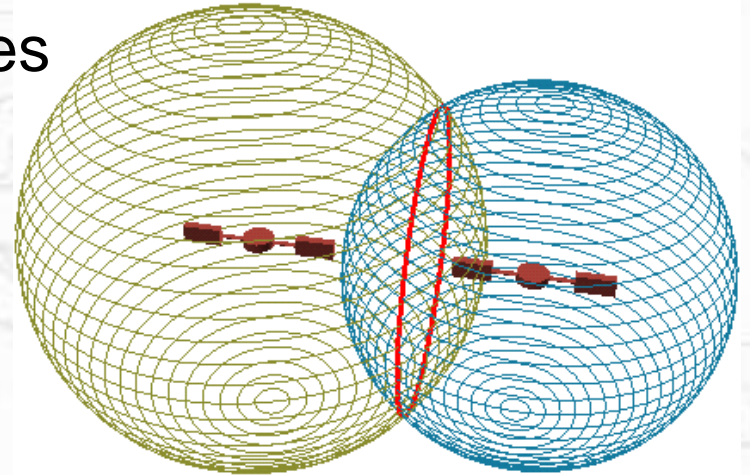


# 3-D Trilateration

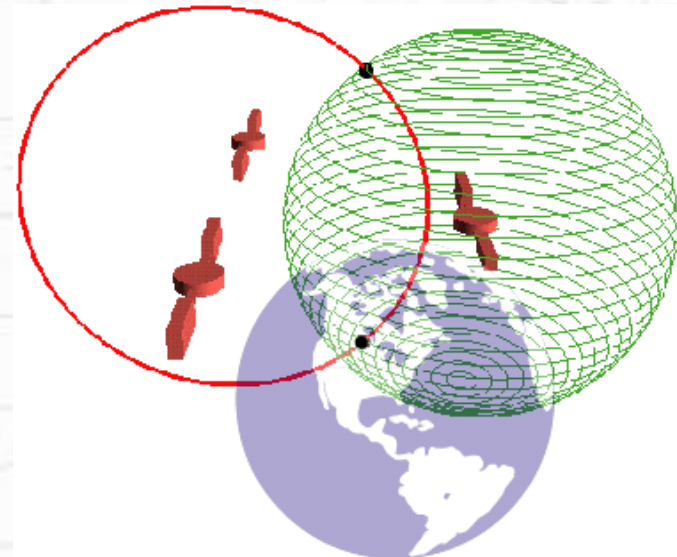
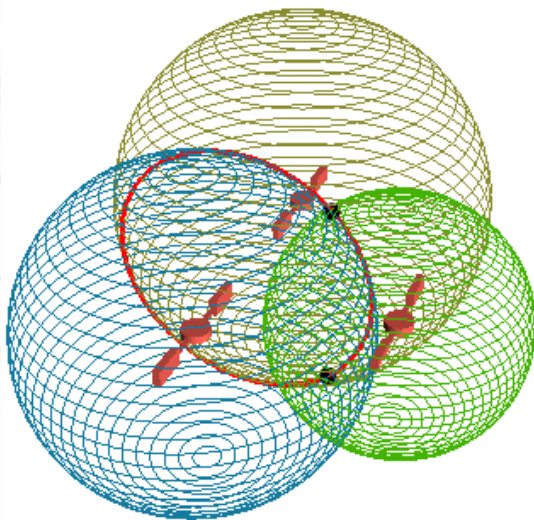
1 Satellite



2 Satellites



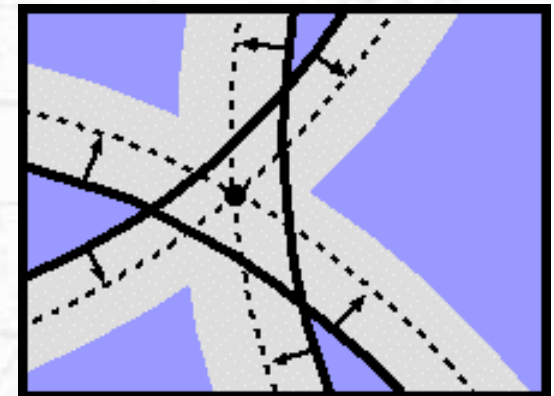
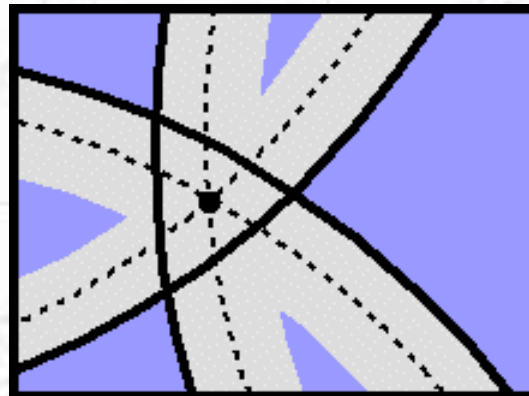
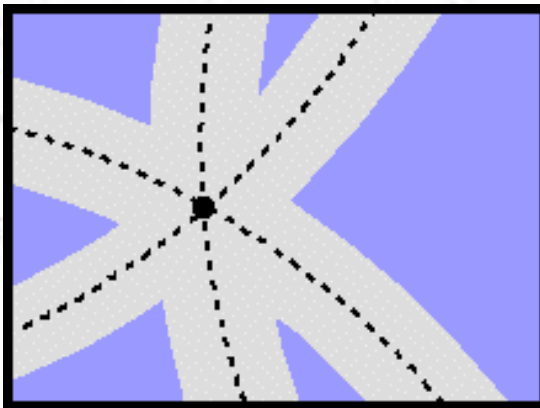
3 Satellites





# Atomic Clocks

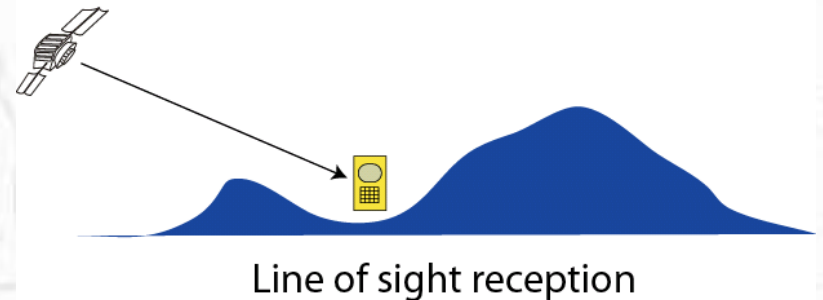
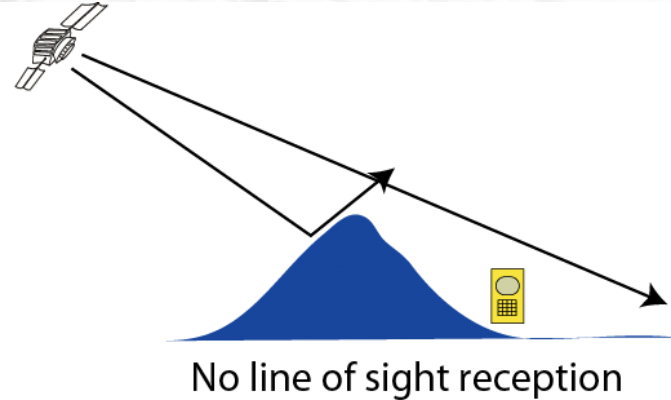
**GPS satellites use Atomic Clocks for accuracy, but because of the expense, most GPS receivers do not.**





# Line of Sight Transmissions

**Line of sight is the ability to draw a straight line between two objects without any other objects getting in the way. GPS transmission are line-of-sight transmissions.**



**Obstructions such as trees, buildings, or natural formations may prevent clear line of sight.**



# Light Refraction

**Sometimes the GPS signal from the satellite doesn't follow a straight line.**

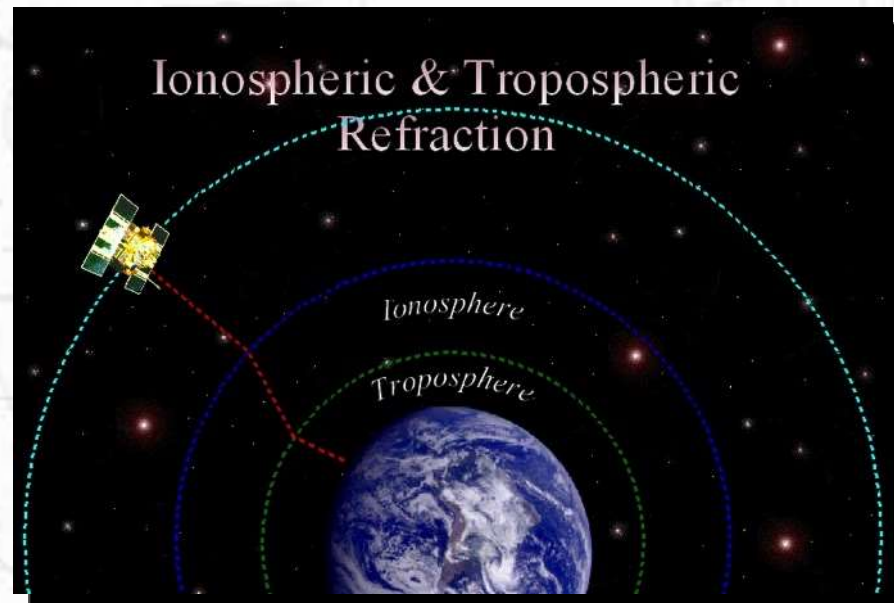
**Refraction is the bending of light as it travels through one media to another.**





# Signal Refraction

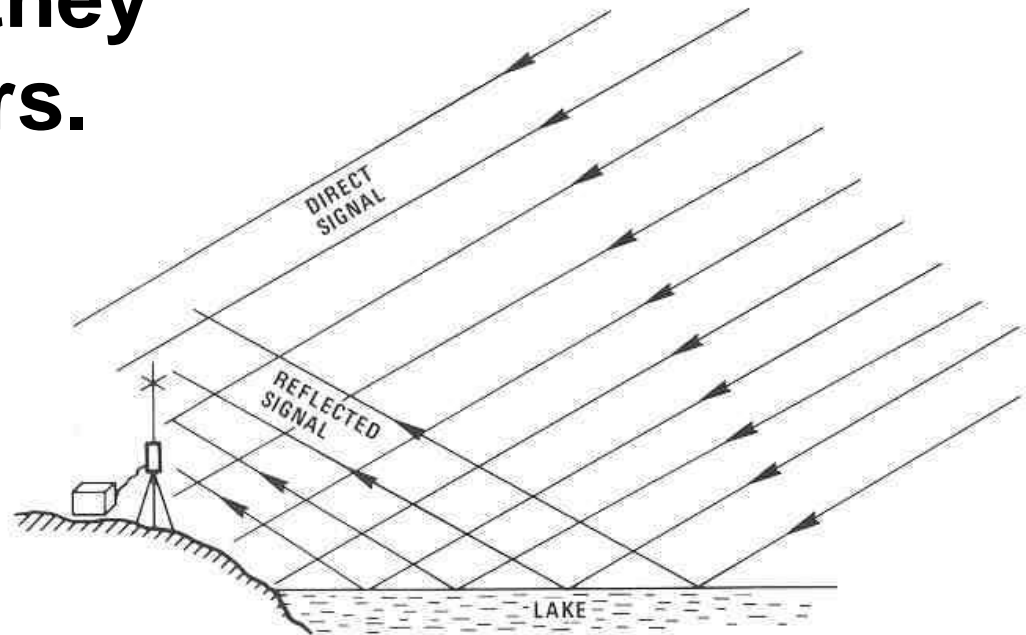
**Signals from satellites can be like light. When they hit some interference (air patterns in the atmosphere, uneven geography, etc.) they sometimes bend a little.**





# Signal Interference

**Sometimes the signals bounce off things before they hit the receivers.**

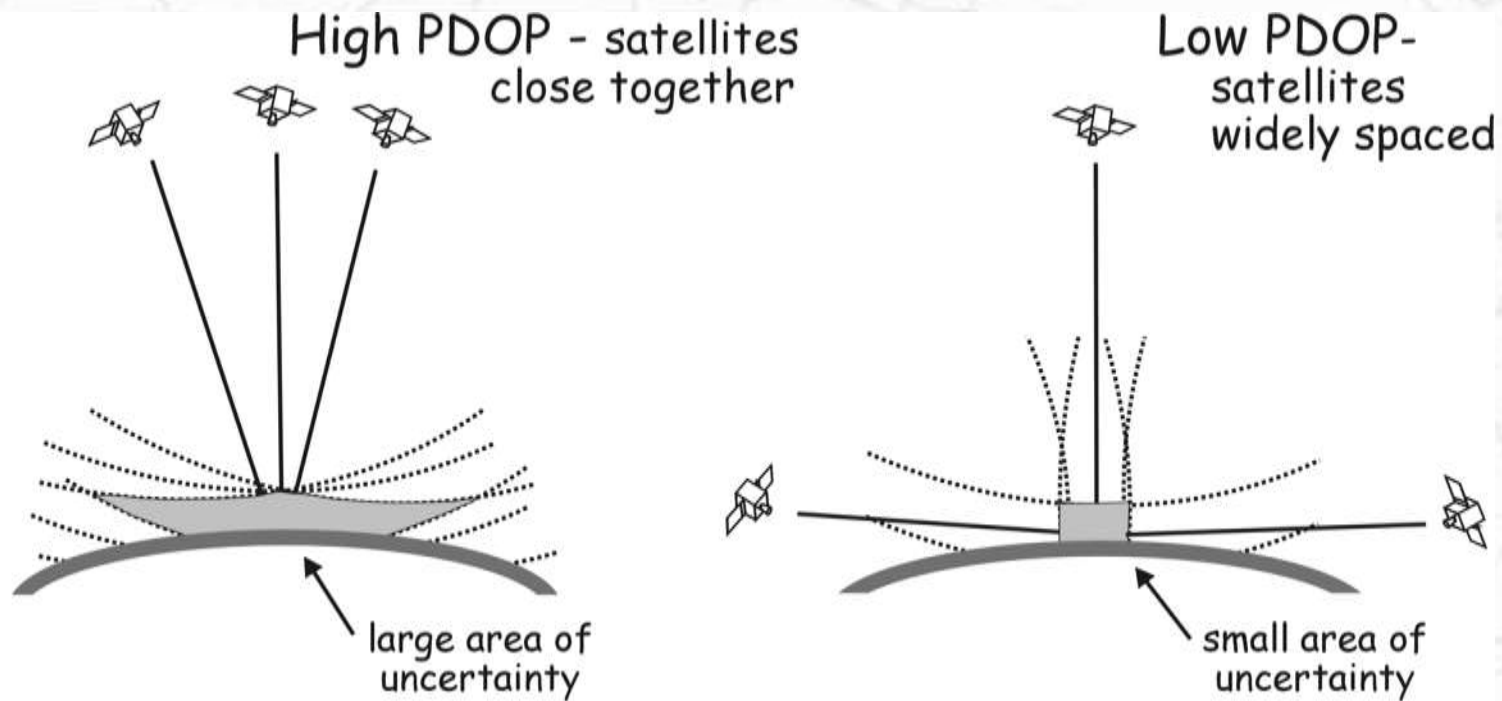






# Satellite Distribution

When the satellites are all in the same part of the sky, readings will be less accurate.

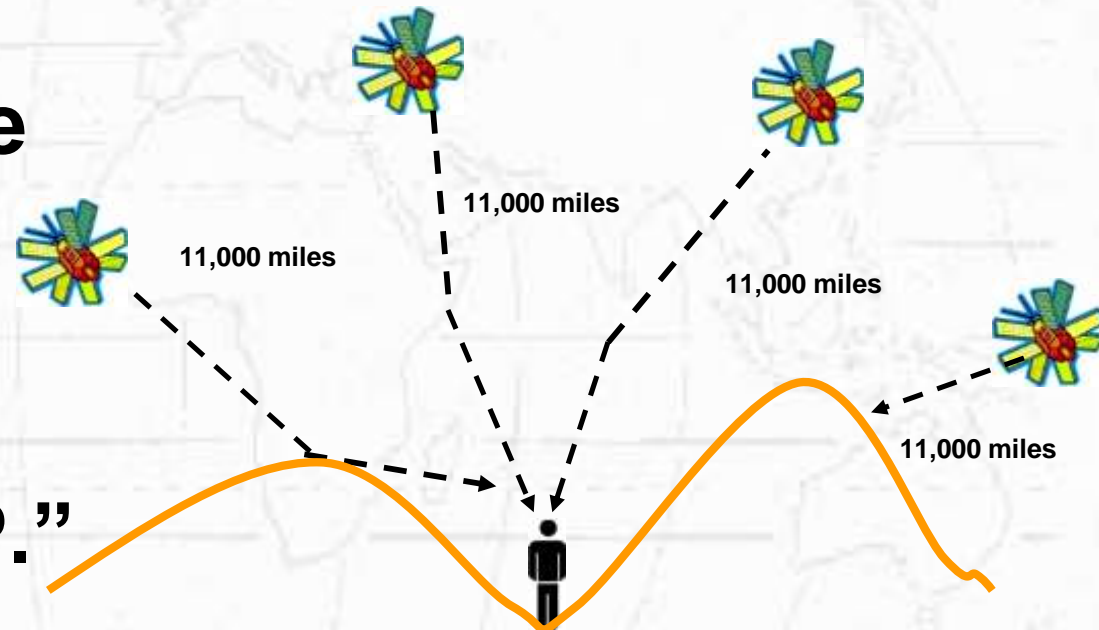




# PDOP

*PDOP = Positional Dilution of Precision*

**All of this  
combines to make  
the signal less  
accurate, and  
gives it what we  
call a high “PDOP.”**



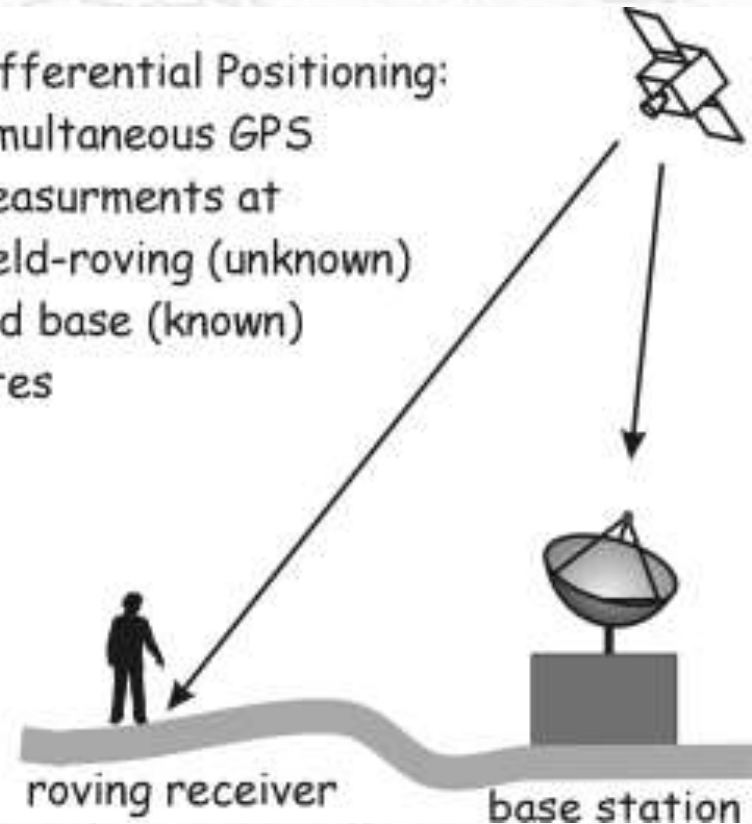
- *A PDOP of <4 is excellent*
- *A PDOP of 4-8 is good*
- *A PDOP of >8 is poor*



# Differential Correction

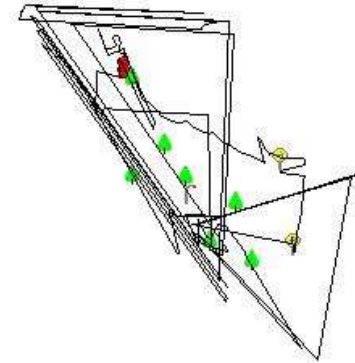
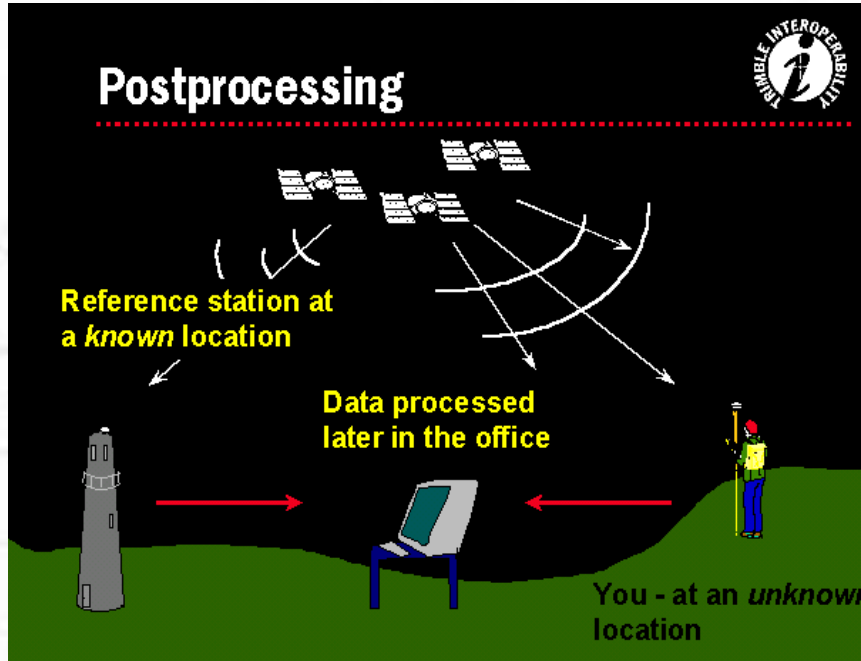
Differential correction is a technique that greatly increases the accuracy of the collected GPS data. It involves using a receiver at a known location - the "base station" - and comparing that data with GPS positions collected from unknown locations with "roving receivers."

Differential Positioning:  
simultaneous GPS  
measurements at  
field-roving (unknown)  
and base (known)  
sites

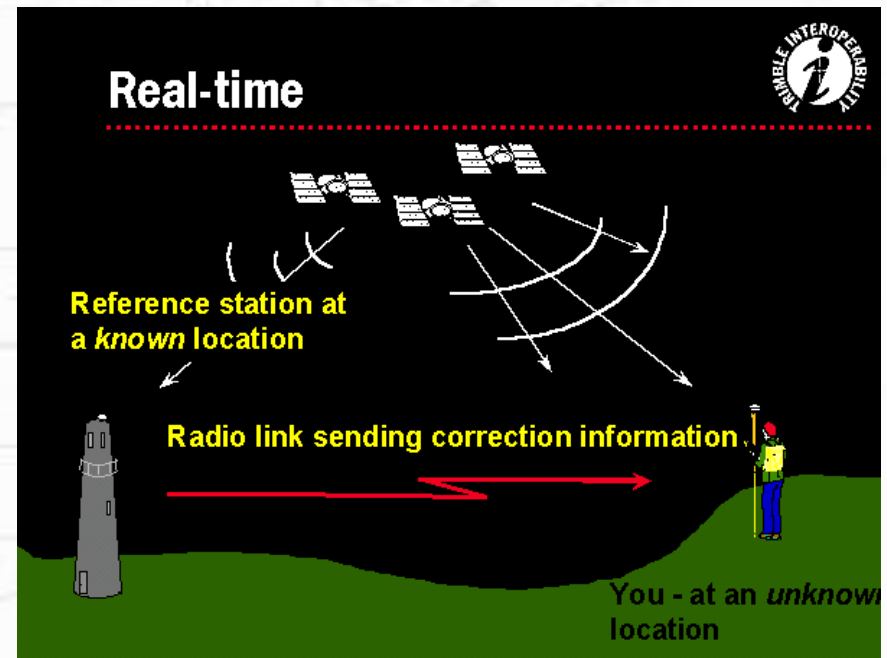




# Postprocessing / Real-time



Before



After

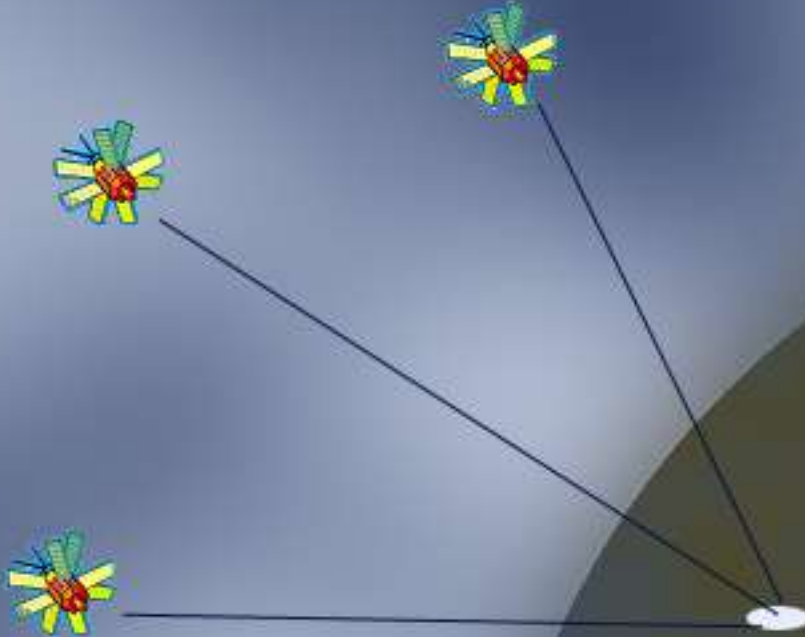




# In a Nutshell

## Global Positioning System

Distance - 186,000 mi/s \* Time



### HOW GPS WORKS

1. Position is calculated by triangulation.
2. Distance is measured by how long a signal takes to reach your position.

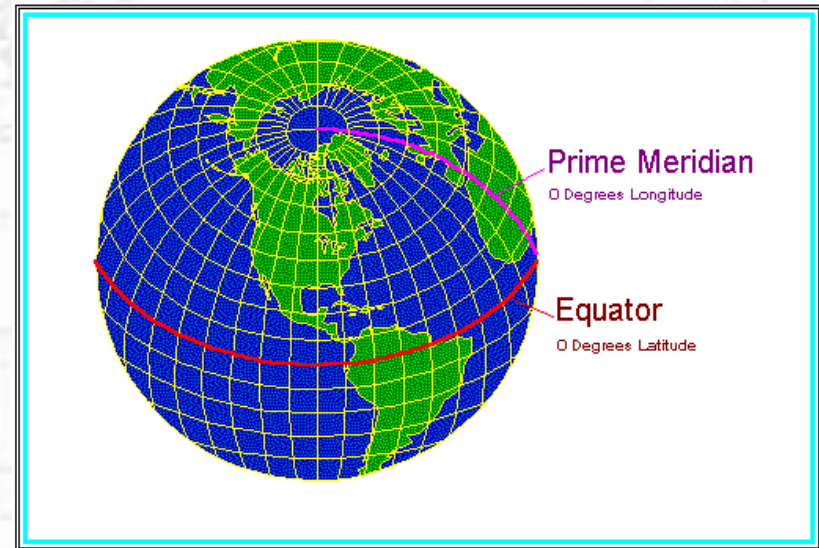
### Factors Affecting Accuracy:

1. Timing of the signal
2. PDOP



# Latitude and Longitude

**Latitude and Longitude are *spherical coordinates* on the surface of the earth. Latitude is measured North or South of the Equator. Longitude is measured East or West of Greenwich. GPS uses Latitudes and Longitudes to reference locations.**

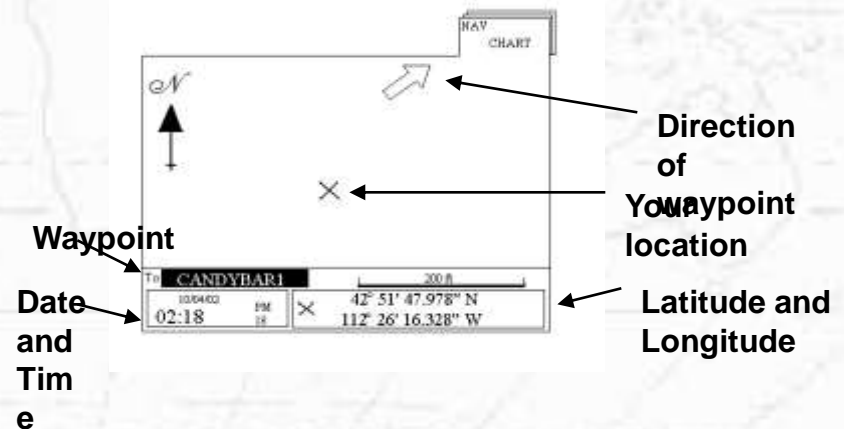




# Waypoints

Waypoints are locations or landmarks that can be stored in your GPS. Waypoints may be defined and stored in the unit manually by inputting latitude and longitude from a map or other reference.




Or more usually, waypoints may be entered directly by taking a reading with the unit at the location itself, giving it a name, and then saving the point.





# Data Dictionary

**GPS units collect data in:**

- Points 
- Lines 
- Areas 

*These are called features.*

**A data dictionary is a means by which we collect specific information about a data feature.**

